



Course of "Automatic Control Systems" 2023/24

Introduction – part 1

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Course Administration

✧ **E-mail:** francesco.montefusco@uniparthenope.it

✧ **Books**

- ✧ Introduction to Dynamic Systems: Theory, Models, and Applications, D. G. Luenberger. John Wiley & Sons
- ✧ Fondamenti di Controlli Automatici, 4° Ed , P. Bolzern, R. Scattolini, N. Schiavoni. McGraw-Hill (Italian)
- ✧ Modern Control Engineering, 3rd Edition, K. Ogata, Prentice Hall, (2004)

✧ **Slides of the lectures**

✧ **Prerequisites**

- ✧ Basic classes in mathematical analysis, physics, algebra and geometry

✧ **Exam**

- ✧ Written exam
- ✧ Oral exam including discussion of a project report about analysis of the dynamics of a linear system, and the device of a closed-loop control system with required characteristics by using Matlab/Simulink



Contents of the course

- ✧ This course is an introductory course on control systems providing the students with the basic engineering knowledge of dynamic systems and feedback.
- ✧ The course is conceptually divided in three parts:
 - ✧ Analysis of linear dynamic system in the time and frequency domains
 - ✧ Key concepts in control
 - ✧ Design method of feedback control systems for linear dynamic system
- ✧ After the course the student should be able
 - ✧ to describe and explain how feedback mechanisms affect system properties such as stability, speed of response, precision, sensitivity and robustness.
 - ✧ to design feedback systems guaranteeing a set of these properties



Introduction to automatic control

- ✧ Automation or automatic control is a discipline whose aim is the study of the methodologies able to reduce or completely eliminate the human intervention in applications of interest.
- ✧ Benefits:
 - ✧ Quality
 - ✧ Accuracy
 - ✧ Reliability
 - ✧ Repeatability
 - ✧ Cost reduction
 - ✧ Security
 - ✧ ...



Applications

✧ Applications in most engineering domains:

- ✧ Aerospace
- ✧ Cars and Vehicles
- ✧ Process industry
- ✧ Energy storage and distribution
- ✧ Home automation
- ✧ Logistic
- ✧ Biology
- ✧ Autonomous systems and robots
- ✧ ...



