

IN COLLABORATION WITH





Sustainable and Green Transportation

MEIM 2021-2022

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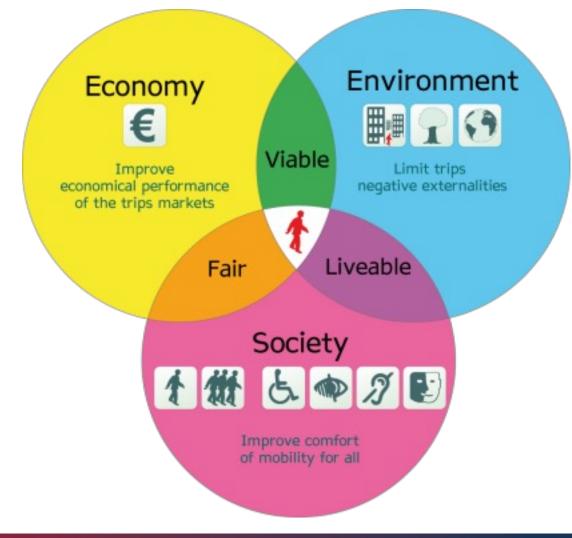
www.meim.uniparthenope.it



Sustainable mobility



Sustainable mobility = Sustainable development applied to mobility







Transportation sustainability

Sustainable transport refers to the broad subject of transport that is or approaches being **sustainable**.

It includes vehicles, energy, infrastructure, roads, railways, airways, waterways, canals, pipelines, and terminals.

Transportation sustainability is largely being measured by transportation system **effectiveness** and **efficiency** as well as the **environmental impacts** of the system



Definition





Sustainable mobility consists in guarantying to citizens the land accessibility and satisfy the travel and mobility freedom on short and long term, meanwhile integrating the collective interest of current and next generations.





Economy, Energy, Environment and Society

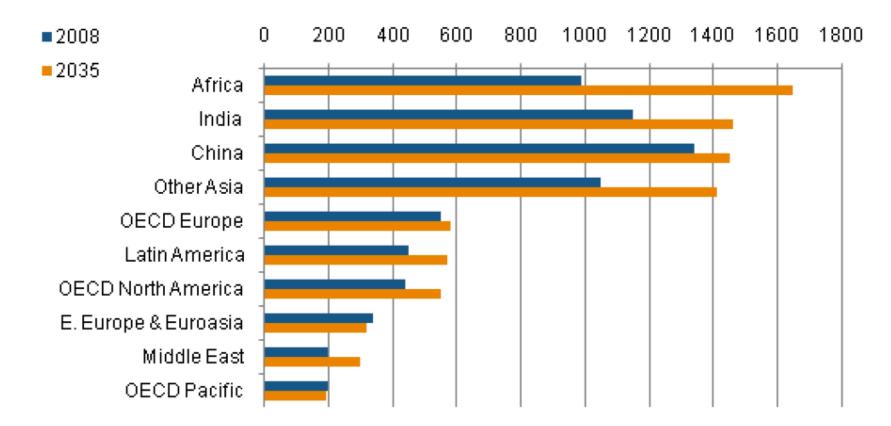




World population projections

Population by major region

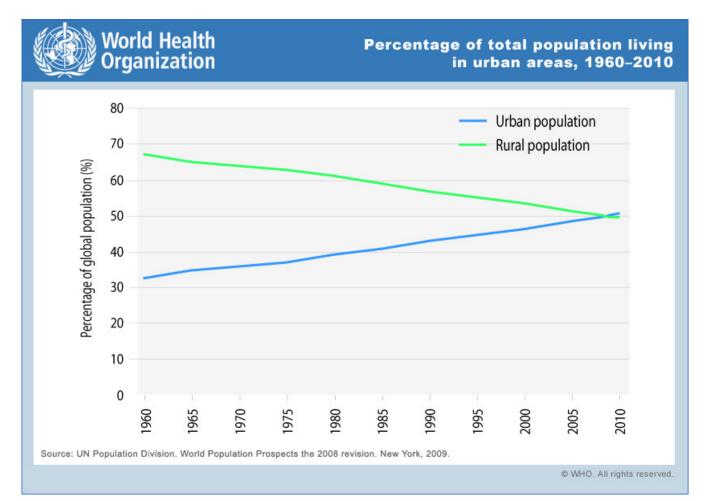
Source: United Nations Population Division and World Bank databases; IEA analysis





Urban vs rural population



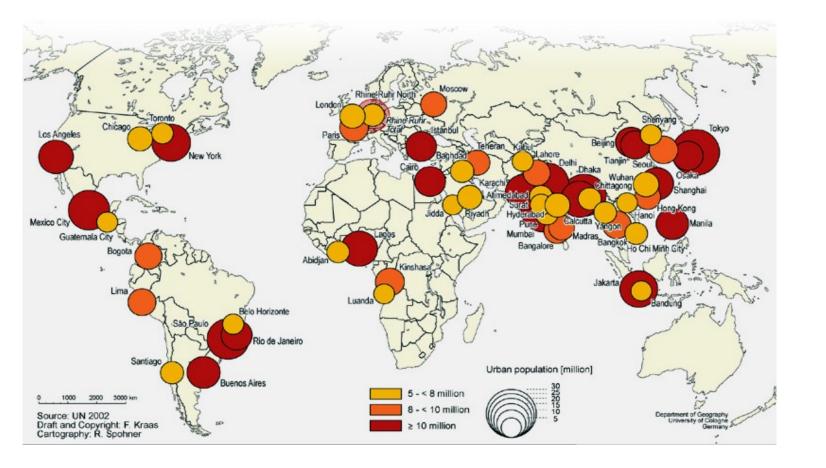


Urban population has surpassed rural population in 2009 http://apps.who.int/gho/data/node.wrapper.URBHEALTH-SITUATION?lang=en





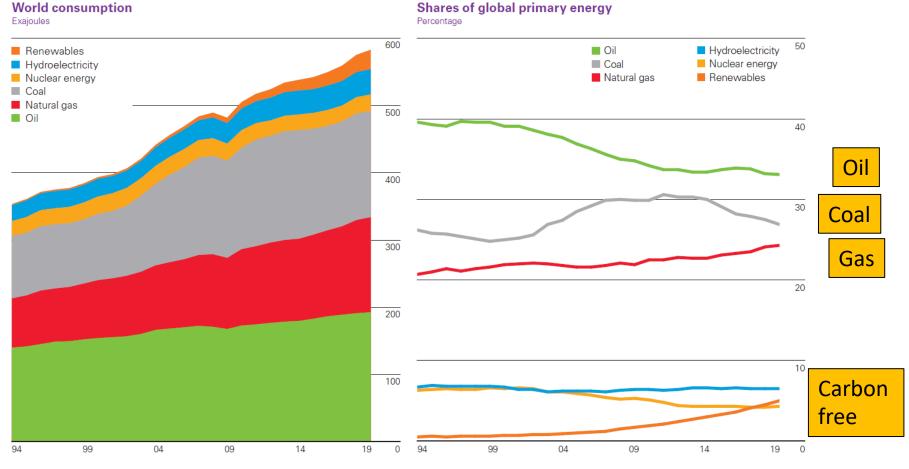
The Emergence of Megacities



- Megacities are engines of growth, rising personal income.
- Megacities produce megaproblems, such as traffic. Mobility in every megacity is unique.



World consumption and shares of primary energy



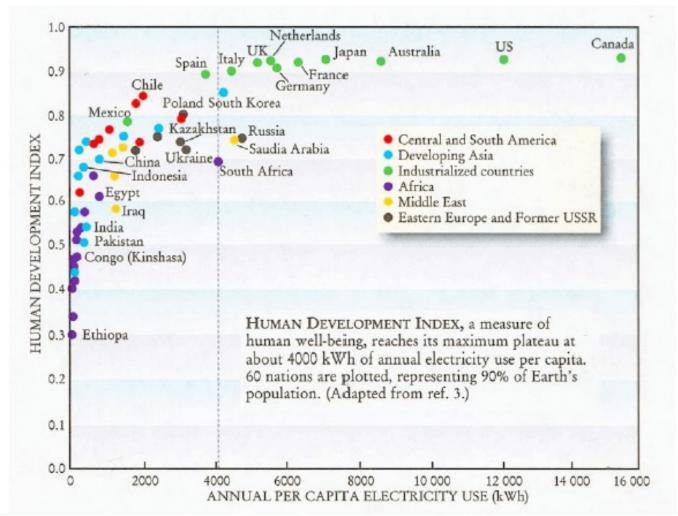
Source: BP Statistical Review of World Energy 2020





Energy Consumption by Country





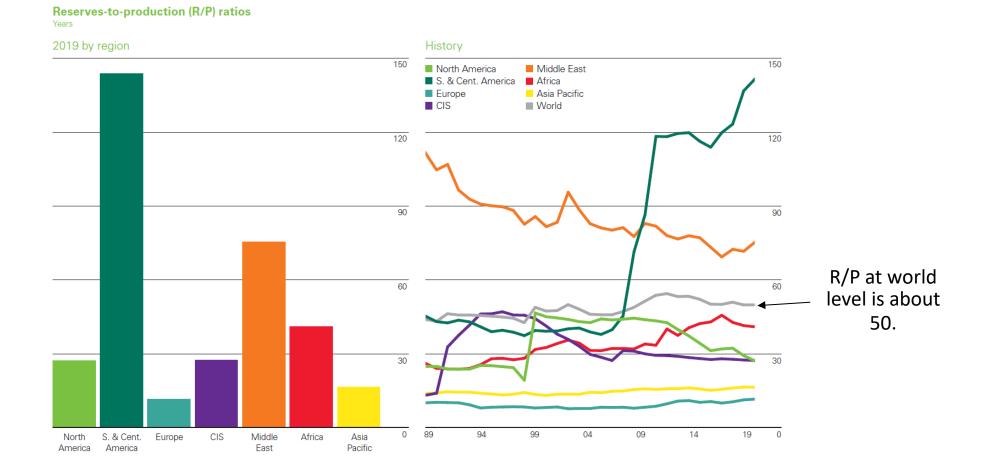
Human development index vs. per capita electricity use for selected countries. Taken from S. Benka, *Physics Today* (April 2002), pg 39, and adapted from A. Pasternak, Lawrence Livermore National Laboratory rep. no. UCRL-ID-140773.







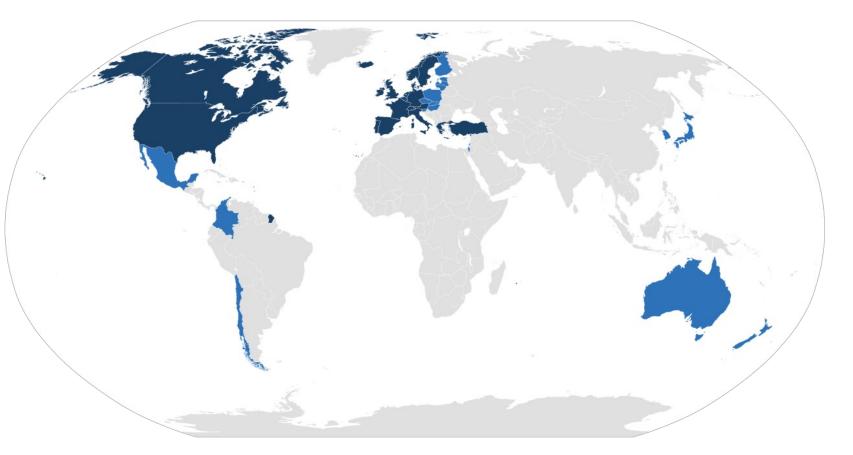
R/P: Ratio between proved reserves and present consumption











The Organisation for Economic Cooperation and Development (OECD)

is an intergovernmental economic organisation with 37 member countries, founded in 1961 to stimulate economic progress and world trade. It is a forum of countries describing themselves as committed to democracy and the market economy,







CIS

The **Commonwealth of Independent States** (CIS) is a regional intergovernmental organization of nine (originally ten) members, plus two founding non-member, post-Soviet republics in Eurasia. It was formed following the dissolution of the Soviet Union in 1991.

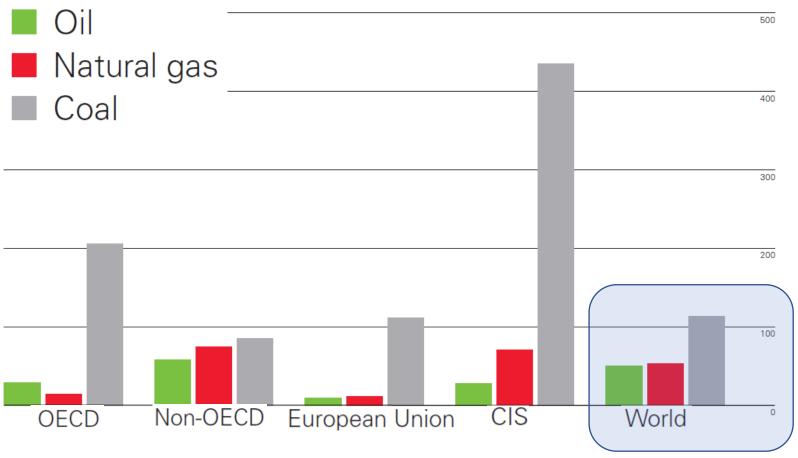


Fossil fuel reserves to production (2015)



Fossil fuel reserves-to-production (R/P) ratios at end 2015

Years



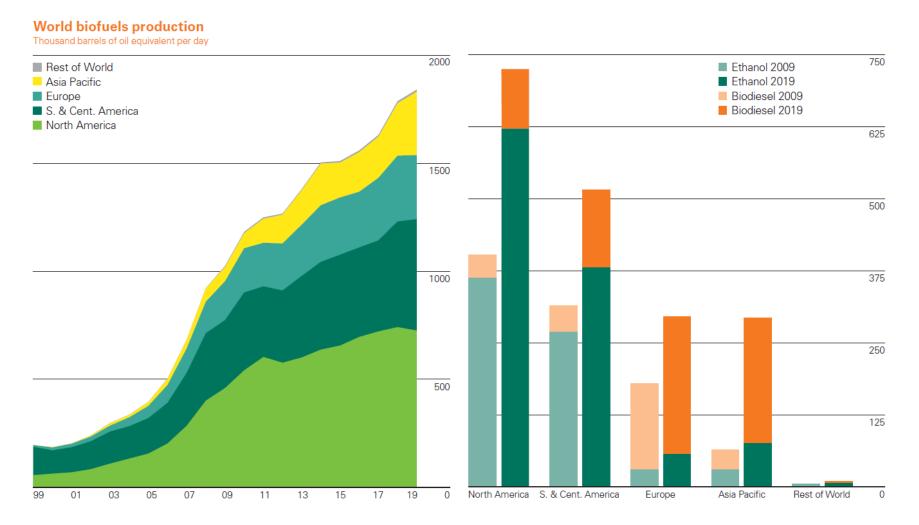
Most energy known fossil reserves are represented by coal and located in ex URSS and OCSE.

