

Per il sistema del II ordine con folt $G(s)$,

$$G(s) = \frac{b}{s^2 + \alpha_1 s + \alpha_0},$$

nelle hp di poli reali negativi,

$$G(s) = \frac{b}{s^2 + \alpha_1 s + \alpha_0} = \frac{b}{(s-p_1)(s-p_2)},$$

dove $p_1, p_2 \in \mathbb{R}^-$,
calcolare la risposta al quadruo unitario $u(t) = \mathbf{1}(t)$.

$$\bullet Y(s) = G(s) U(s) = \frac{b}{(s-p_1)(s-p_2)} \cdot \frac{1}{s} = \frac{K_1}{(s-p_1)} + \frac{K_2}{(s-p_2)} + \frac{K_3}{s}.$$

$$K_1 = \lim_{s \rightarrow p_1} (s-p_1) Y(s) = \lim_{s \rightarrow p_1} \frac{(s-p_1) b}{(s-p_1)(s-p_2)} \cdot \frac{1}{s} = \frac{b}{p_1-p_2} \cdot \frac{1}{p_1}$$

$$\text{Nota che } G_0 = \frac{b}{\alpha_0} = \frac{b}{p_1 p_2}, \text{ quindi } \frac{b}{p_1} = G_0 p_2$$

$$\text{e } K_1 = \frac{b}{p_1-p_2} \cdot \frac{1}{p_1} = \frac{G_0}{p_1-p_2} \cdot \frac{p_2}{p_1}$$

$$K_2 = \lim_{s \rightarrow p_2} (s-p_2) Y(s) = \lim_{s \rightarrow p_2} \frac{(s-p_2) b}{(s-p_1)(s-p_2)} \cdot \frac{1}{s} = \frac{b}{p_2-p_1} \cdot \frac{1}{p_2}$$

$$= \frac{G_0 p_1}{p_2-p_1} = - \frac{G_0 p_1}{p_1-p_2}$$

$$K_3 = \lim_{s \rightarrow 0} s Y(s) = \lim_{s \rightarrow 0} s \frac{G(s)}{s} = G(s) = G_0 = \frac{b}{\alpha_0} = \frac{b}{p_1 p_2}$$

Quindi

$$Y(s) = \underbrace{\frac{G_0 \frac{p_2}{p_1-p_2}}{s-p_1}}_{\mathcal{L}^{-1}} - \underbrace{\frac{G_0 \frac{p_1}{p_1-p_2}}{s-p_2}}_{\mathcal{L}^{-1}} + \frac{G_0}{s}$$

$$y(t) = G_0 \left[\frac{p_2}{p_1-p_2} e^{p_2 t} - \frac{p_1}{p_1-p_2} e^{p_1 t} + 1 \right] \mathbf{1}(t)$$

\bullet Nel caso $u(t) = (u_0 \cdot \mathbf{1}(t))$, allora

$$y(t) = G_0 u_0 \left[\frac{p_2}{p_1-p_2} e^{p_2 t} - \frac{p_1}{p_1-p_2} e^{p_1 t} + 1 \right] \mathbf{1}(t)$$

\bullet Nel caso si vuole risolvere l'escita in termini di costanti di tempo ($\tau_1 = -1/p_1$, $\tau_2 = -1/p_2$)

$$G(s) = \frac{b}{(s-p_1)(s-p_2)} = \frac{b}{(-p_1)\left(\frac{s}{-p_1} + 1\right)(-p_2)\left(\frac{s}{-p_2} + 1\right)} =$$

$$= \frac{b}{p_1 p_2 / (s\tau_1 + 1)(s\tau_2 + 1)} =$$

$$= \frac{G_0}{(s\tau_1 + 1)(s\tau_2 + 1)}$$

$$K_1 = G_0 \frac{p_2}{p_1-p_2} = G_0 \frac{-\frac{1}{\tau_2}}{-\frac{1}{\tau_1} + \frac{1}{\tau_2}} = G_0 \frac{-\frac{1}{\tau_2}}{\frac{\tau_1-\tau_2}{\tau_1\tau_2}} = -\frac{G_0 \tau_1}{\tau_1 - \tau_2}$$

$$K_2 = G_0 \frac{p_1}{p_2-p_1} = -G_0 \cdot \frac{p_1}{p_1-p_2} = -G_0 \frac{-\frac{1}{\tau_1}}{-\frac{1}{\tau_1} + \frac{1}{\tau_2}} = -G_0 \frac{-\frac{1}{\tau_1}}{\frac{\tau_1-\tau_2}{\tau_1\tau_2}} = +\frac{G_0 \tau_2}{\tau_1 - \tau_2}$$

Quindi,

$$y(t) = G_0 u_0 \left(-\frac{\tau_1}{\tau_1 - \tau_2} e^{-t/\tau_1} + \frac{\tau_2}{\tau_1 - \tau_2} e^{-t/\tau_2} + 1 \right) \mathbf{1}(t)$$