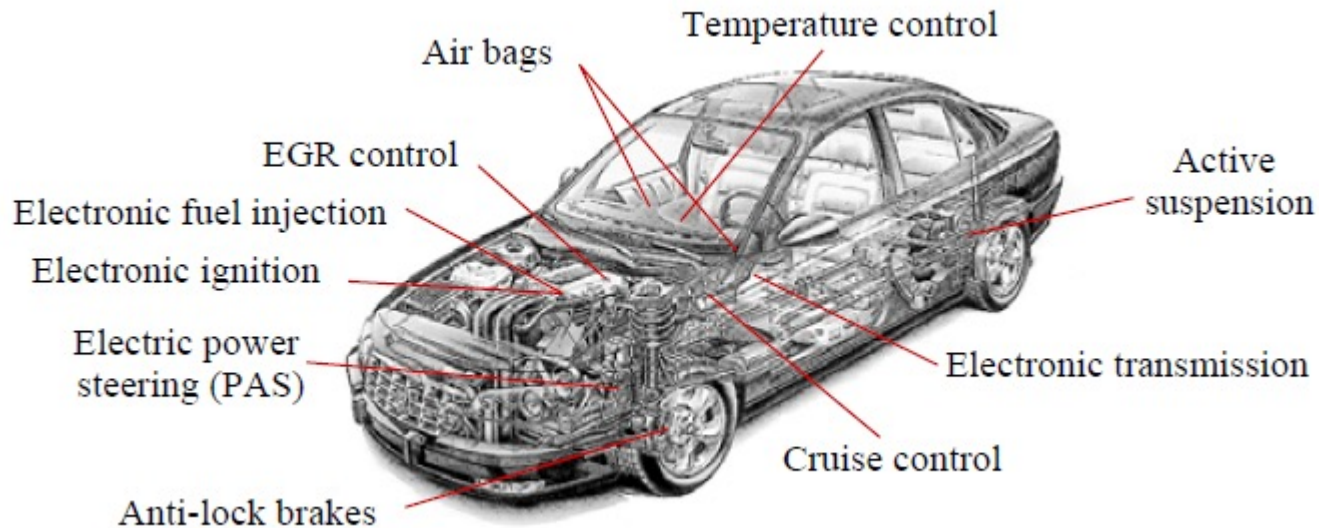
Aerospace



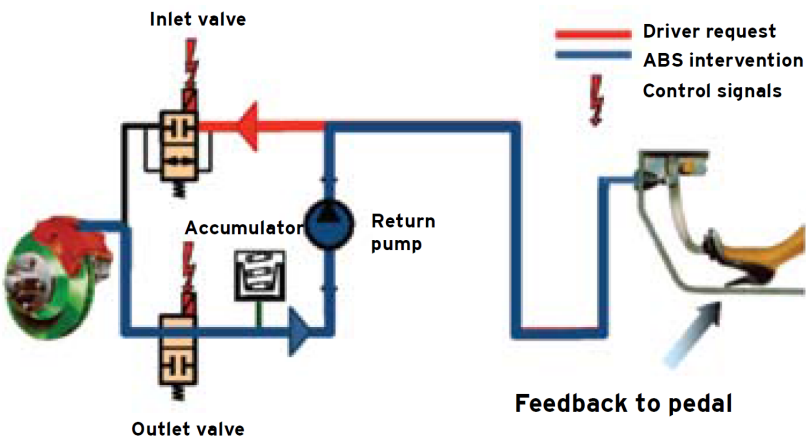
Vehicle control



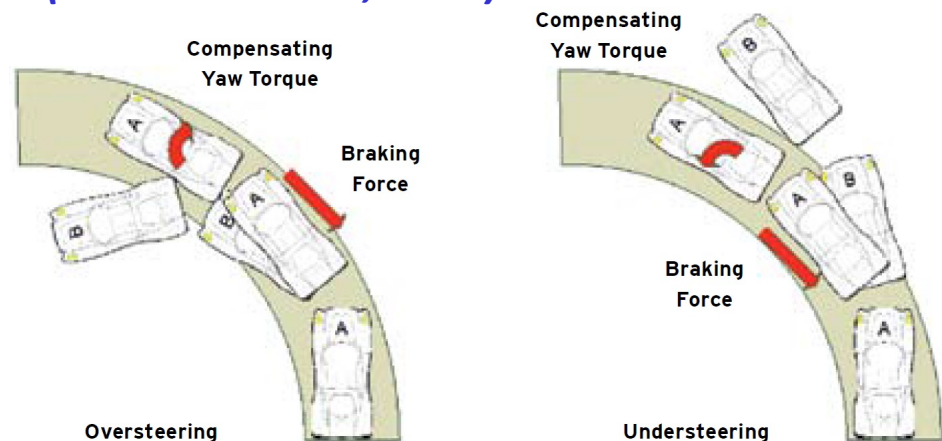
Automobile control



