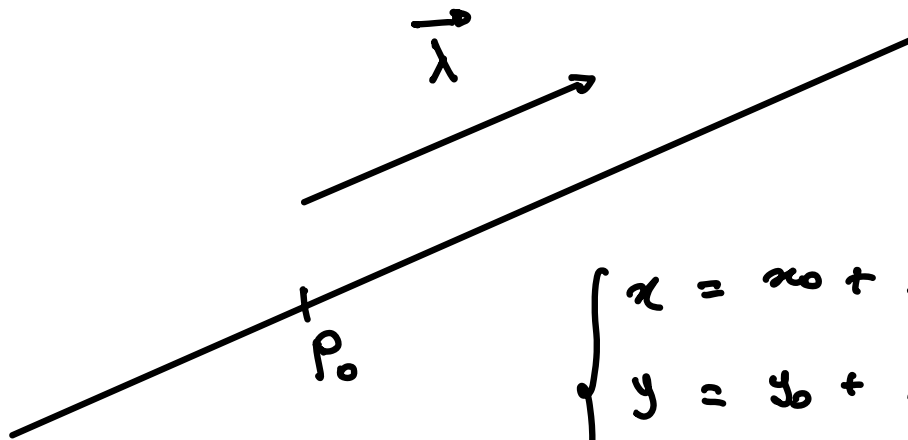
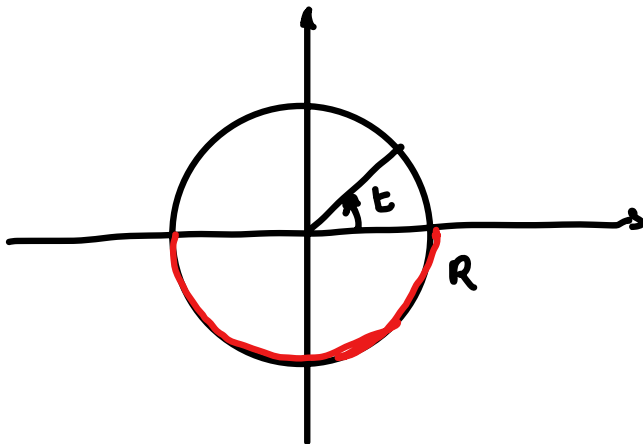


# Curve equivalents



$$\begin{cases} x = x_0 + \lambda_1 t \\ y = y_0 + \lambda_2 t \\ z = z_0 + \lambda_3 t \end{cases}$$



$$\begin{cases} x = R \cos t \\ y = R \sin t \end{cases} \quad t \in [0, 2\pi]$$

$$\begin{cases} x = R \cos s \\ y = R \sin s \end{cases} \quad s \in [0, 4\pi]$$

$$\begin{cases} x = R \cos t \\ y = R \sin t \end{cases} \quad t \in [-\pi, 0]$$

$$\begin{cases} x = R \cos 2s \\ y = R \sin 2s \end{cases} \quad s \in [\frac{\pi}{2}, \pi]$$

Def.  $\varphi: I \longrightarrow \mathbb{R}^2 \text{ (} \mathbb{R}^3 \text{)}$   
 $t \longrightarrow \varphi(t)$

$$\psi: J \longrightarrow \mathbb{R}^2 \text{ (} \mathbb{R}^3 \text{)}$$
$$s \longrightarrow \psi(s)$$

Altre ipotesi:

SI DICE CHE  $\varphi$  e  $\psi$  sono EQUIVALENTI  
SE ESISTE

$$g: I \longrightarrow J \text{ di classe } C^1$$
$$s = g(t) \quad \text{invertibile}$$

$$g'(t) \neq 0 \quad \forall t \in I$$

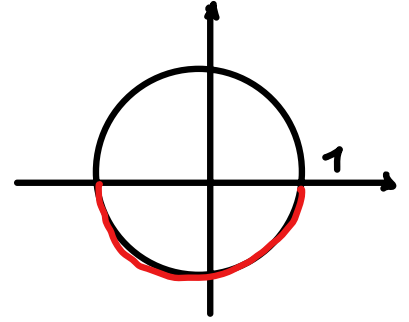
ed inoltre

$$\varphi(t) = \psi(g(t)).$$

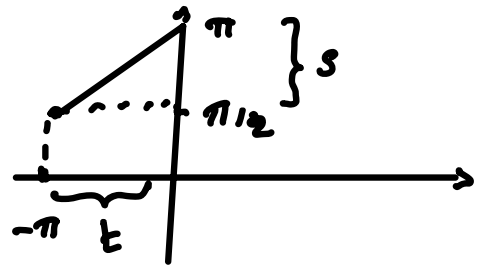
Oss. Abbiamo che  $g'(t) \neq 0$  oppure  
 $g'(t) \leq 0$ .