BP Statistical Review of World Energy 2016



Biofuels: production



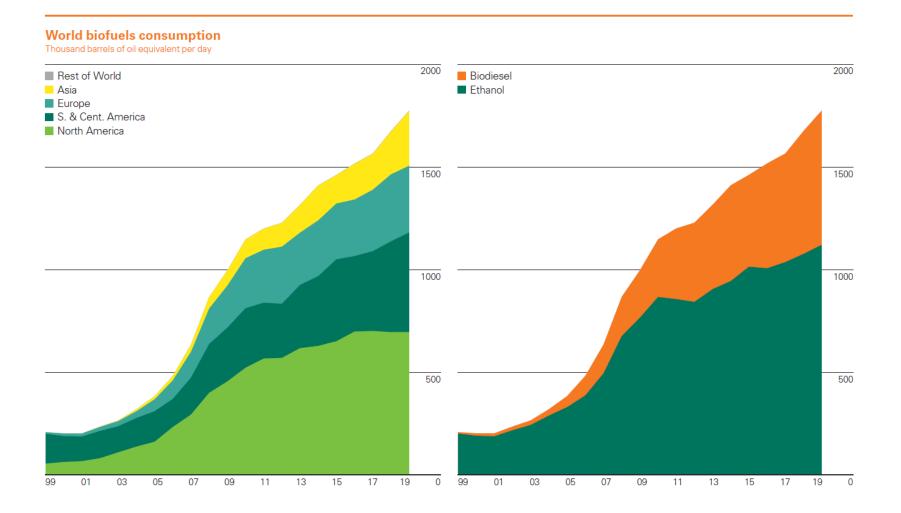


Source: BP Statistical Review of World Energy 2020



Biofuels: consumption





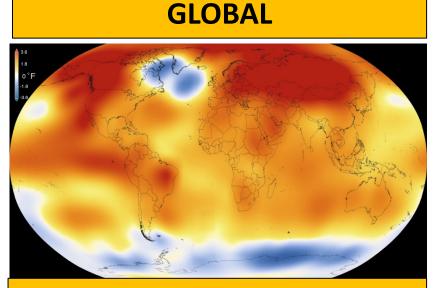
Source: BP Statistical Review of World Energy 2020



Global and Local Emissions



There are two different type of impacts of the emissions on the environment



GHG (Green House Gas), as CO₂, impacting on global warming and climate changes, <u>irrespectively of the</u> <u>location they were generated</u>.

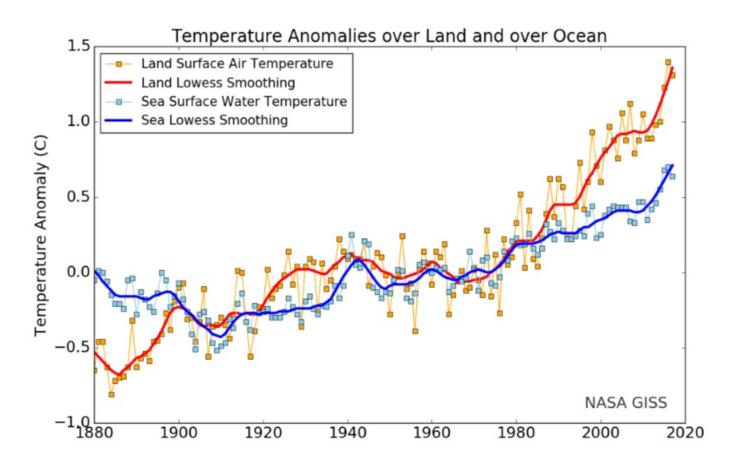


Gaseous emissions (CO, NOx) and PM impacting on smog, air pollution and health. <u>They are</u> <u>particularly harmful in the cities</u>.









The «precautionary principle» must be claimed

Source: NASA – Goddard Institute for Space Studies, 2018 <u>https://data.giss.nasa.gov/gistemp</u>



Global warming and CO2





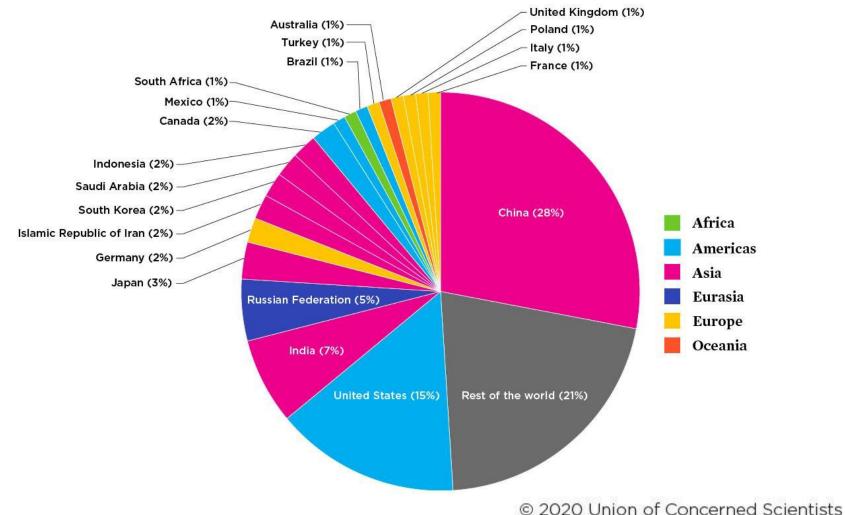
CO2 concentration: 405,4 ppm¹, CO2 safeguard limit: 450 ppm² CO2 annual growth: 1.5 ppm/Y²

¹ MAUNA LOA Observatory data, <u>https://www.co2.earth/co2-monitoring</u> ² IPCC Sixth Assessment Report, September 2017, https://www.ipcc.ch/



CO2 Emissions by Country





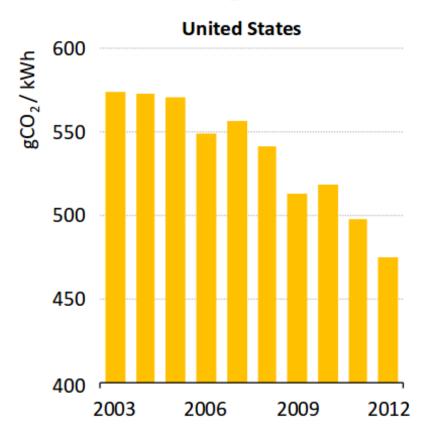
Data: Earth Systems Science Data 11, 1783–1838, 2019

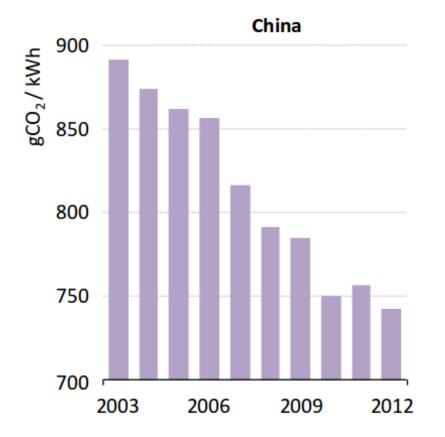




CO2 Emissions by Country

CO₂ emissions per unit of electricity generation







Global warming and CO2? Nothing new!

"The Rodnen & Otamatea Time", a New Zealand newspaper, predicted global warming due to CO₂ emissions in **1912**!



The Rodney & Otamatea Times waitemata & kaipaka gazette. PRICE-10s per annum in advance WARKWORTH, WEDNESDAY, AUGUST 14, 1912. 3d per Copy.

COAL CONSUMPTION AFFECT-ING CLIMATE.

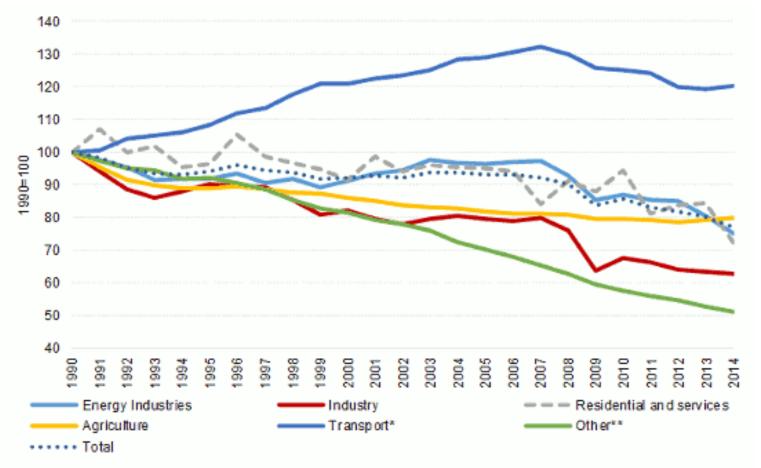
Science Notes and News,

The furnaces of the world are now burning about 2,000,000,000 tons of coal a year. When this is burned, uniting with oxygen, it adds about 7,000,000,000 tons of carbon dioxide to the atmosphere yearly. This tends to make the air a more effective blanket for the earth and to raise its temperature. The effect may be considerable in a few centuries.



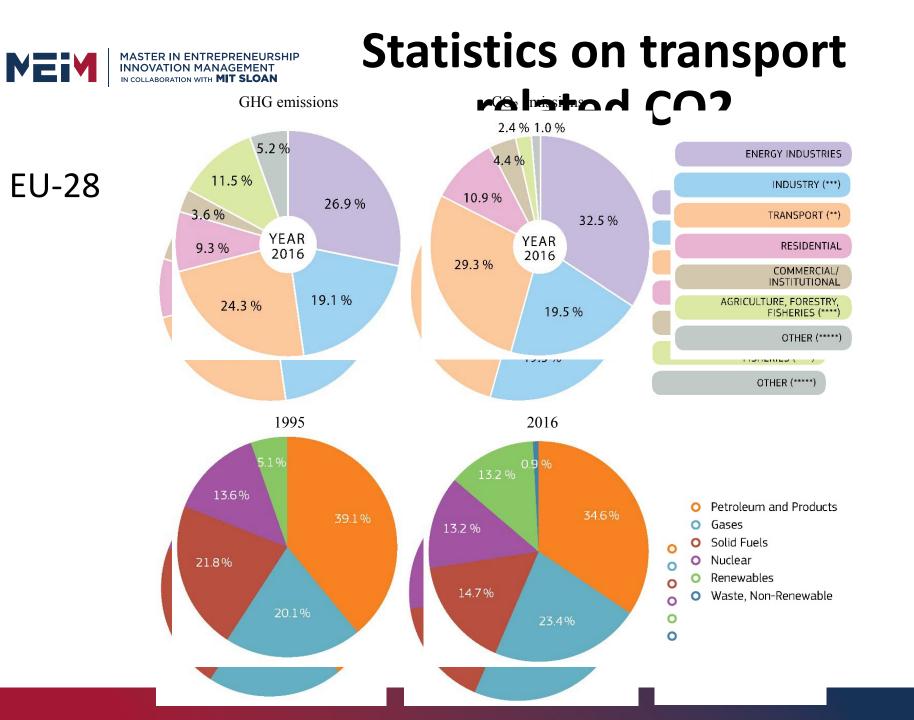


CO2 emissions per sectors (EU)



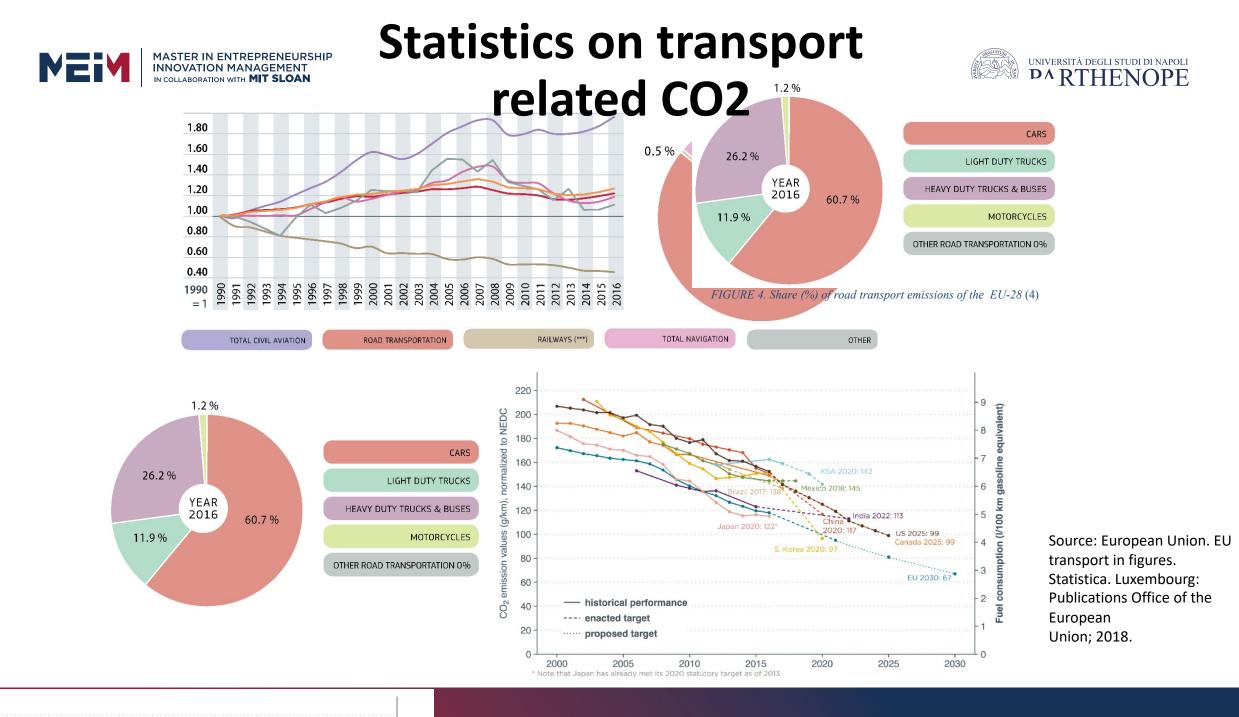
https://ec.europa.eu/clima/policies/transport_en

Transport represents almost a quarter of Europe's greenhouse gas emissions and is the main cause of air pollution in cities. The transport sector has not seen the same gradual decline in emissions as other sectors: emissions only started to decrease in 2007 and still remain higher than in 1990.