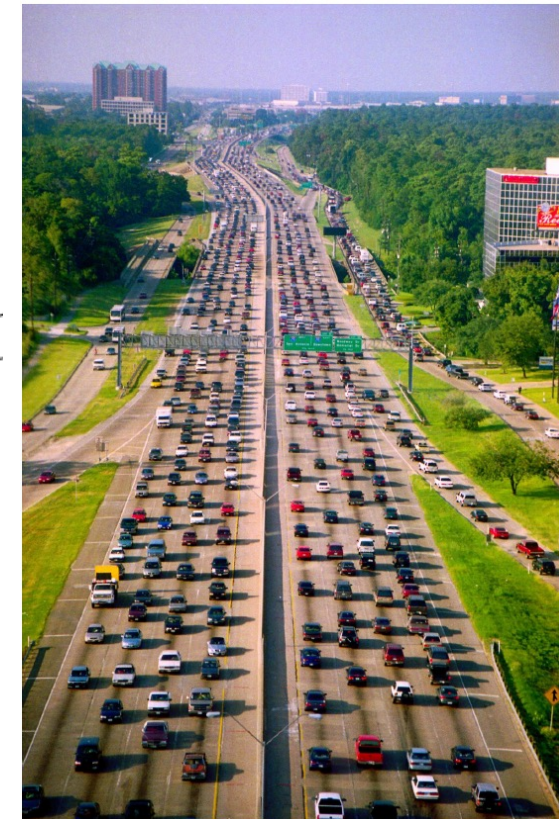
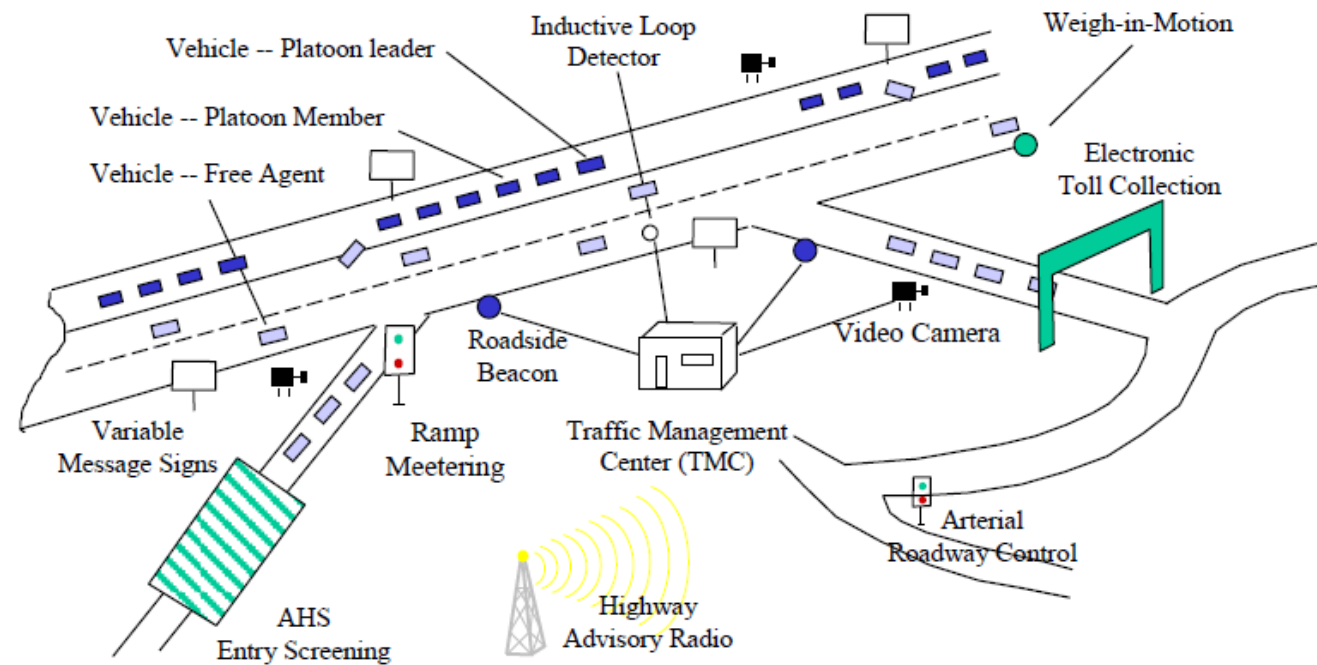
ABS: Antilock braking system (Bosch, 1978)



ESC: Electronic Stability Control (Mercedes-Benz, 1992)



