



Course of "Automatic Control Systems" 2023/24

Project

Prof. Francesco Montefusco

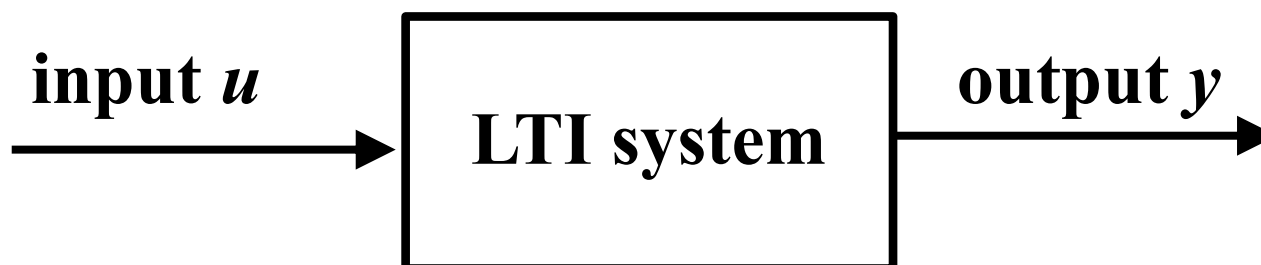
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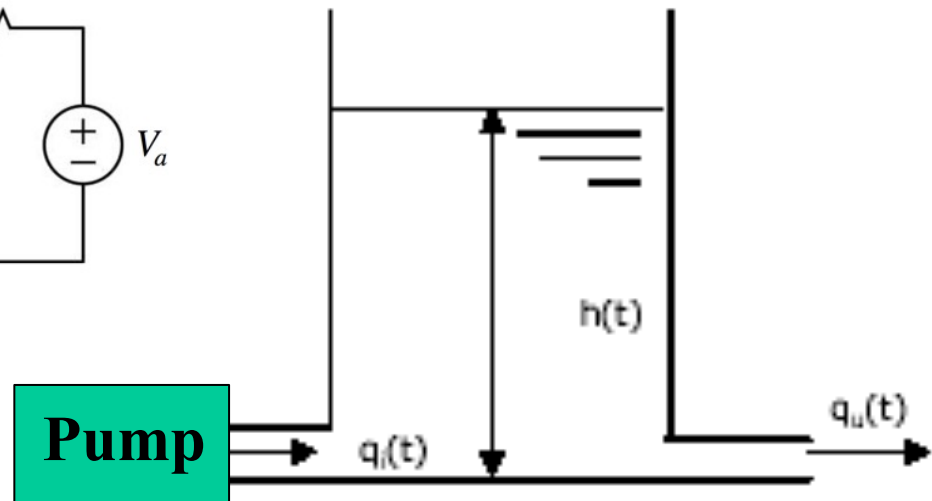
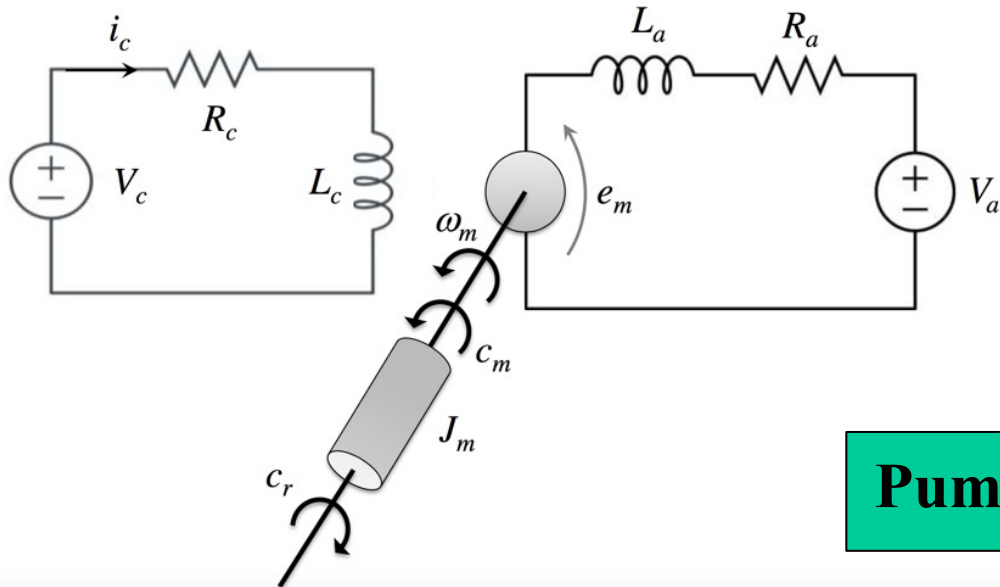
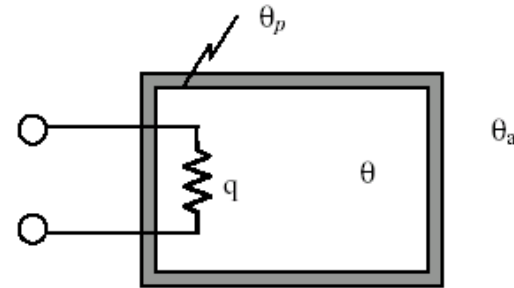
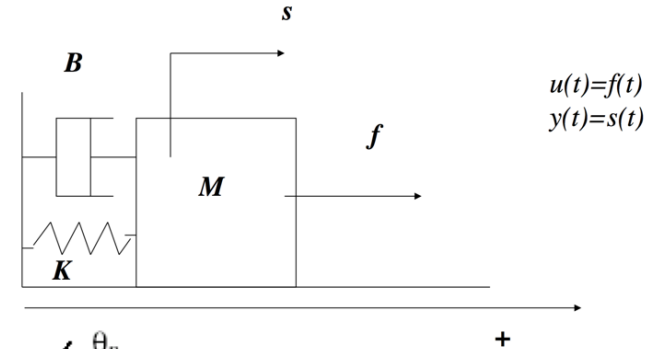
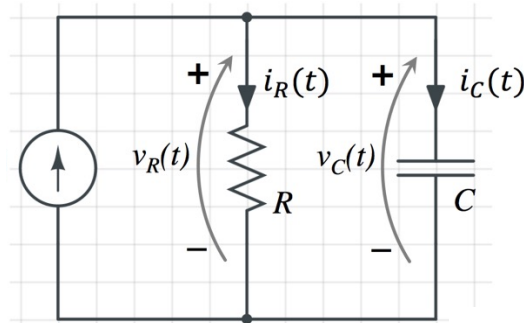
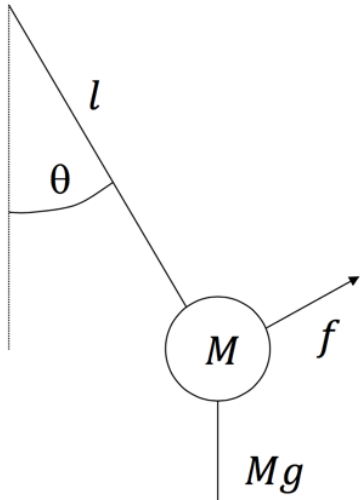
Team code: **mfs9zfr**