$\gamma(t)$  "CAMBIAMENTO AMMISSIBILE DI PARAMETRO"

ES.  $\varphi(t) = \begin{cases} x = \cos t \\ y = \sin t \end{cases} \quad t \in [-\pi, 0]$



$$\psi(s) = \begin{cases} x = \cos(2s) \\ y = \sin(2s) \end{cases} \quad s \in [\frac{\pi}{2}, \pi]$$



$$s = g(t) = \frac{t}{2} + \pi, \quad t \in [-\pi, 0]$$

OSS. DUE CURVE EQUIVALENTI HANNO LO STESSO SOSTEGNO!!

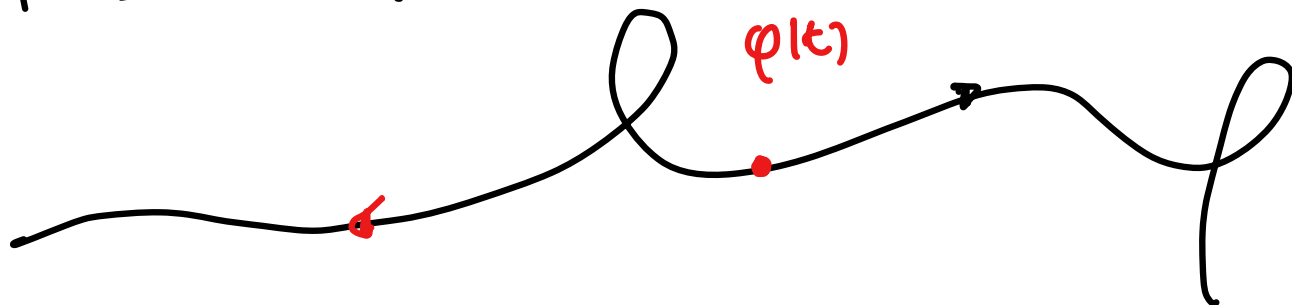
Verifichiamo che  $\varphi(t) = \psi(g(t))$

$$\begin{aligned} \psi(g(t)) &= (\cos 2g(t), \sin 2g(t)) = \\ &= (\cos(t + 2\pi), \sin(t + 2\pi)) \\ &= (\cos t, \sin t) = \varphi(t) \end{aligned}$$

# ORIENTAMENTO DI UNA CURVA

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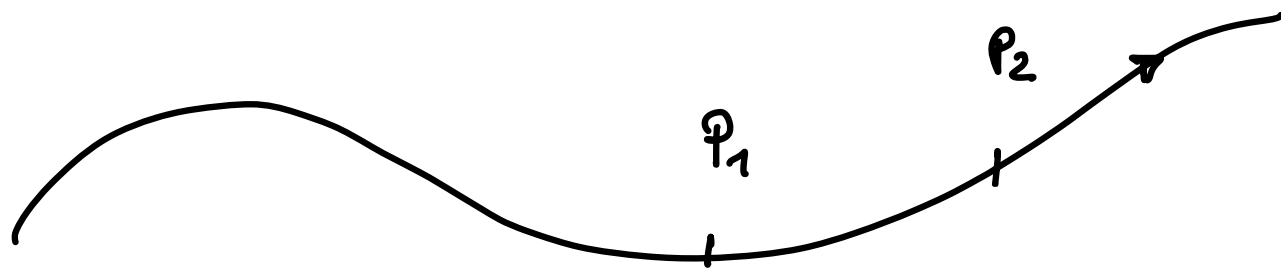
$$\varphi: \mathbb{I} \rightarrow \mathbb{R}^2 (\mathbb{R}^3)$$