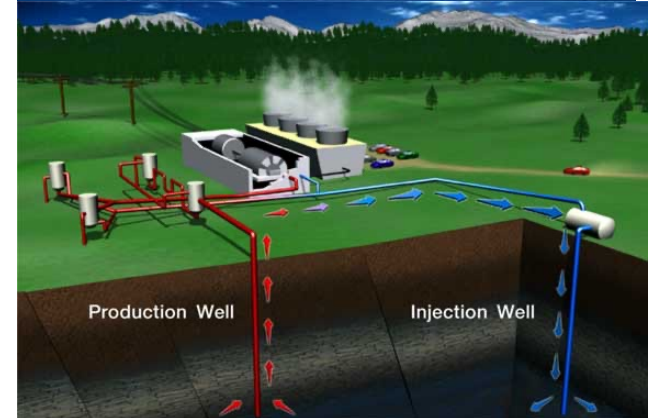
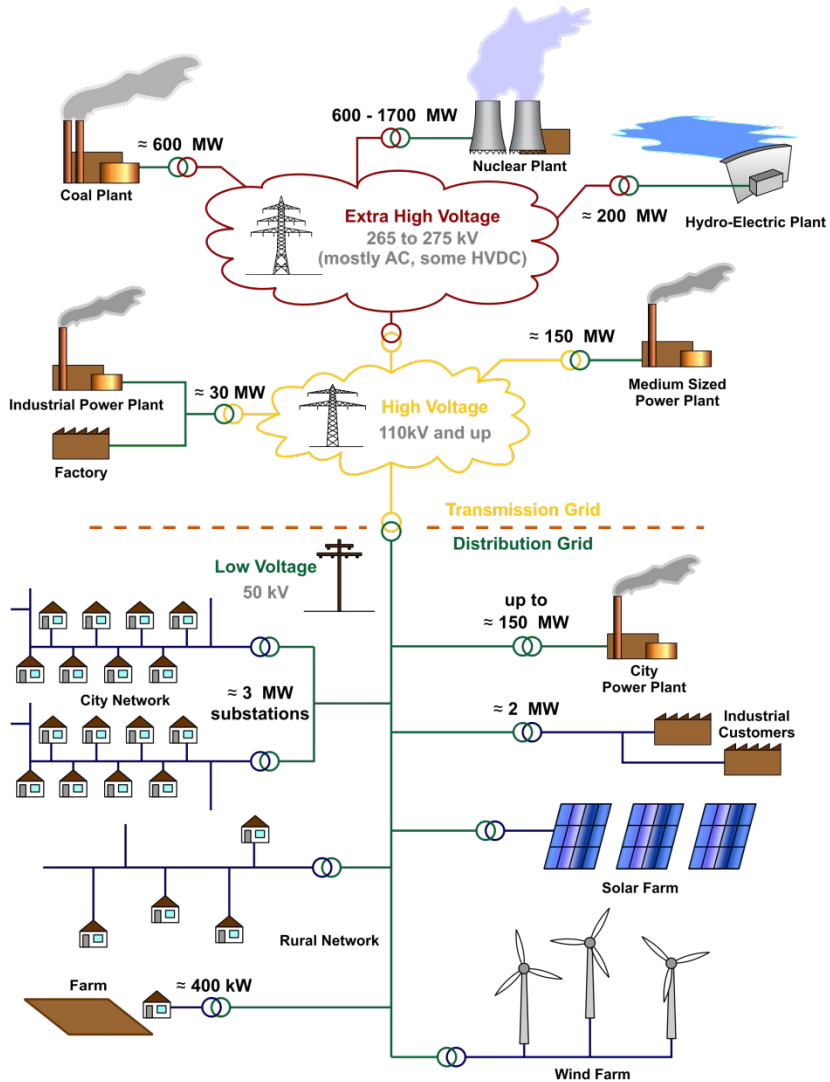
Intelligent vehicle highway systems



Process Industry



Energy control (power grids)