Analysis of LTI system in the time and frequency domains

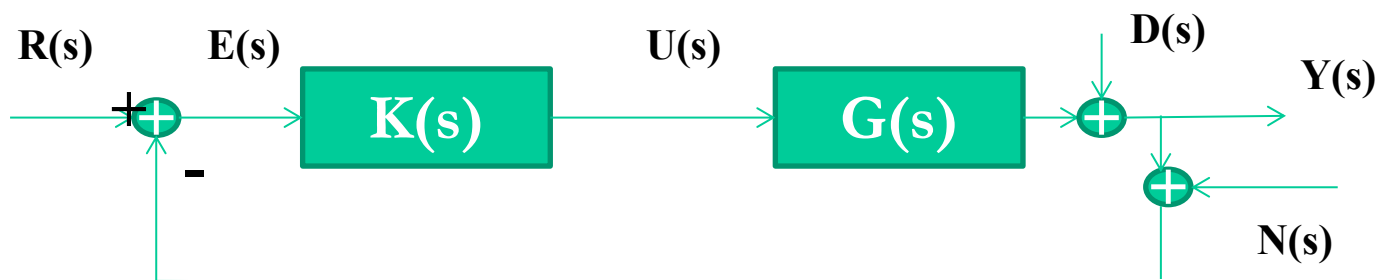


- ✧ *Input output representation*
- ✧ *State space representation*
- ✧ *Transfer function*
- ✧ *Stability analysis*
- ✧ *Free evolution*
- ✧ *Force response (to step, sinusoidal, ramp signals, etc.)*
- ✧ *Frequency response (system as a filter)*