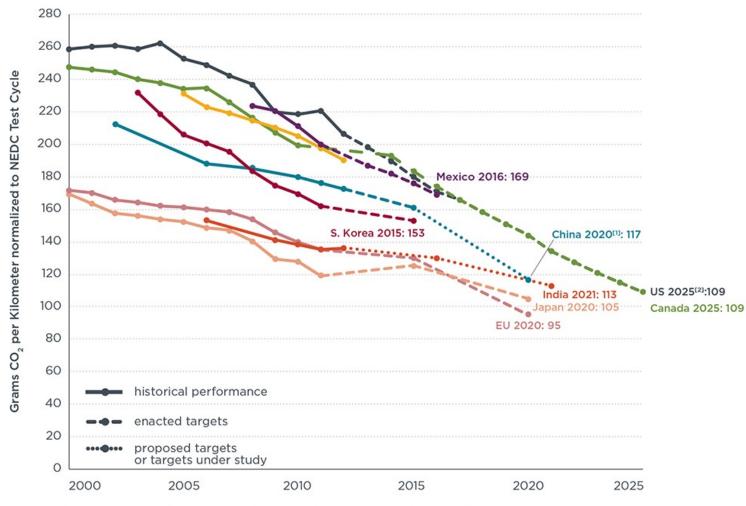
Source: European Union. EU energy in figures. Statistica. Luxembourg: Publications Office of the European Union; 2018.





CO2 Regulations





[1] China's target reflects gasoline vehicles only. The target may be higher after new energy vehicles are considered. [2] US, Canada, and Mexico light-duty vehicles include light-commercial vehicles.

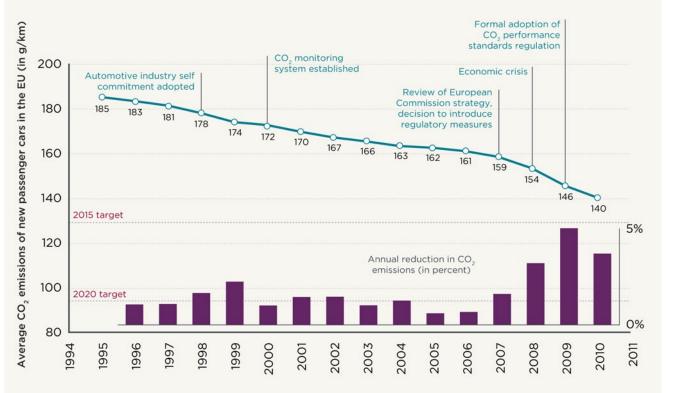
[3] Supporting data can be found at: http://www.theicct.org/info-tools/global-passenger-vehicle-standards



EU CO2 Regulations



CO₂ **PERFORMANCE STANDARDS IN THE EUROPEAN UNION** New passenger cars 1995-2010



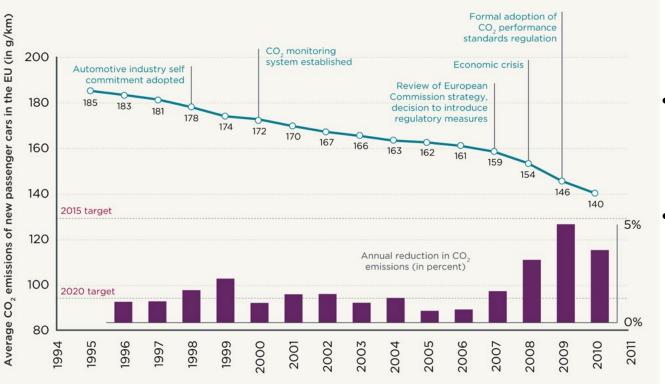
- In 1998, the European Automobile Manufacturers' Association (ACEA), JAMA, and KAMA agreed to reduce average CO2 emissions from new cars sold to 140 g/km by 2008, which translated into a 25% reduction compared to the 1995 level.
- They also agreed to review the rate of progress, with a view toward making subsequent reductions —120 g CO2/km by 2012.
- But the automakers' commitment lacked any binding burden-sharing. The result was annual emission reductions of only 0.6 to 2.2% between 1998 and 2006.
- As it became clear that neither the 2008 target of 140 g CO2/km nor the 120 g CO2/km objective for 2012 would be met, the European Commission announced that it would propose mandatory reductions.
- The regulation (EC 443/2009) setting CO2 emission performance standards for new passenger cars was adopted in April 2009



EU CO2 Regulations



CO₂ **PERFORMANCE STANDARDS IN THE EUROPEAN UNION** New passenger cars 1995-2010

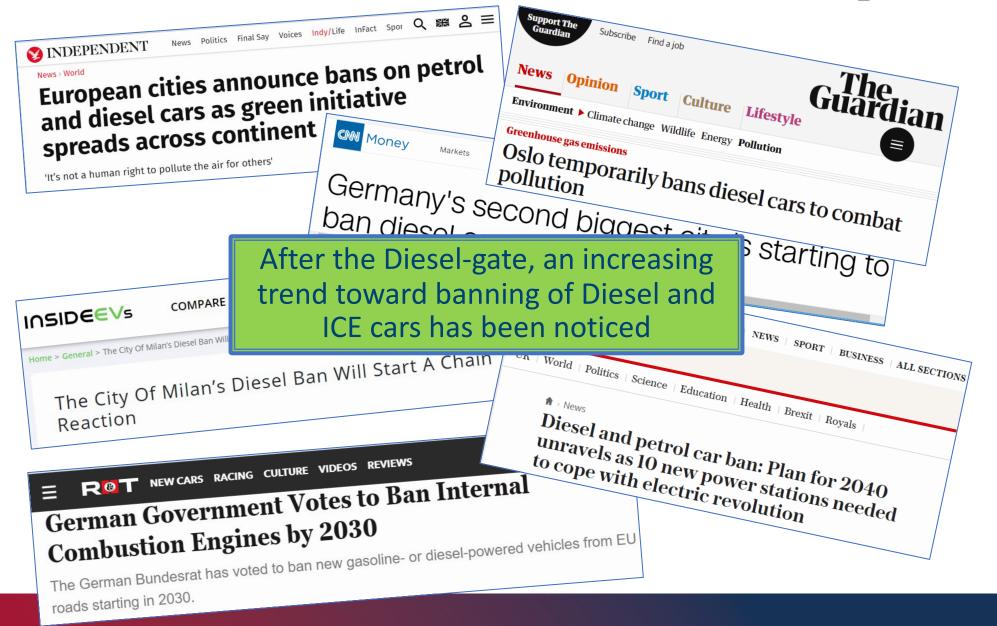


- Beginning with the Commission's announcement, the rate of reduction in specific CO2 emissions from new passenger cars began to rise sharply: 1.6% in 2007, 3.2% in 2008 and 5.4% in 2009.
- This suggests the **magnitude of difference regulation makes**.
- While the effects of the economic crisis and resulting incentives for new vehicle purchases offered by many EU member states potentially distort the annual emission reduction for 2009, the trend is very clear: switching from a nonbinding voluntary industry commitment to a binding regulation spurred significant reductions in specific CO2 emissions from new passenger cars in the EU.



Diesel/ICE ban coming?

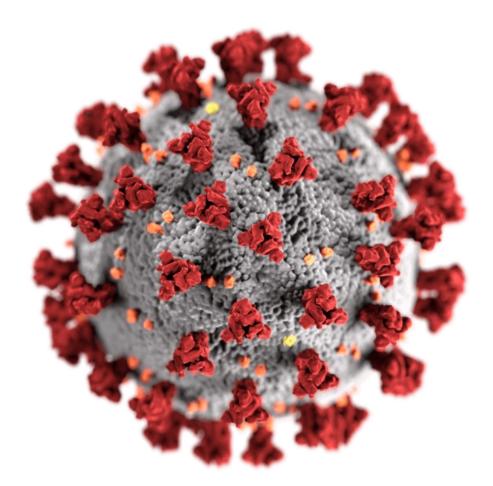






COVID Effects





Since 2020, the COVID pandemic produced their effects on road transport also





CO2 and global warming







Everybody's Health







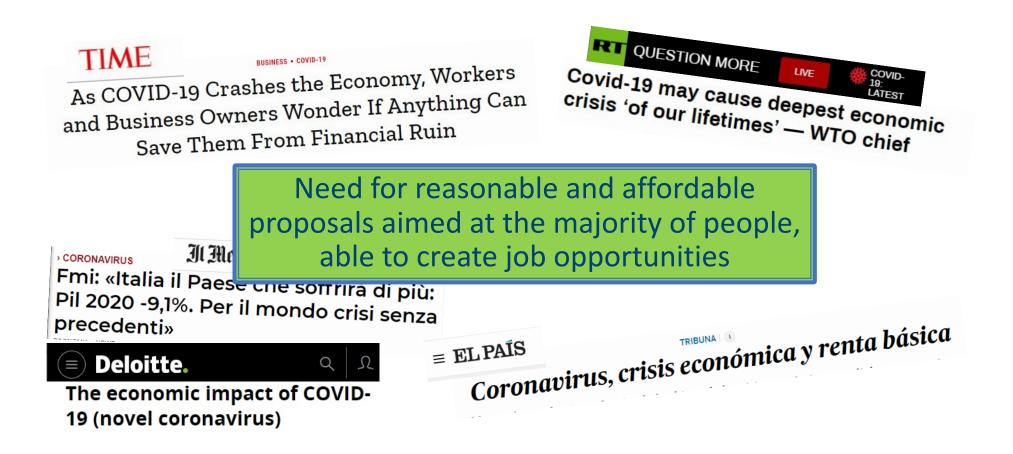
The way we will move around







Jobs and money





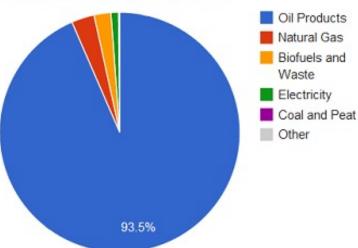
Transportation Energy



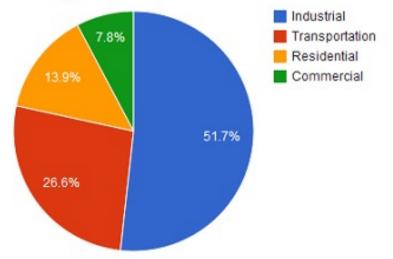
Worldwide energy use totaled **524 quads** in 2012, with **transportation using about 27%**

(A quad is a unit of energy equal to 1.055×10^{18} joules (1.055 exajoules or EJ) in SI units)

World Transportation Energy by Source, 2009 (IEA data)



World Energy Consumption by Sector, 2012 (EIA Data)

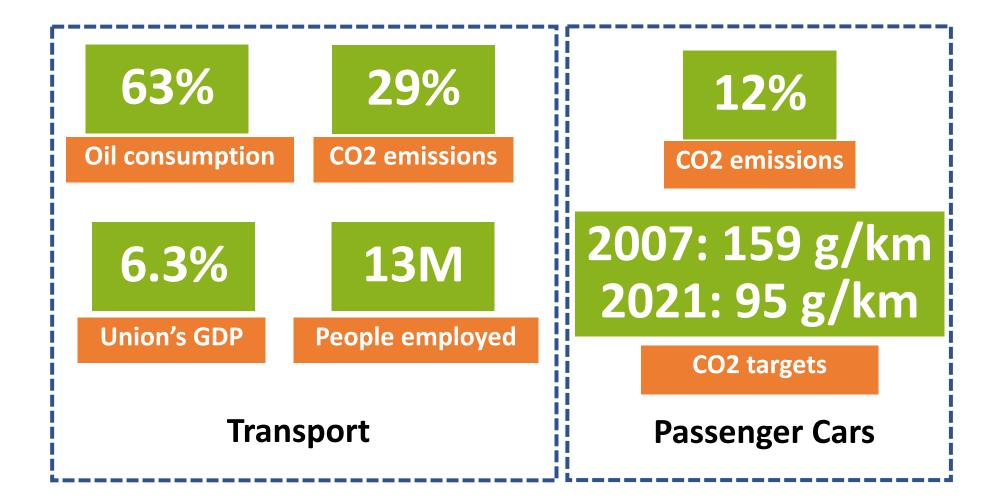


About 93% of transportation energy consumption comes from **petroleum** for a total of 87 million barrels per day.