" Si dice che un punto  $P_1 = \varphi(t_1)$  precede  $P_2 = \varphi(t_2)$  nel verso di percorrenza (o orientamento) indotto dal parametro  $t$  se

$$t_1 < t_2 \quad "$$

==



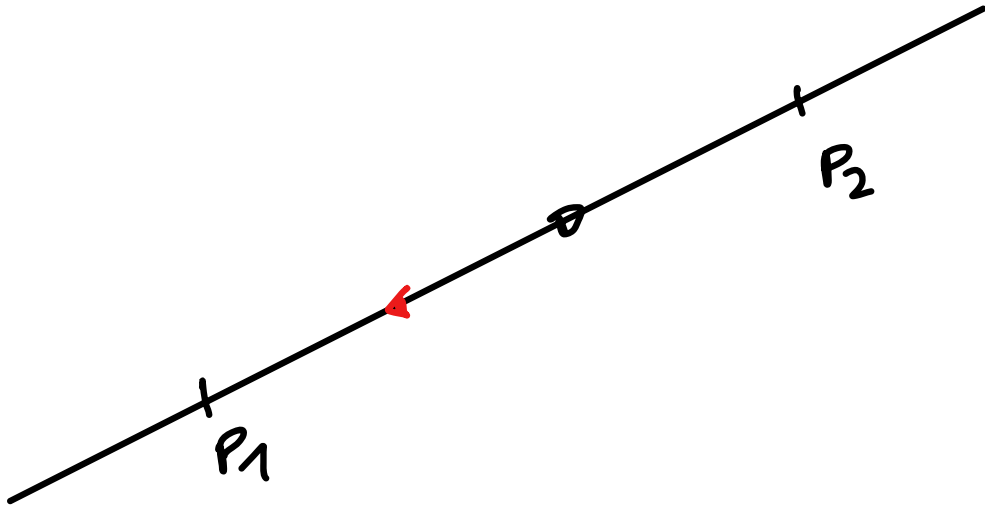
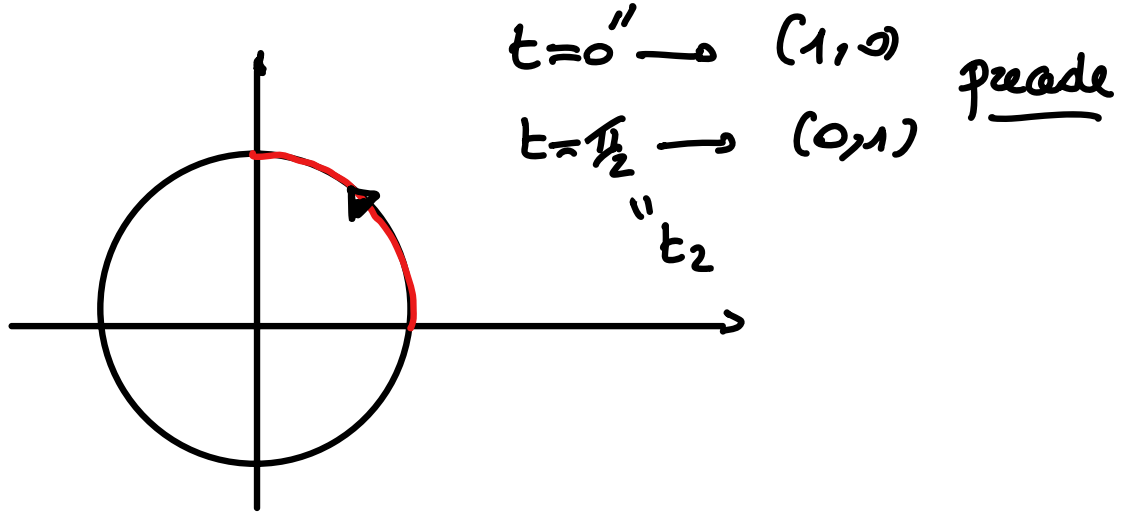
ES.

(1)

$$\begin{cases} x = \cos t \\ y = \sin t \end{cases}$$

$$t \in [0, \pi/2]$$

$t_1$



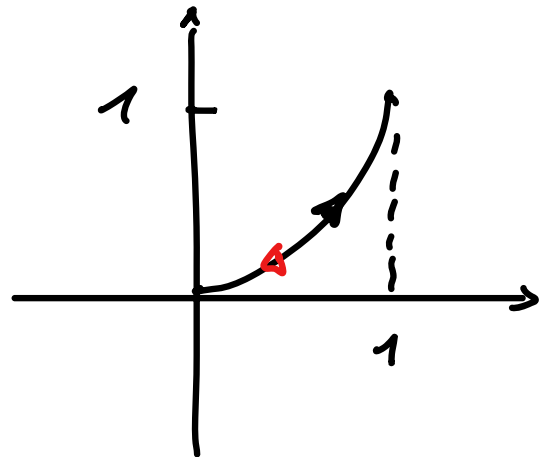
$$\begin{cases} x = t x_2 + (1-t) x_1 \\ y = t y_2 + (1-t) y_1 \end{cases} \quad t \in [0,1]$$