Examples of dynamical systems



Controller design

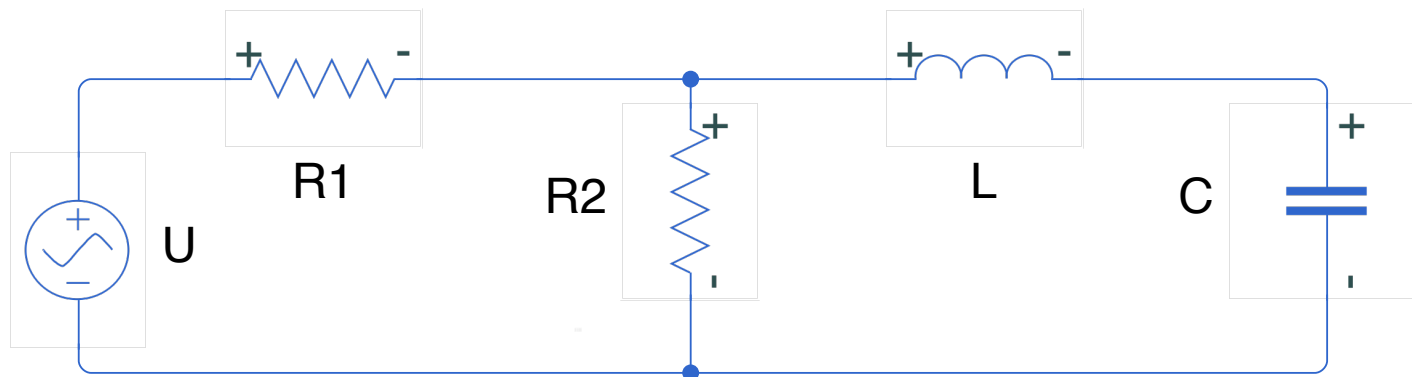


✧ *Stability*

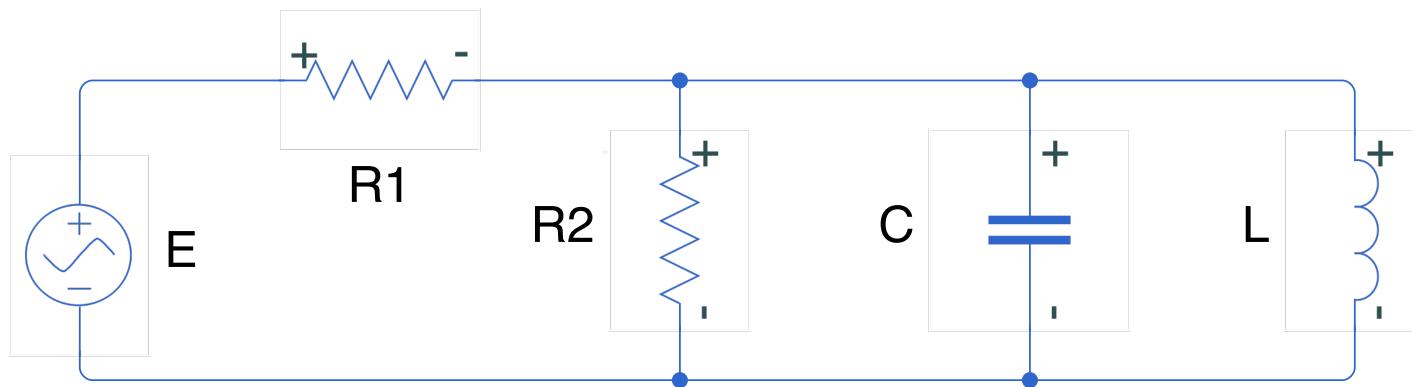
✧ *Robust stability*

✧ *Steady-state performances*

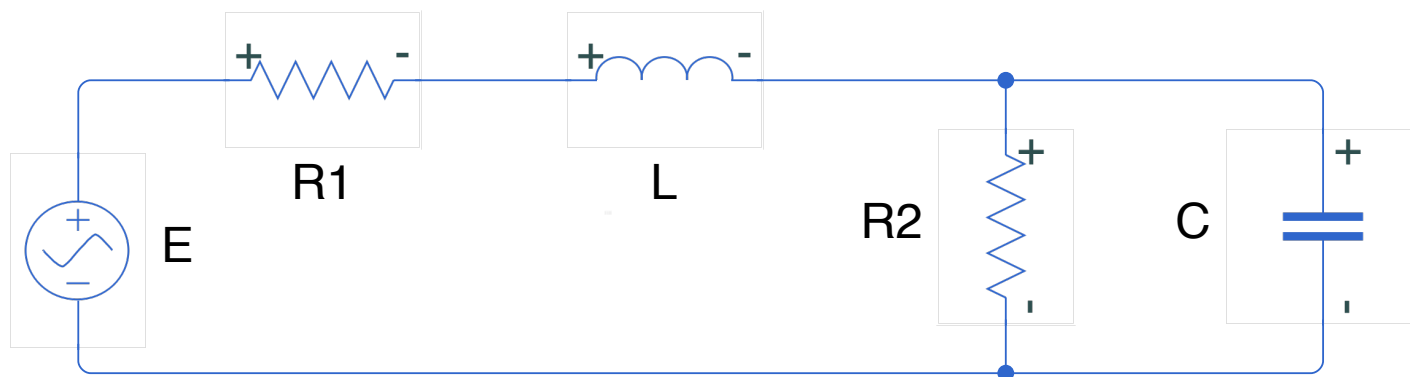
✧ *Transient performances*



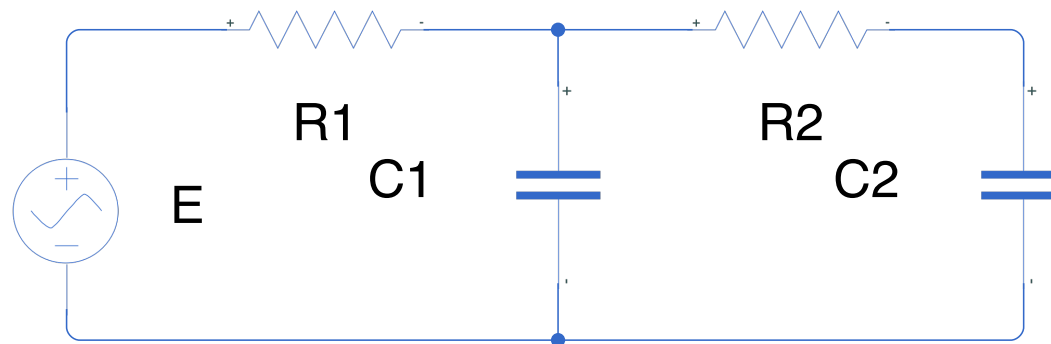
Input u : the voltage of generator U
Output y : the voltage across the capacitor C