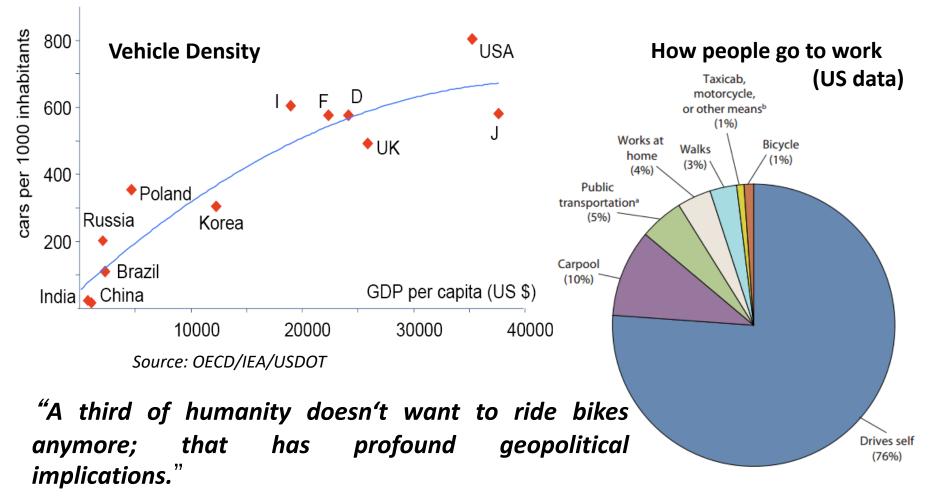
Transport is a major issue for EU





Vehicle Density and Use





Anne Korin, the co-director of the Institute for the Analysis of Global Security (May 1, 2005)



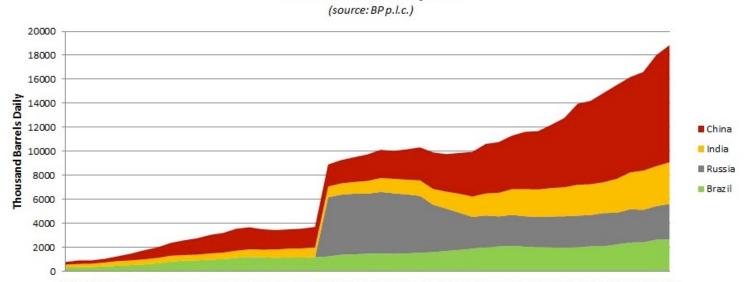
Transportation Energy



In 2011, **60%** of the total transportation energy consumption in the United States was used for **personal transportation** (passenger cars, light trucks, and motorcycles)

The **demand** for personal transportation is **rapidly growing** in the world, mostly due to the economic development of countries such as Brazil, Russia, India, China (BRIC).

BRIC Oil Consumption



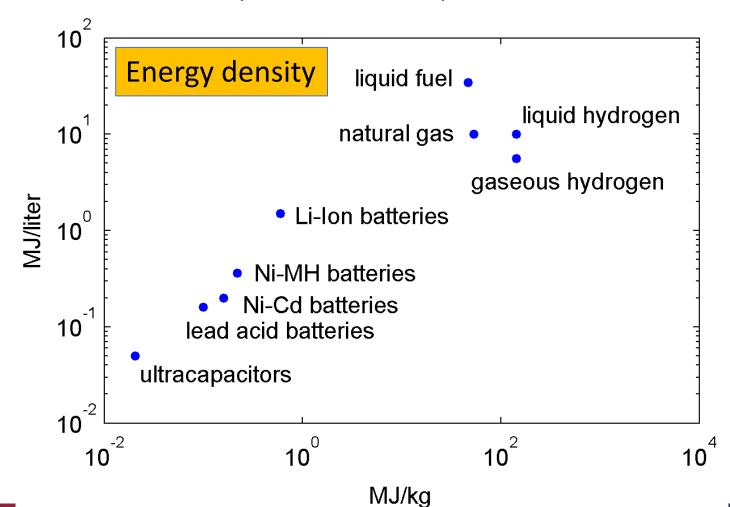
1965 1967 1969 1971 1973 1975 1977 1979 1981 1983 1985 1987 1989 1991 1993 1995 1997 1999 2001 2003 2005 2007 2009 2011







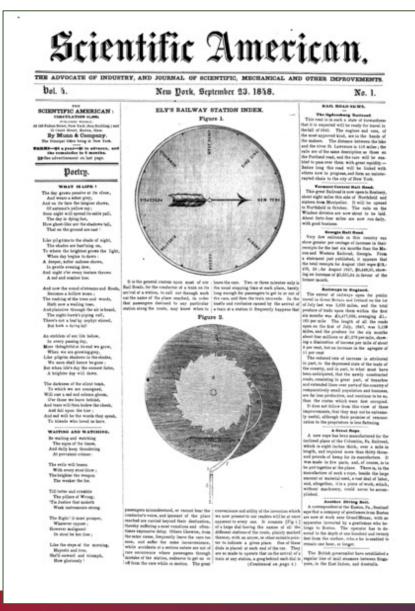
How can we achieve petroleum independence ?





Predictions





"That the <u>automobile has</u> <u>practically reached the</u> <u>limit of its development</u> is suggested by the fact that during the past year no improvements of a radical nature have been introduced."

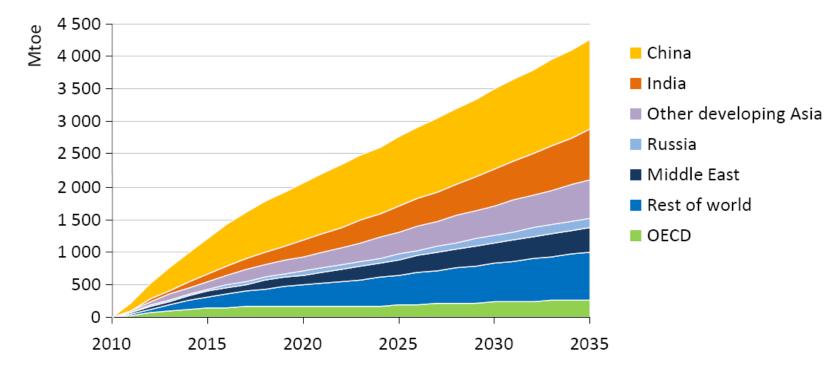
Scientific American, Jan. 2, 1909







Growth in primary energy demand



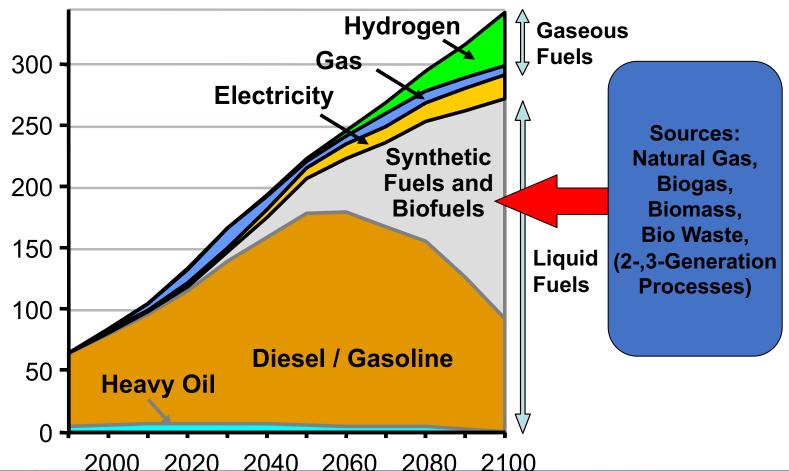
Global energy demand increases by one-third from 2010 to 2035, with China & India accounting for 50% of the growth



Availability of Fuels in the Future



Energy Demand (x10¹⁸ J)



Source: She





Transport scenarios

Two different scenarios have been studied by the World Energy Council:

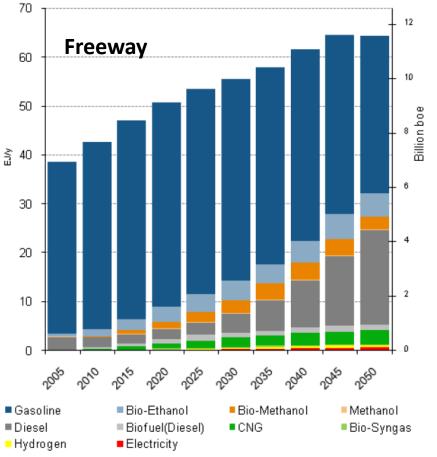
- Freeway: market forces prevail to create a climate for open global competition, privatization, deregulation and liberalization.
- **Tollway:** Regulated world where governments decide to put common interests at the farefront and intervene in markets.

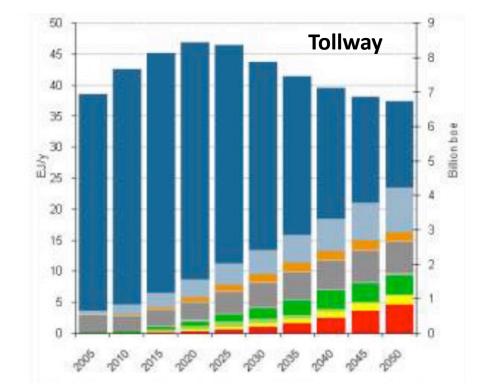


MASTER IN ENTREPRENEURSHIP Fuels for LDV/cars: demand between 2010 and 2050



In Freeway, global fuel consumption for cars is expected to increase by about 51% between 2010 and 2050. The world's car fleet will still depend heavily on gasoline and diesel, which will still constitute about 80% of the fuel mix in 2050.

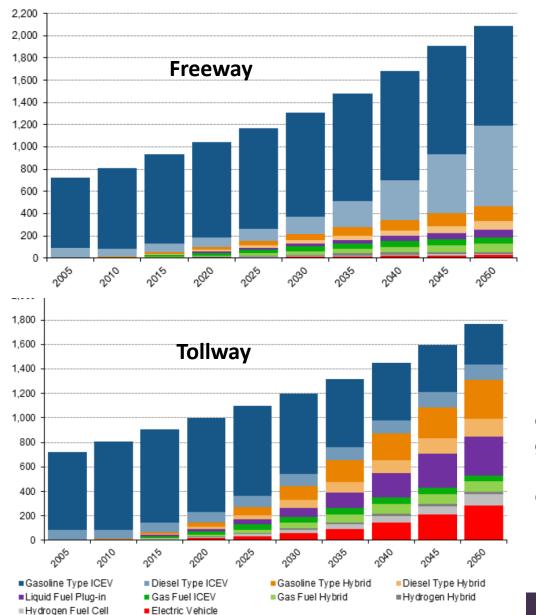




For Tollway, the global fuel consumption for cars is expected to drop by about 13% between 2010 and 2050. Car fleet will still depend on fossil fuels as gasoline and diesel will still constitute about 52% of the fuel mix in 2050



Technology mix for cars



In **Freeway** the global car fleet will still be dominated by a **78%** share for the conventional liquid fuel ICEV (43% gasoline and 35% diesel). Gasoline and diesel **hybrids** are expected to share about 11% (7% gasoline and 4% diesel). The gas ICEV and gas hybrids are expected to be about 7%. The remaining minority 6% is captured by electric, fuel cells, and plug-in vehicles.

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PARTHENOPE

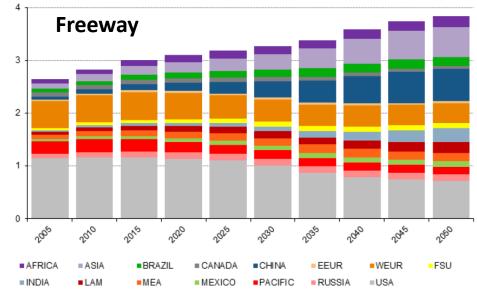
In **Tollway**, the global car fleet in 2050 has shares of **26%** for liquid fuel conventional ICEV (19% gasoline and 7% diesel); **26% for liquid hybrids** (18% gasoline and 8% diesel); 18% plug-ins; 16% electric; 8% gas vehicles



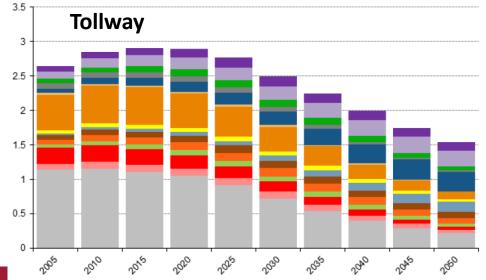
Impact on CO2



CO₂ emissions from cars (GtCO₂/y)



Although global fuel consumption for cars is expected to increase by about 51% between 2010 and 2050, CO2 emissions from cars are expected to **increase by 36%**. The relative drop in CO2 emissions is primarily due to engine fuel-burning improvements and changes in fuel mix, namely consuming more biofuels and CNGs.



Due to the 13% drop in global fuel consumption for cars between 2010 and 2050, CO2 emissions from cars are also expected to **drop by 46%**. As with Freeway, the relative drop in CO2 emissions is primarily due to engine fuel-burning improvements and the changes in fuel mix, namely consuming more biofuels and CNGs.