$$\begin{cases} x = t x_1 + (1-t) x_2 \\ y = t y_1 + (1-t) y_2 \end{cases} \quad t \in [0,1]$$

$$y = x^2$$

$$x \in [0, 1]$$

$$\begin{cases} x = t \\ y = t^2 \end{cases} \quad t \in [0, 1]$$



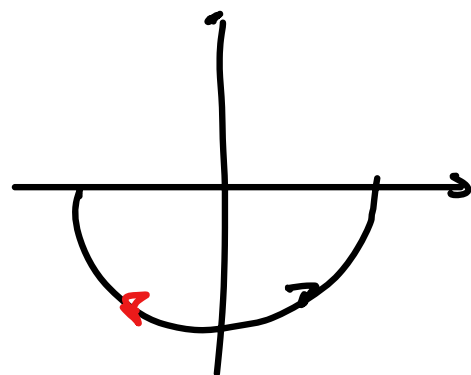
$$t = 0 \rightarrow (0, 0) \text{ \textit{precede}}$$

$$t = 1 \rightarrow (1, 1)$$

$$\begin{cases} x = -s \\ y = s^2 \end{cases}$$

$$s \in [-1, 0]$$

$$\begin{cases} x = \cos t \\ y = \sin t \end{cases} \quad t \in [-\pi, 0]$$



$$\begin{cases} x = \cos s \\ y = -\sin s \end{cases} \quad s \in [0, \pi]$$

$$s = g(t) = -t$$

$$g'(t) = -1$$

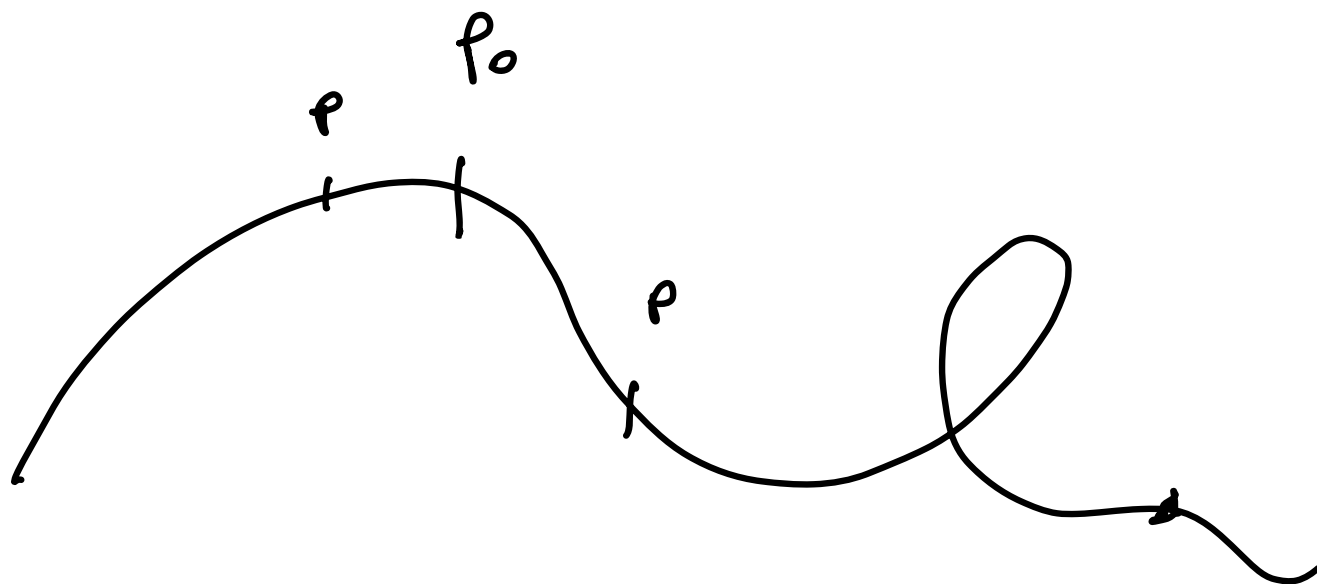
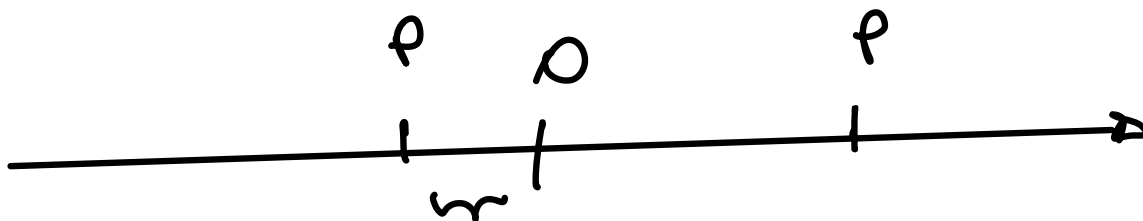
OSS