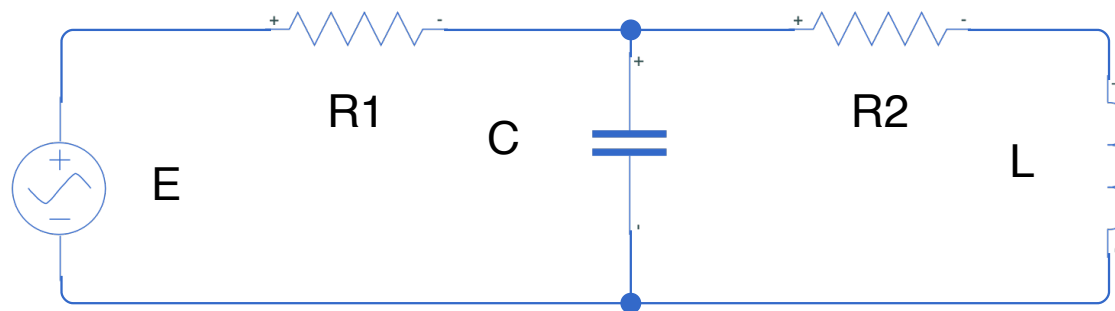
Input u : the voltage of generator E
Output y : the voltage across the capacitor C



Input u : the voltage of generator E
Output y : the voltage across the capacitor C



Input u : the voltage of generator E
Output y : the voltage across the capacitor $C2$



Input u : the voltage of generator E

Output y : the voltage across the capacitor C