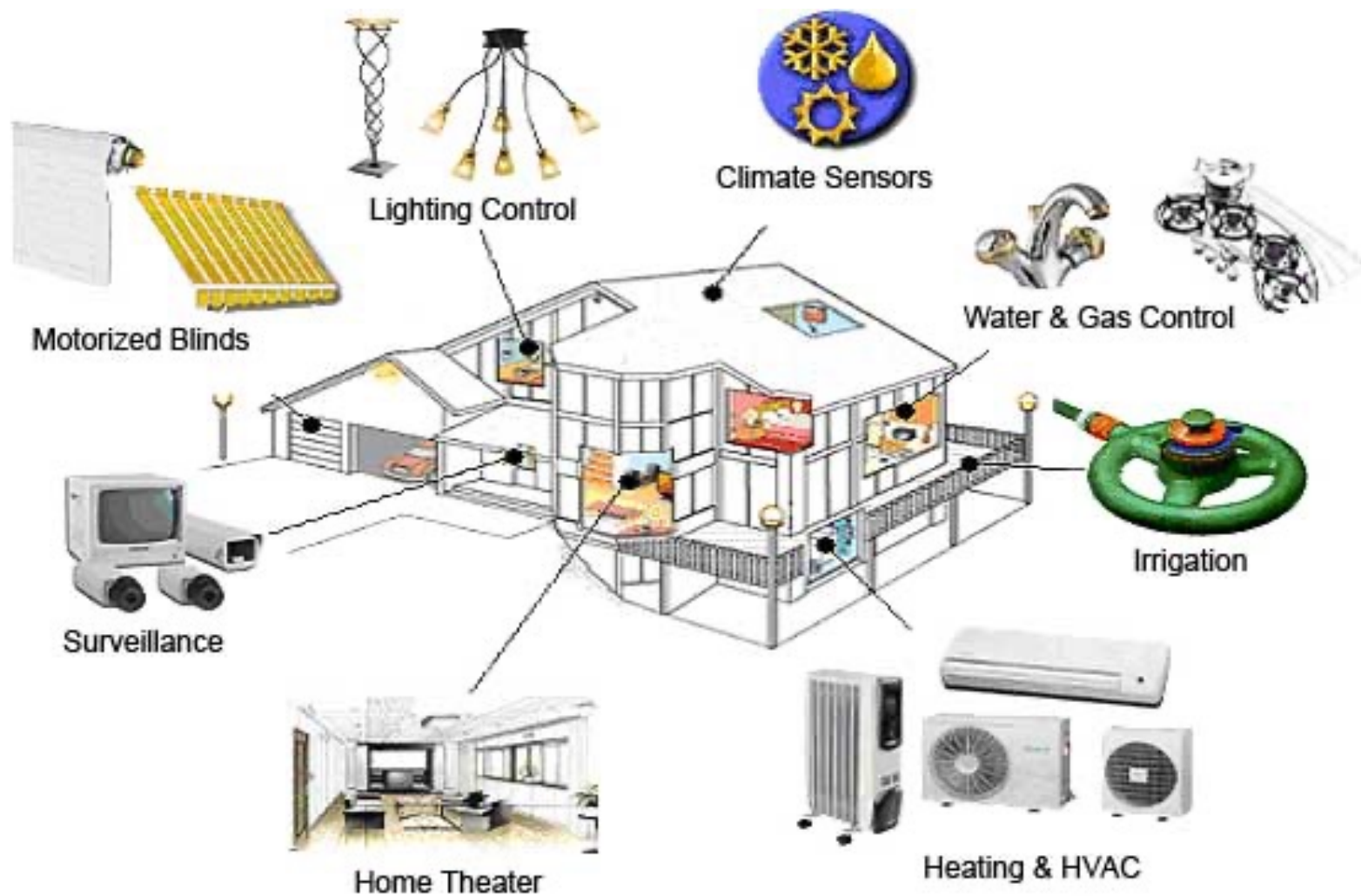


Automated storage and retrieval system