2018 BP Energy Outlook The Evolving Transition scenario

Efficiency

gains

2040

Contributions to transport

energy consumption growth

Population

growth

Income

per head

Billion toe

5

4

3

2

0

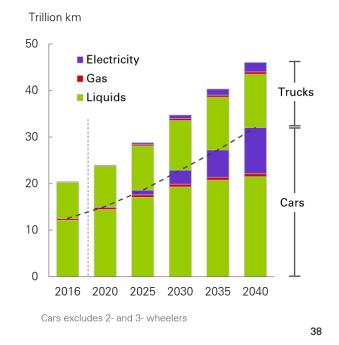
2016

% per annum -GDP 6% -Primary energy 5% Energy intensity 4% 3% 2% 1% 0% -1% -2% -3% 1970- 1980- 1990- 2000- 2010- 2020- 2030-1980 1990 2000 2010 2020 2030 2040

Growth in GDP and primary energy

World GDP more than doubles by 2040. Slow growth in transport energy consumption. The share of vehicle kilometres **powered by** electricity increases.

Vehicle kilometres (Vkm) by fuel type





Passenger car parc growing

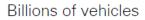
Litres/100km**

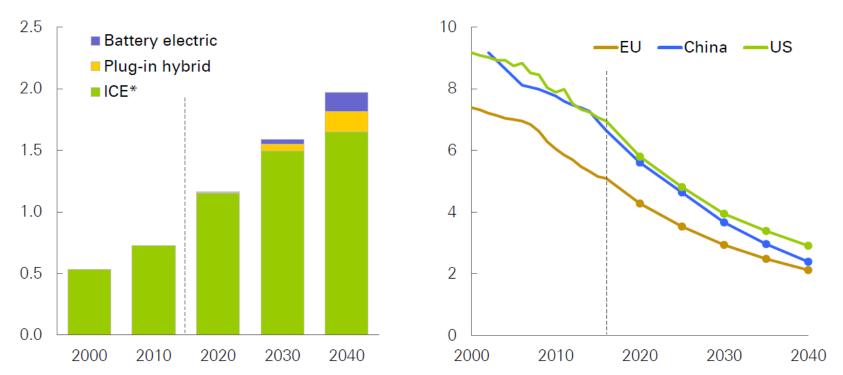


Evolving Transition scenario

Passenger car parc by type

Fuel economy of new cars





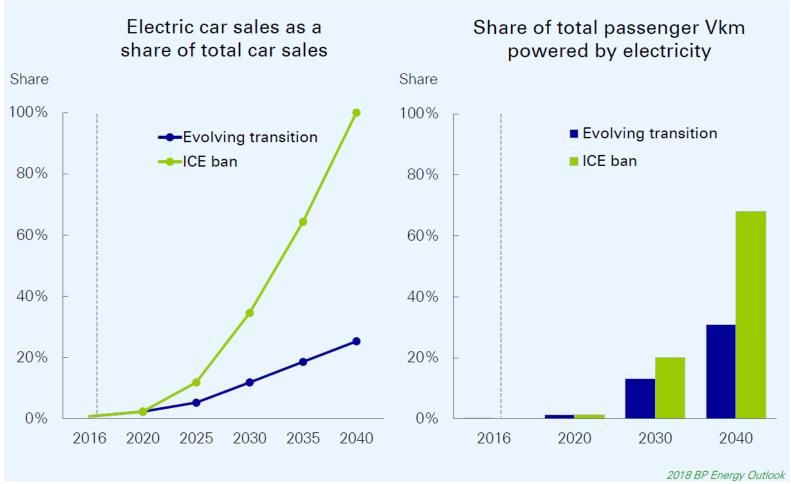
*ICE vehicles includes hybrid vehicles which do not plug into the power grid **Based on the NEDC (New European Drive Cycle), gasoline fuel

2018 BP Energy Outlook



Alternative scenario: impact of faster growth in electric





Even in the most advanced scenario (ICE ban) the share of electric car sales would reach 50% between 2030 and 2035. In the more conservative scenario (ET) the share would be 3 times lower.







Transport systems have significant impacts on the environment, accounting for **20% - 25% of world energy consumption and carbon dioxide emissions**.

Greenhouse gas emissions from transport are increasing at a faster rate than any other energy using sector.

Road transport is also a major contributor to **local air pollution and smog**.

Vehicles powered by **liquid fuels** will continue to play a relevant role, according to many scenarios.







Fossil fuels represent an enormous economic cost, with political, economic, and environmental risks associated to oil exploration and production

Fossil fuels are responsible for a significant **fraction of anthropogenic** CO_2 : about 1/3 of total CO_2 emissions from energy consumption.

Oil dependence is becoming a **pressing issue** for many countries.







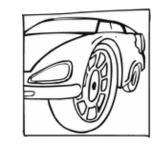
Limits of conventional vehicles and possible alternatives

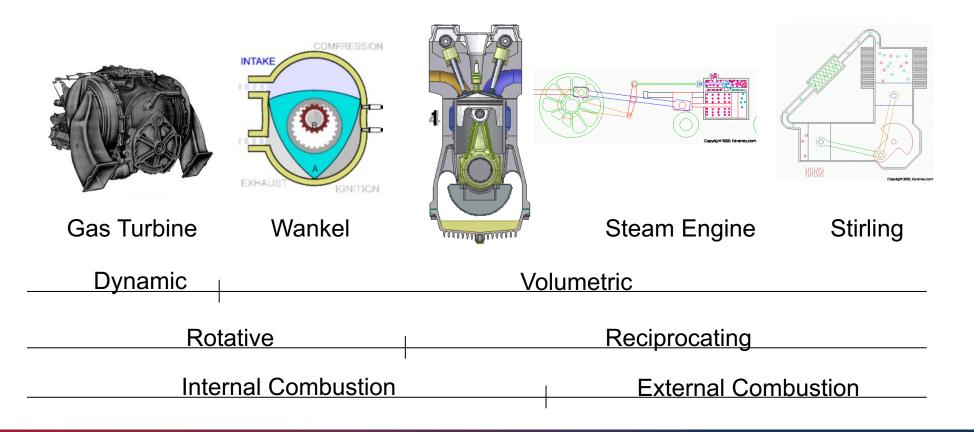


Thermal Engines



A large majority of today vehicles is moved by a thermal engine

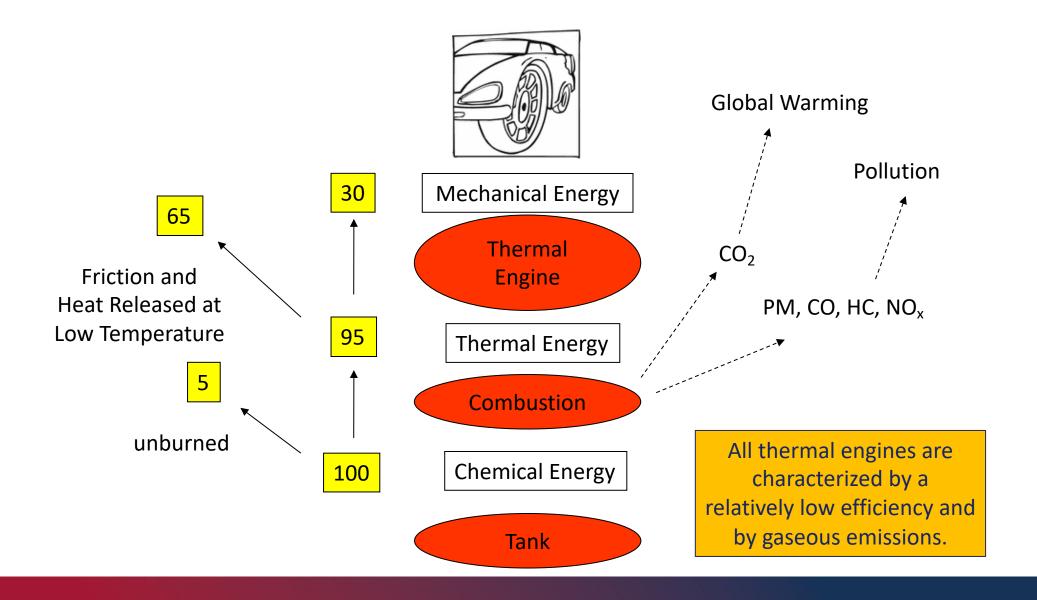








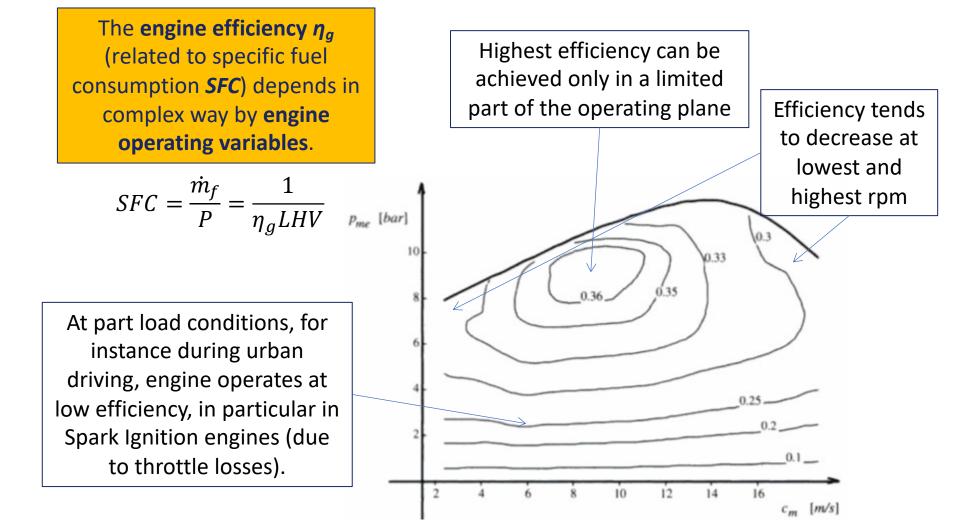






Engine efficiency map

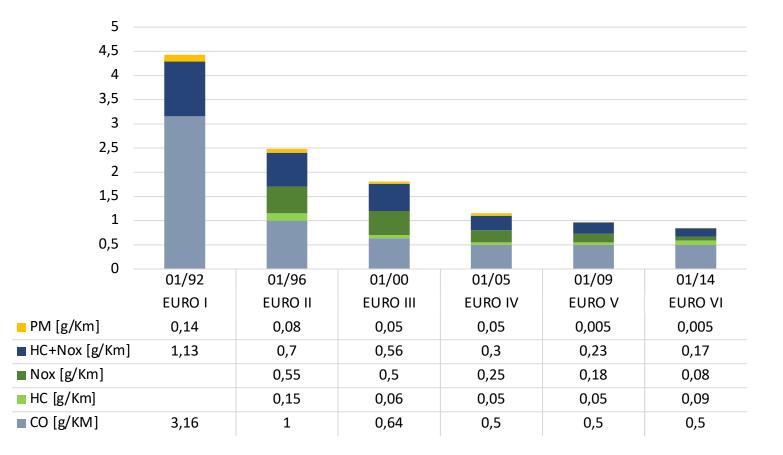






NOx/HC/CO/PM





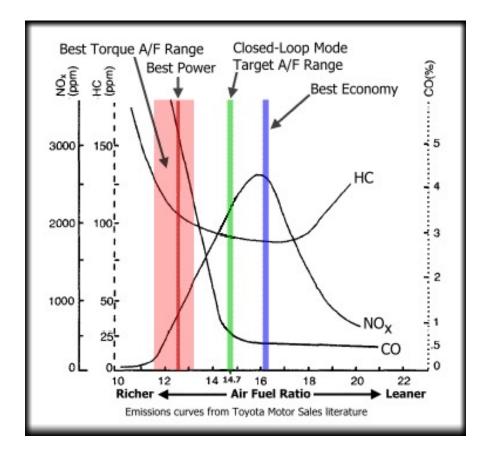
The trend in the reduction of admitted pollutant emissions has continued until last years, both in US (EPA) and in Europe.



NOx/HC/CO/PM



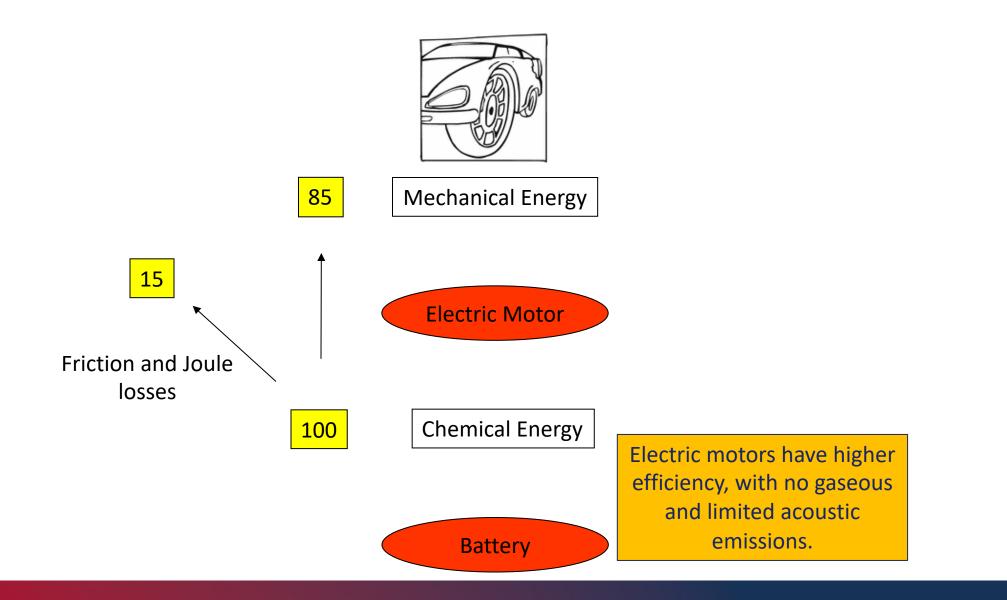
In the spark ignited engines, the need to simultaneously **oxidating** CO and HC and **reducing** NOx requires the recourse to **three-way catalysist**. The engine must work at **stoichiometric** conditions, with a **closed-loop** controlled ignition system.