Se  $\varphi$  e  $\psi$  sono equivalenti, esse inducono lo stesso orientamento se

$$g'(t) \neq 0$$

ASCISSA CURVILINEA

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$s(P) =$  "ASCISSA CURVILINEA DI P"

$$= \begin{cases} |\widehat{P_0 P}| & \text{se } P \text{ segue } P_0 \\ -|\widehat{P_0 P}| & \text{se } P \text{ precede } P_0 \end{cases}$$

$\varphi(t)$  rappresentazione parametrica "REGOLARE"

ASCISSA CURVILINEA :  $t_0 \in [a, b]$

$$s(t) = \int_{t_0}^t \|\varphi'(\tau)\| d\tau, \quad t \in [a, b]$$

$P_0 = \varphi(t_0)$  ORIGINE DELLE ASCISSE

$P = \varphi(t)$  : se  $P$  segue  $P_0$ , si ha

$$t > t_0$$

$$\Rightarrow s(t) = \int_{t_0}^t \|\varphi'(\tau)\| d\tau = \text{lunghezza dell'arco } \widehat{P_0 P}$$



: se  $P$  precede  $P_0$ , si ha  
 $t < t_0$

$$s(t) = - \int_t^{t_0} \underbrace{\|\varphi'(\tau)\|}_{L(\widehat{P_0P})} d\tau$$
$$= - (\text{lunghezza di } \widehat{P_0P})$$

OSS.

$$s'(t) = \|\varphi'(t)\| \neq 0 \quad (\text{TEOR. FOND. CALCOLO})$$

$s = s(t)$  stretta crescente

$s: t \in [a, b] \xrightarrow{\text{str. crescente}} s(t) \in [s(a), s(b)]$

$t = t(s)$  inversa di  $s(t)$   $t(s)$

$t = t(s): s \in [s(a), s(b)] \rightarrow t \in [a, b]$

$\psi(s) = \varphi(t(s))$  :  $\psi$  e  $\varphi$  equivalenti  
comb. ammissibile

$$s'(t) = \|\varphi'(t)\|$$

$$\psi'(s) = \varphi'(t(s)) \cdot \frac{dt}{ds}$$

$$= \varphi'(t(s)) \cdot \frac{1}{s'(t(s))}$$

$$= \varphi'(t(s)) \cdot \frac{1}{\|\varphi'(t(s))\|}$$

$$\Rightarrow \|\psi'(s)\| = 1.$$

ES.

$$\begin{cases} x' = -\sin t \\ y' = \cos t \\ z' = 1 \end{cases}$$

$$\begin{cases} x = \cos t \\ y = \sin t \\ z = t \end{cases} \quad \begin{matrix} t \in [0, 2\pi] \\ t_0 = 0 \end{matrix}$$

$$P_0 = (1, 0, 0)$$

$$s = s(t) = \int_0^t \underbrace{\|\varphi'(\tau)\|}_{\sqrt{2}} d\tau = \sqrt{2} t \quad t \in [0, 2\pi]$$

$$t = \frac{s}{\sqrt{2}}$$

$$\begin{cases} x = \cos \frac{s}{\sqrt{2}} \\ y = \sin \frac{s}{\sqrt{2}} \\ z = \frac{s}{\sqrt{2}} \end{cases}$$

$$s \in [0, 2\sqrt{2}\pi]$$

$$\begin{cases} x'(s) = -\frac{1}{\sqrt{2}} \sin\left(\frac{s}{\sqrt{2}}\right) \\ y'(s) = \frac{1}{\sqrt{2}} \cos\left(\frac{s}{\sqrt{2}}\right) \\ z'(s) = \frac{1}{\sqrt{2}} \end{cases}$$

$$(x')^2 + (y')^2 + (z')^2 = \frac{1}{2} + \frac{1}{2} = 1$$

$$\| \varphi'(s) \| = 1$$