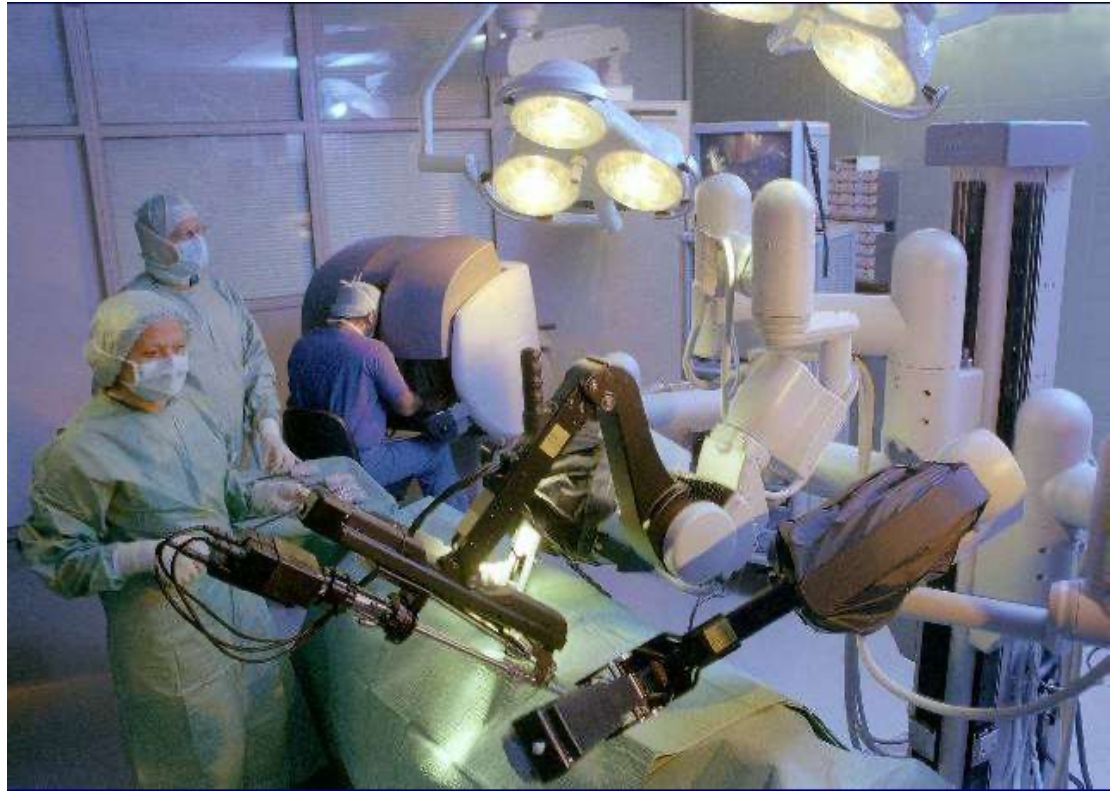


automated guided vehicle (bot)