Electric Motor









Electric mobility: the problems

- There are several **issues to be solved** for the diffusion of electric mobility:
 - Lower range respect to conventional cars, due to lower energy and power density of batteries with respect to liquid fuels.
 - High **cost** of batteries, even if with a **decreasing trend**.
 - The limited diffusion of charging infrastructure, and the relatively long time needed for recharging.
 - Impact of vehicle charging on **electric infrastructure**.
 - High impact on electric consumption of power needed for heating and refrigerating the car.
- Moreover, the **CO₂** impact strongly depends on **electric generation mix**.



Energy density: batteries vs liquid fuels



|--|

	kWh/ton	%	kWh/m3	%
Liquid Fuel	11.667	100,00	15.556	100,00
Lead-Acid	30	0,26	50	0,32
Li-Ion	130	1,11	350	2,25



Considering that only 25% of fuel chemical energy can be converted in mechanical energy:

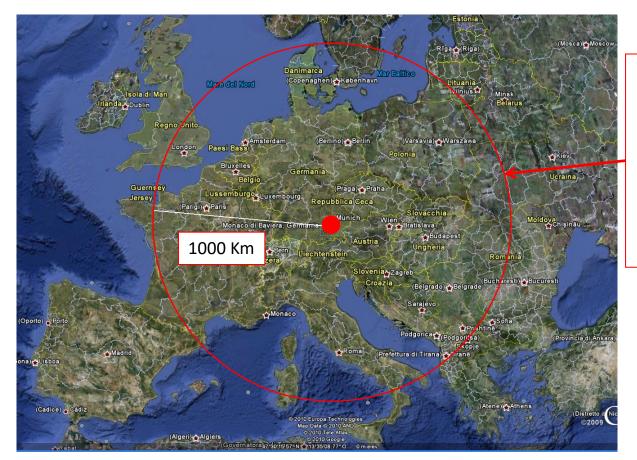
	kWh/ton	%	kWh/m3	%
Liquid Fuel	2.917	100,00	3.889	100,00
Lead-Acid	30	1,03	50	1,29
Li-Ion	130	4,46	350	9,00

Further increases in energy density for Lithium-Ion batteries can be achieved by adopting innovative nano-composite materials (Magasinki et al., 2010).



About the range





Almost 30 different countries and about 100.000 fuel pumps in a radius of 1000 Km (with an average density of about 0,04 pumps per Km²)

Is a 1000 Km range <u>really</u> necessary for a car?

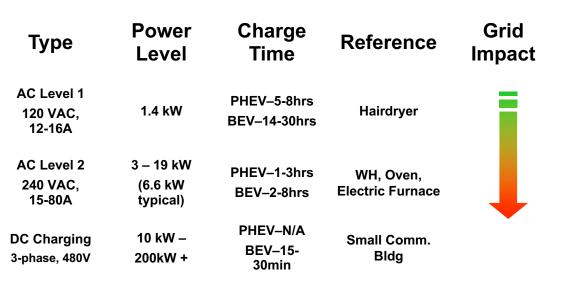


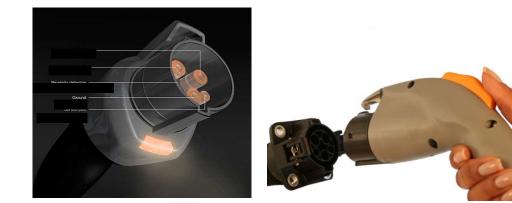
Charging issues



- Vehicles can be charged at multiple power levels:
- SAE J1772 Standard Charge Connector
 - Level 1 120VAC, 1 Phase up to 16A
 - Level 2 240VAC, 1 Phase up to 80A
- DC Charging (Fast Charging) No current standard for charging or connector
 - Will requires different connector (A standard exists in Japan)
 - Current Japanese DC charge rate: Max 500VDC, 200A

Level 1 and Level 2 vehicle charging rates are similar to other loads within the home.





A standard charge connector SAE J1772 was adopted on January 14, 2010 by the SAE Motor Vehicle Council. The companies participating in or supporting the revised 2009 standard include <u>GM</u>, <u>Chrysler</u>, <u>Ford</u>, <u>Toyota</u>, <u>Honda</u>, <u>Nissan</u> and <u>Tesla</u>.







- Compare the energy per unit time (i.e. the recharging power) entering into
 - i) the reservoir of a conventional car and
 - ii) the battery of a EV car.

		modello A COLO	DNNA
		disponibili:	
	2 x 3,7 kW 2 x 3	7,4 kW	
	2 x 11 kW 2 x	22 kW	ë
modello WALLBOX			
Potenze disponibili:		6	
1 x 3,7 kW 1 x 7,4	kW		
1 x 11 kW 1 x 22	kW		







Recharge: ICE vs EV







Power (energy per unit time) in input during «recharge»: **3.7-22 kW**

Fast DC recharge: about 100 kW

MJ/kg	42
Minutes	2
Density kg/dm3	0,75
Liters	33,33
l/s	0,28
kg/s	0,21
MW	8,75



Energy consumption of auxiliary systems in an EV



Energy consumption of auxiliary systems may severely impact battery consumption and range in a EV.

Cooling and **heating** may impact on traction battery energy up to 30-35%.

Heating energy is free in conventional cars, as well as in hybrid cars.

Auxiliary systems	Part of traction battery energy, %
Climate control:	
- cooling;	Up to 30%
- heating.	Up to 35%
Power steering	Up to 5%
Braking system	Up to 5%
Other (lights, media,	Up to 5%
locks etc.)	_

EV Auxiliary Systems Impacts, http://avt.inl.gov/sites/default/files/pdf/fsev/auxiliary.pdf

Evtimov, I., Ivanov, R., & Sapundjiev, M. (2017). Energy consumption of auxiliary systems of electric cars. Paper presented at the *MATEC Web of Conferences, , 133* doi:10.1051/matecconf/201713306002

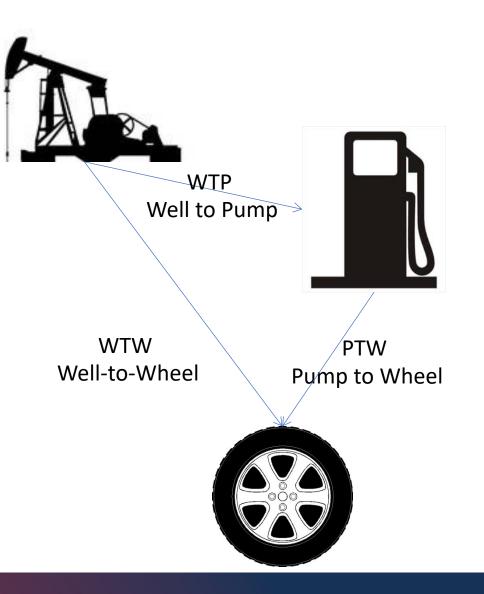
MASTER IN ENTREPRENEURSH Energy conversion schemes



When analyzing energy conversion processes and Green House Gas Emissions for a car fueled with fossil fuels, different schemes can be considered:

- PTW Pump to Wheel
- WTP Well to Pump
- WTW Well-to-Wheel

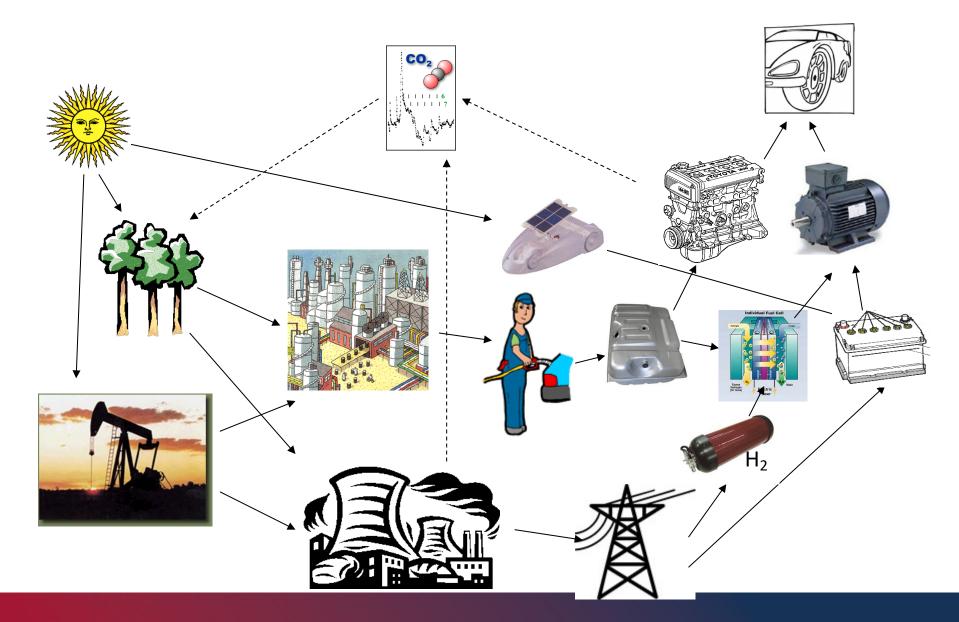
The concept can be generalized to include bio-fuels, electricity, hydrogen, solar and other energy sources.





Well to wheel

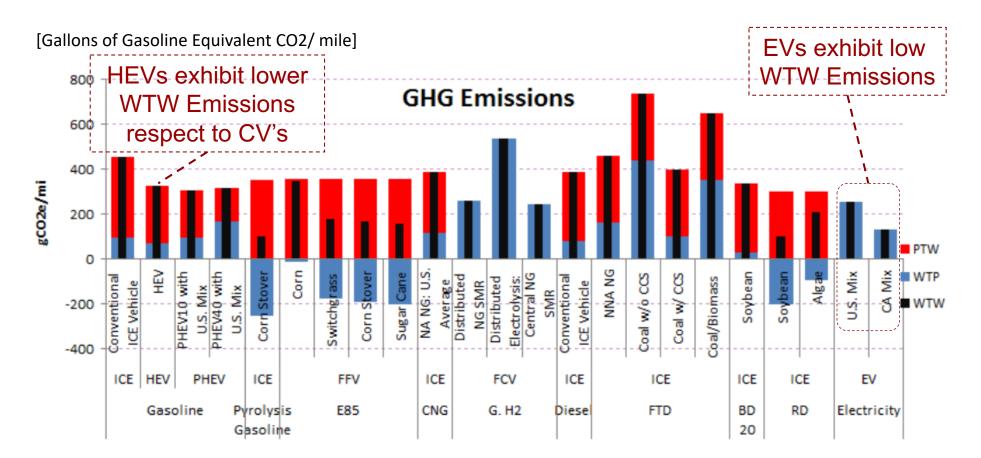






Green House Gas Emissions



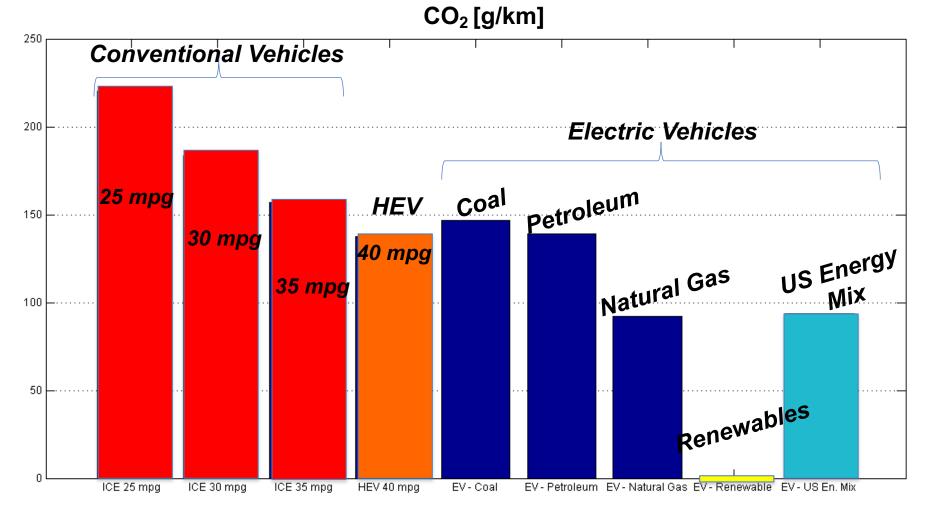


Source: GREET 2012 http://greet.es.anl.gov/ Green House Gas Emissions PTW Pump to Wheel WTP Well to Pump WTW Well-to-Wheel



Energy Source vs. CO2 Emissions





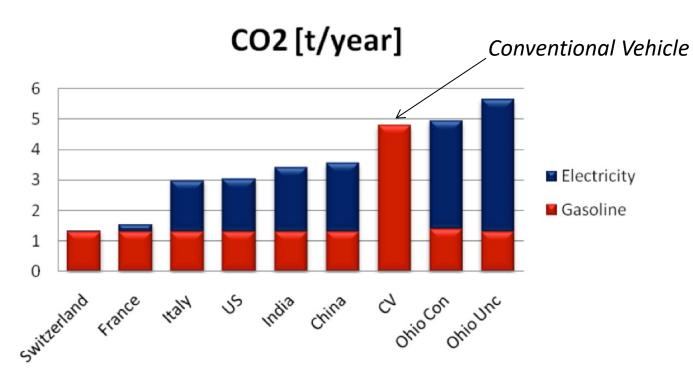
The impact on CO₂ emissions for Electric Vehicles depends strongly on electric power generation!!







CO2 Emissions of Plug-In HEV in different countries

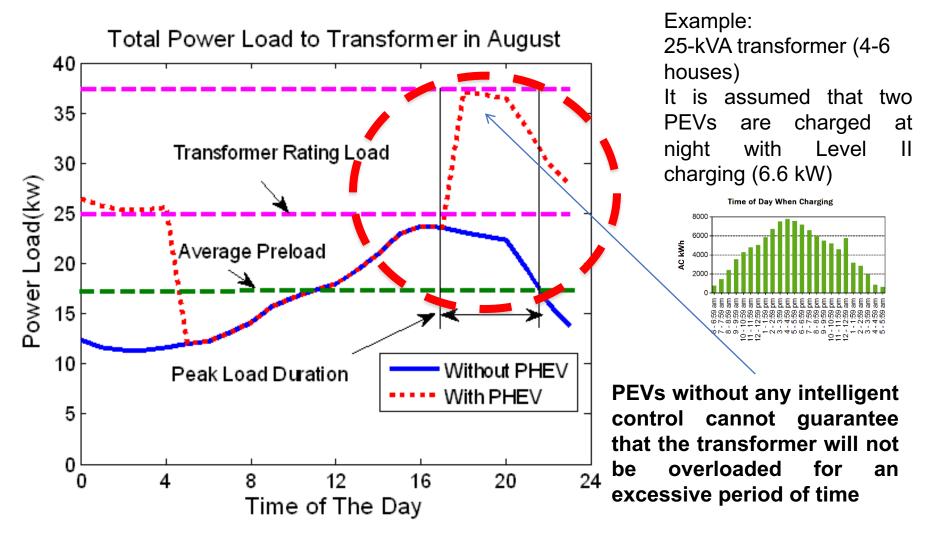


The benefits of PHEV with respect to conventional vehicles strongly depend on the **generation mix** of the given country. In some cases (i.e. Ohio, where coal is mostly used), the emissions of **CO**₂ with PHEV's can be greater than conventional vehicles (and also **NO**_x and **SO**₂ would increase)









Gong Q., Midlam-Mohler S., Marano V, Rizzoni G., "Study of PEV Charging on Residential Distribution Transformer Life", IEEE Transactions on Smart Grid 3: 1. 404-412 March, 2012



Impact of PEV Charging on Power **Distribution Networks**



SAMPLE STUDY

Results for 2-4-6 PEVs connected to the same 25kVA distribution transformer, considering level II charging (6.6 kW) for different charging strategies

	2 PEV	4 PEV	6 PEV
7 PM	14.41	0.0432	0.00012
12 AM	OK	0.5148	0.001
Randomized (30 min)	OK	13	2.27
Randomized (15 min)	OK	20.7	1.36
Average Charging	OK	OK	ОК

Transformer time life (years)

Gong Q., Midlam-Mohler S., Marano V, Rizzoni G., Study of PEV Charging on Residential Distribution Transformer Life", IEEE Transactions on Smart Grid 3: 1. 404-412 March, 2012

- With poorly managed charging, even a small number of vehicles on a single residential transformer lead to dramatic loss of insulation life.
- More sophisticated charging strategies can allow the same transformer to service a large number of vehicles without serious detriment to life.



Sustainable Mobility: Possible Solutions



- Fuel economy improvements in conventional vehicles.
- Alternative fuels: Bio-fuel, Hydrogen, efuels vehicles.
- Fuel-cell vehicles.
- Hybrid Electric Vehicles.
- Plug-in Electric/Hybrid Vehicles.
- Integration with V2V/V2I communication technologies.
- Integration with solar/renewable energy.
- Fleet reconversion.









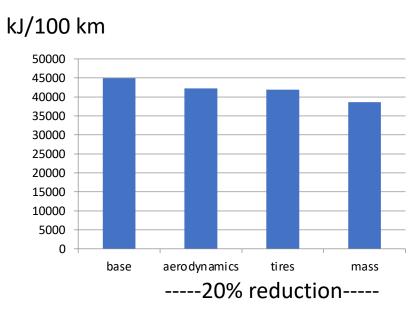
Some recent trends about the research on transportation can be sinthetized by the lines in the **Horizon 2020** Work Programme **«Smart, Green and Integrated Transport**»:

- Mobility for Growth
- Green Vehicles
- Small Business and Fast Track Innovation for Transport



Effects of vehicle variables on energy consumption





 $E \cong 19000 \cdot A_f \cdot c_w + 840 \cdot m \cdot c_r + 11 \cdot m$ [kJ/100km]

Base values for full-size car

$A_f c_w [m^2]$	0,7
C _r	0,012
m [kg]	1500

Mass has highest effects on car energy consumption!!





From passive to active safety







Active safety: avoid the accident.

Passive safety: reduce the effects of accidents.

Mass reduction Energy consumption reduction

IN COLLABORATION WITH MIT SLOAN IN COLLABORATION WITH MIT SLOAN IN COLLABORATION WITH MIT SLOAN



Intelligent Transport Systems (ITS) include telematics and all types of communications in vehicles, between vehicles (e.g. car-to-car), and between vehicles and fixed locations (e.g. car-to-infrastructure).

Nei

ITS are **not restricted to Road Transport** - they also include the use of information and communication technologies (ICT) for rail, water and air transport, including **navigation systems**.



Adoption of **ITS** can be helpful in **reducing the risk of accidents and in reducing vehicle mass**, so allowing further **energy savings**.



Technological solution for green vehicles



The four zero-emissions technologies have advantages and disadvantages.

Variations across categories 🗧 High performance 🗖 Medium-high 📑 Medium-low 📑 Low performance								
Emissions	Bio/synfuel	Hydrogen internal combustion engines (H2-ICE)	Hydrogen (H2) fuel cell	Battery electric				
CO ₂ intensity	CO ₂ intensity depends on source of biomass/carbon	Zero/minimal CO ₂ if using green/blue H2	Zero/minimal CO ₂ if using green/blue H2	CO ₂ intensity depends on grid mix; zero CO ₂ if using renewable power				
Air quality	NOx ¹ and particulate- matter emissions similar to diesel	No significant NOx emissions with SCR ² aftertreatment	Zero emissions	Zero emissions				
Total cost of								
ownership Efficiency (well-to-wheel)	~20%	~30% for renewable H2 production	~35% for renewable H2 production	75–85%+ depending on transmission and charging losses				
Powertrain capital expenditure	Same as today's combustion engines	H2 engine with similar capex as diesel ICE, but H2 tank required	High capex for fuel cells and batteries, but more scalable than BEV ³	High capex if large batteries required (medium for smaller/ lighter segments)				
Constraints (space/payload)	Same size and weight as today's combustion engines	Engine with same size as today, but H2 tank needed	More space needed than combustion engine for fuel cell and H2 tank	Higher weight than combustion engine; payload constraints subject to use case				
Uptime/refueling	<15 minutes, depending on tank size	<15–30 minutes, depending on tank size	<15-30 minutes, depending on tank size	3+ hours, depending on ability for fast charging				
Infrastructure costs	Can use existing infrastructure	H2 distribution and refueling infra- structure required	H2 distribution and refueling infra- structure required	Charging infra- structure and grid upgrades required				

The low-emission propulsion systems currently considered include BEVs or FCEVs, ICEs powered with synthetic fuels, and ICEs powered with hydrogen, also in hybrid powertrains.

¹Nitrogen oxides. ²Selective catalytic reduction. ³Battery electric vehicle.







- Thermal engines convert only a limited fraction of the primary energy into mechanical energy, due to limitations of the second principle of thermodynamics.
- Moreover the combustion produces CO2 and pollutant emissions.
- Since '70s, the recourse to electronic control and to catalysts produced a substantial decrease in pollutant emissions.
- Electric motors have many benefits in terms of energy efficiency, noise and pollution, but car range and power recharge are now critical limiting factors for the diffusion of electric cars.
- The energy and environmental impact of vehicles must be considered in a wider perspective (LCA), not only during their operation on the road.
- Downsizing is an effective way to reduce fuel consumption in ICEs.
- Mass reduction and Intelligent Transport Systems may reduce energy demand in cars.





The 3 R's of Sustainability





Is massive car scrapping a sustainable perspective?







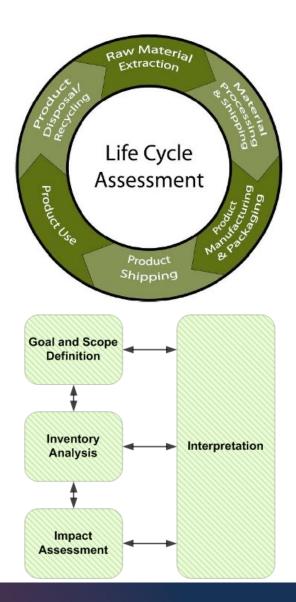
Life Cycle Assessment



Life-cycle assessment (LCA) is a technique to assess environmental impacts associated with <u>all</u> <u>the stages of a product's life</u> from raw material extraction through materials processing, manufacture, distribution, use, repair and maintenance, and disposal or recycling.

The steps of LCA are:

- Compiling an <u>inventory</u> of relevant <u>energy</u> and material inputs and <u>environmental</u> releases;
- Evaluating the **potential impacts** associated with identified inputs and releases;
- Interpreting the results to help <u>make a</u> <u>more informed decision</u>.





The GREET Model



<u>Argonne National Laboratory</u> (U.S. Dept. of Energy) has a recognized leadership in performing LCA analyses.

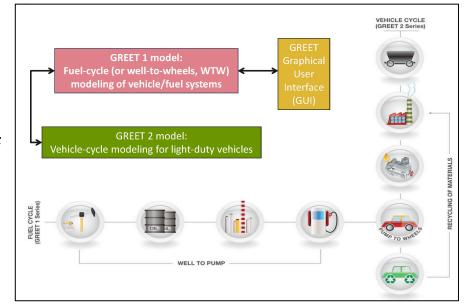
Its work led to the development of a tool, called <u>GREET</u> (Greenhouses gases, Regulated Emissions, and Energy use in Transportation) model, specific for the <u>automotive</u> <u>sector</u>.

This software provides a comprehensive, <u>lifecycle based</u> <u>approach</u> to compare <u>energy use and emissions</u> of conventional (ICEVs) and advanced vehicle technologies (HEVs, PHEVs and EVs).

It takes into account **energy and environmental impact** of vehicles in three phases:

- Fuel cycle (Well-to-Pump)
- Vehicle Cycle (Assembling and junking)
- Vehicle Operation (Use of vehicle)

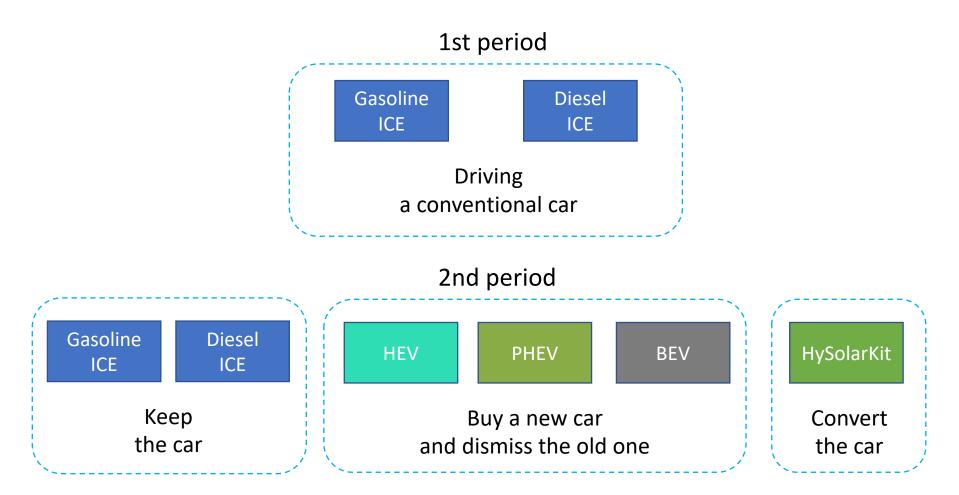










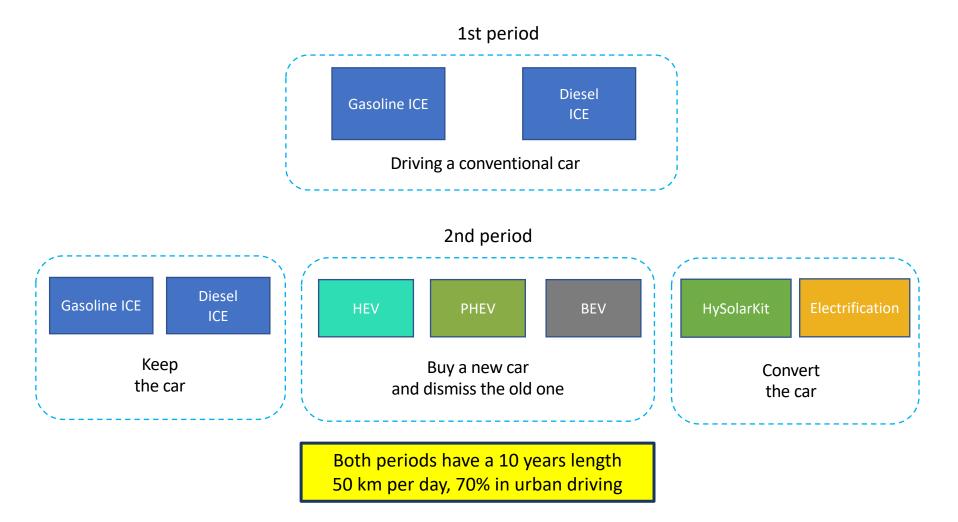


Francesco Antonio Tiano, Gianfranco Rizzo, Giovanni De Feo, Silvio Landolfi **Converting a Conventional Car into a Hybrid Solar Vehicle: a LCA Approach** ECOSM 2018, Changchun, Sept. 19-22, 2018.