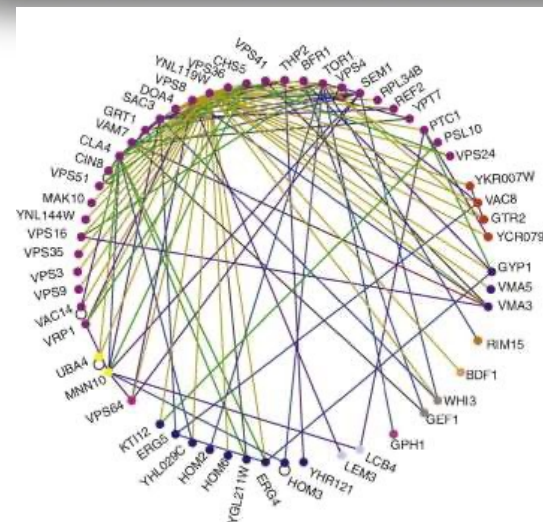
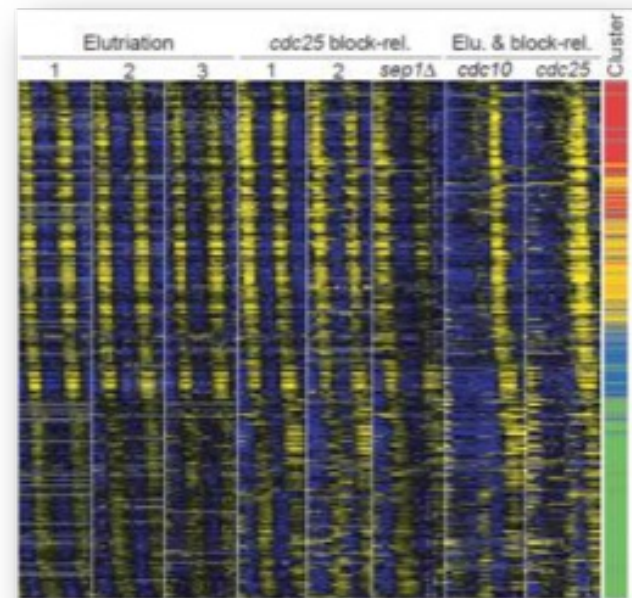
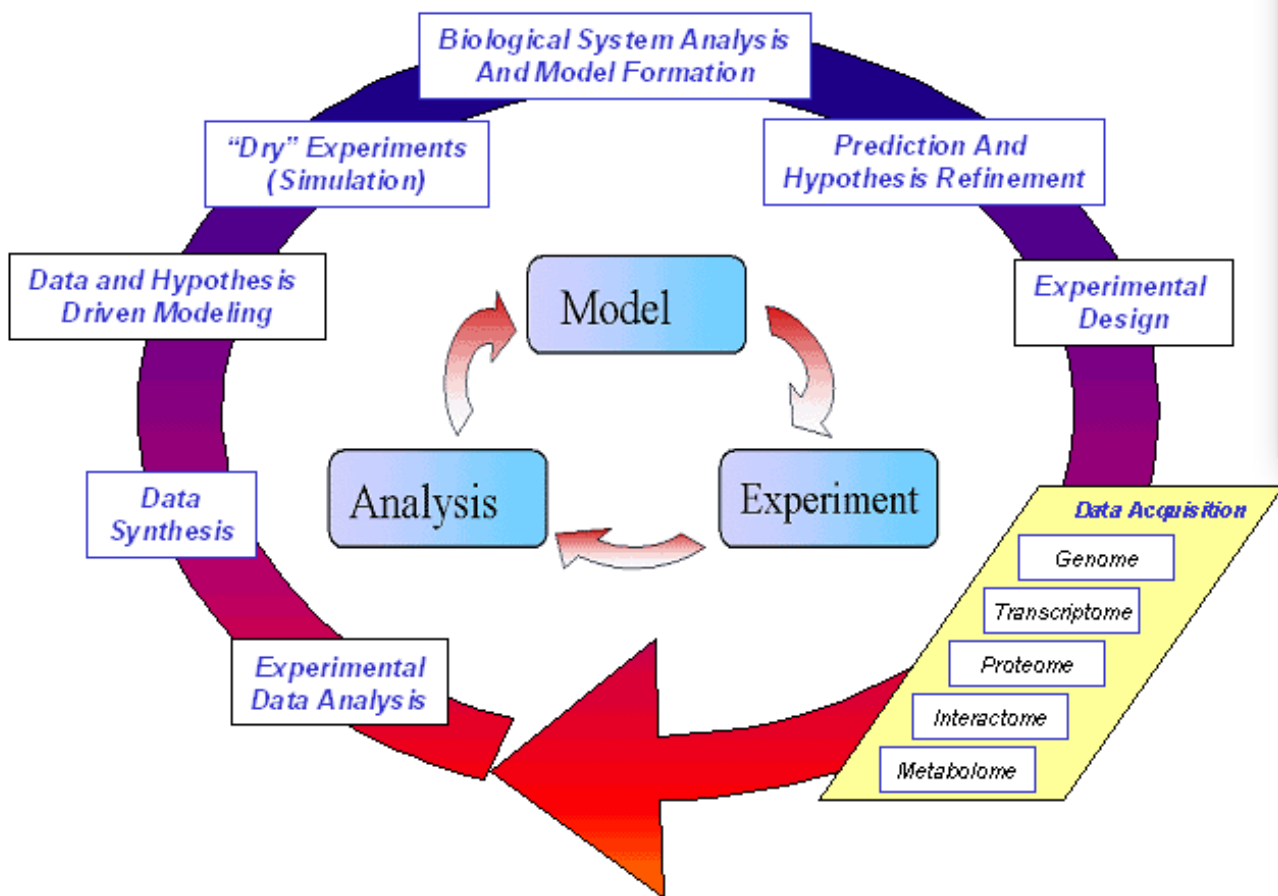
Home automation



Automation in the Life Sciences



Computer-controlled system





Detailed program of the course 1/2

- ✧ Introduction
- ✧ Analysis of linear dynamic system
 - ✧ Definition and classification of dynamical systems
 - ✧ Free and forced evolution of linear system in the time domain
 - ✧ Stability analysis
 - ✧ Definition and properties of Laplace transform
 - ✧ Transfer function
 - ✧ Analysis of linear systems in the frequency domain
 - ✧ Bode diagrams



Detailed program of the course 2/2

- ✧ Understanding of key concepts in control
 - ✧ Feedback and feedforward controls
 - ✧ Block diagrams
 - ✧ Steady-state and transient requirements

- ✧ Design method of feedback control systems
 - ✧ Nyquist plots and Nyquist criteria
 - ✧ Nichols plots and Nichols charts
 - ✧ Frequency shaping technique for closed loop control design
 - ✧ PID
 - ✧ Example