The scenarios



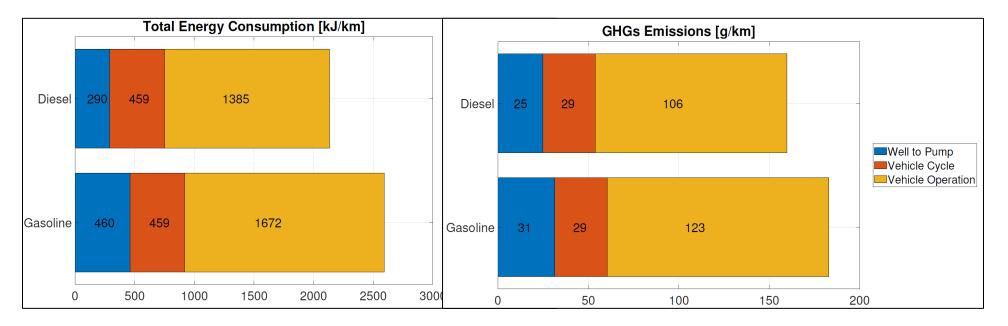


Tiano, F A; Rizzo, G Life Cycle Assessment (LCA) study for different options of sustainable mobility, including vehicle conversion *International Journal of Powertrains*, **2020**, *9*(*1-2*), 122-149



1st period | Results | Energy and GHGs





Diesel fueled vehicle shows **lower energy consumption**, in both **vehicle operation** and in **fuel cycle**.

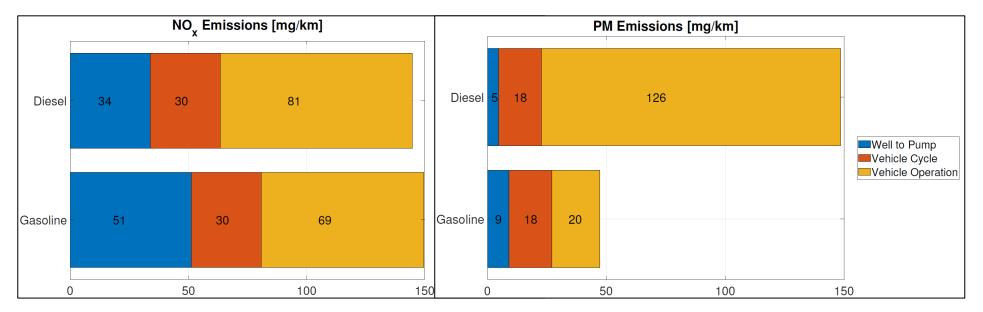
The **same behavior** is found for GHGs emission.

These **results were expected** since diesel engines have **higher efficiency** and diesel fuel is **less refined** than gasoline.



1st period | Results | NOx and PM





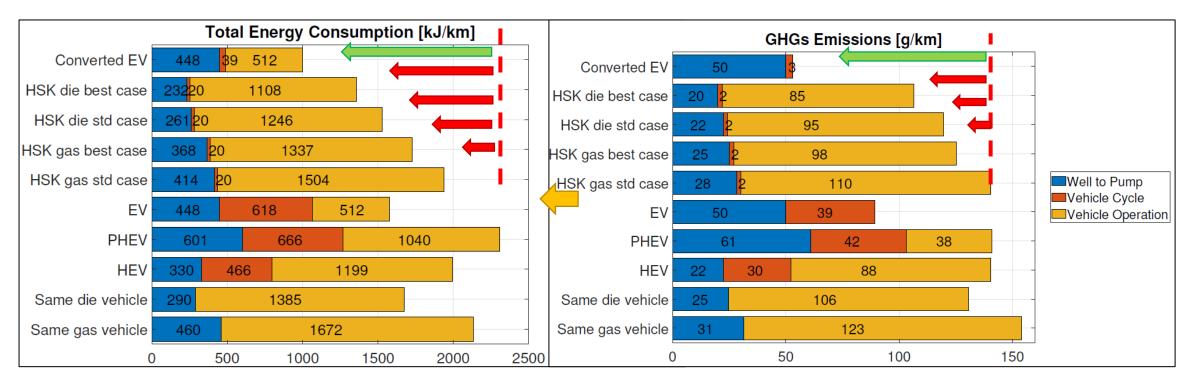
NOx emissions show a <u>not expected results</u>. Diesel fueled vehicle, although have higher emissions in vehicle operation, have an overall <u>slightly lower NOx emissions than Gasoline</u> fueled vehicle.

As expected, **PM emissions** are <u>largely higher</u> for **diesel** fueled vehicle than for **gasoline** fueled vehicle.



2nd period | Results | Energy and GHGs





<u>Converted vehicles</u> have <u>better results</u> than new PHEVs both in terms of Total Energy and GHGs Emissions. <u>PHEVs have the greatest total energy consumptions</u>.

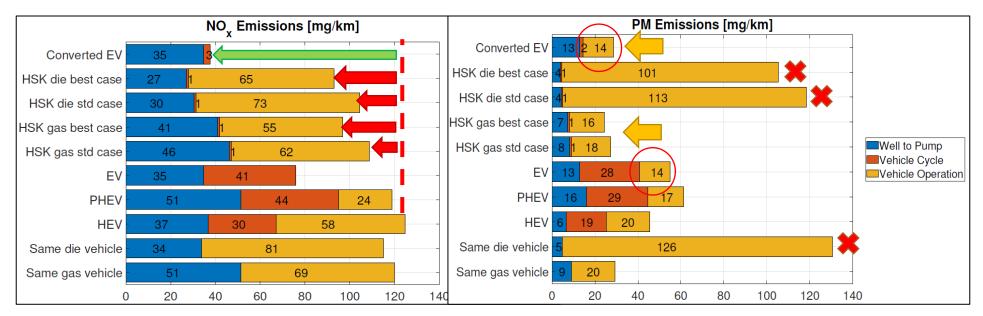
Emissions of PHEVs and EVs strongly depends on Fuel Mix Generation of electricity.

Conversion of diesel vehicles exhibits the best results with GHGs (EVs excluded)



2nd period | Results | NOx and PM





Converted vehicles have **lower NOx emissions** than both PHEVs and HEVs.

<u>Converted gasoline HEVs and converted EVs</u> have the best results in NOx and PM emissions. These emissions depends on <u>Fuel Mix Generation of electricity</u>.

PM emissions of EVs during the vehicle operation are associated to **<u>brakes</u>** and **<u>tyres</u>**.

Diesel vehicles show the worse result in terms of PM emissions due to intrinsic combustion processes.



Summary of the results



	Energy Consumption (kJ/kg)				Percent			
	Fuel	Vehicle	Operation	Total	Fuel	Vehicle	Operation	Total
Diesel	290	459	1385	2134	13.6%	21.5%	64.9%	100%
Gasoline	460	459	1672	2591	17.8%	17.7%	64.5%	100%
PHEV	601	666	1040	2307	26.1%	28.9%	45.1%	100%
HEV	330	466	1199	1995	16.5%	23.4%	60.1%	100%
EV	448	618	512	1578	28.4%	39.2%	32.4%	100%
Diesel+HySolarKit	232	20	1108	1360	17.1%	1.5%	81.5%	100%
Gasoline+HySolarKit	369	20	1337	1726	21.4%	1.2%	77.5%	100%
Converted EV	448	39	512	999	44.8%	3.9%	51.3%	100%
Mean Value	397	343	1096	1836	23.2%	17.1%	59.7%	100%
		GHG emiss	ions (g/km)	Percent			
	Fuel			Fuel	Vehicle	cle Operation Total		
Diesel	25	29	106	160	15.6%	18.1%	66.3%	100%
Gasoline	31	29	123	183	16.9%	15.8%	67.2%	100%
PHEV	61	42	38	141	43.3%	29.8%	27.0%	100%
HEV	22	30	88	140	15.7%	21.4%	62.9%	100%
EV	50	39	0	89	56.2%	43.8%	0.0%	100%
Diesel+HySolarKit	20	2	85	107	18.7%	1.9%	79.4%	100%
Gasoline+HySolarKit	25	2	98	125	20.0%	1.6%	78.4%	100%
Converted EV	50	3	0	53	94.3%	5.7%	0.0%	100%
Mean Value	36	22	67	125	35.1%	17.3%	47.6%	100%

- <u>Vehicle operation</u> has a major role (59/53 % for energy consumption and GHG).
- <u>Fuel cycle</u> accounts in average for 22/27%, while <u>Vehicle cycle</u> for 19%.
- There are significant <u>differences</u> in relative weights between different options.
- <u>Vehicle conversion</u> is a good option both in terms of energy consumption and GHG emissions.



Test – Team working



Estimate the **yearly energy** required to power the **actual Italian fleet** of cars in case of **total replacement** with **electric cars**.

Use the **web** to find for the required information.

Present your **results** and **assumptions** in one or more slides or in an Excel sheet.

Choose a **name** and a **logo** for your team!













Hybrid vehicles are characterized by two or more prime movers and power sources.

Usually, the term "hybrid vehicle" is used for a vehicle combining an **engine** and an **electric motor** (**Hybrid Electric Vehicle**, HEV).

Other "hybrid" configurations have been also proposed (mechanical, pneumatic, hydraulic, solar, fuel cell).



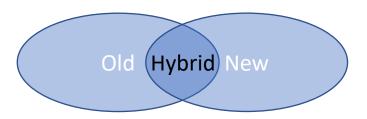
Hybrid technologies



Hybrid propulsion occurred often in the past, when a **gradual transition** to a new technology was needed.

For almost a century, **ships** with **sailing** and **steam propulsions** coexisted. When reliability and mileage of steam engines improved, sailing was abandoned.

Also, first **motocycles** maintained the **pedals**, for assistance in climbing. When power increased and an efficient gear was adopted, pedals disappeared.









Toyota Prius



- The Toyota Prius, first went on sale in Japan in 1997, has been the first mass-produced hybrid vehicle. It was introduced worldwide in 2000.
- The Prius is sold in almost 80 countries and regions, with its largest markets being those of Japan and the United States.
- Global cumulative Prius sales reached the milestone 1 million vehicle mark in May 2008, 2 million in September 2010, and passed the 3 million mark in June 2013.





More recent HEV and PHEV





Toyota Yaris



Hyundai loniq





BMW 225xe









Range Rover Sport PHEV P400e

https://buglionedomenico.wordpress.com/2018/07/02/auto-ibride-2018-i-modelli-in-commercio-in-italia-prezzi-e-autonomia/

MASTER IN ENTREPRENEURSHIP IN COLLABORATION WITH MIT SLOAN MORE RECENT HEV and PHEV





Toyota Auris Hybrid



Toyota C-HR Hybrid







Suzuki Baleno Hybrid



Hybrid vehicles sales



Country	Number of hybrids sold or registered by year									
	2015	2014	2013	2012	2011	2010	2009	2008 ^[137]	2007 ^[138]	
 Japan 	633,200 ^{(1)[130]}	Over 1 million ^[112]	679,100 ^{(1)[139]}	678,000 ^{(1)[140]}	316,300 ^{(1)[140]}	392,200 ^{(1)[140]}	334,000 ^[141]	94,259	69,015	
US	384,404 ^[142]	452,152 ^[16]	495,771 ^[16]	434,498 ^[14]	268,752 ^[143]	274,210 ^[144]	290,271 ^[144]	312,386 ^[144]	352,274[144]	
France ⁽²⁾	56,030 ^[145]	41,208 ^[145]	46,785 ^[146]	27,730 ^[147]	13,340 ^[148]	9,443 ^[149]	9,399 ^[150]	9,137 ^[150]	7,268 ^[151]	
S UK	44,580 ^[152]	37,215 ^[153]	29,129 ^[153]	24,900 ^[154]	23,391 ^[155]	22,127 ^[156]	14,645 ^[157]	15,385 ^[157]	15,971 ^[157]	
Italy	25,240 ^[145]	21,154 ^[145]	14,695 ^[158]	5,885 ^[159]	5,244 ^[160]					
Germany	22,529 ^[161]	22,908 ^[162]	24,963 ^[163]	21,438 ^[164]	12,622 ^[165]	10,661 ^[166]	8,374 ^[166]	6,464 ^[166]	7,591 ^[166]	
s Spain	18,406 ^[145]	12,083 ^[145]	10,294 ^[167]	10,030 ^[168]	10,350 ^[169]					
Netherlands	13,752 ^[170]	10,341 ^[171]	18,356 ^[172]	19,519 ^{[173][174]}	14,874 ^[160]	16,111 ^[175]	16,122 ^[176]	11,837 ^[176]	3,013 ^[176]	
• Canada	Not available		~15,000 ^[177]	~25,000 ^[178]	Not available		16,167 ^[179]	19,963 ^[180]	14,828	
World	Over 1.2 million	Over 1.6 million	Over 1.3 million	Over 1.2 million	-	-	740,000 ^[181]	511,758	500,405	

Hybrid (HEV and PHEV) sales in EU and EFTA had the highest rate of increase in last years.

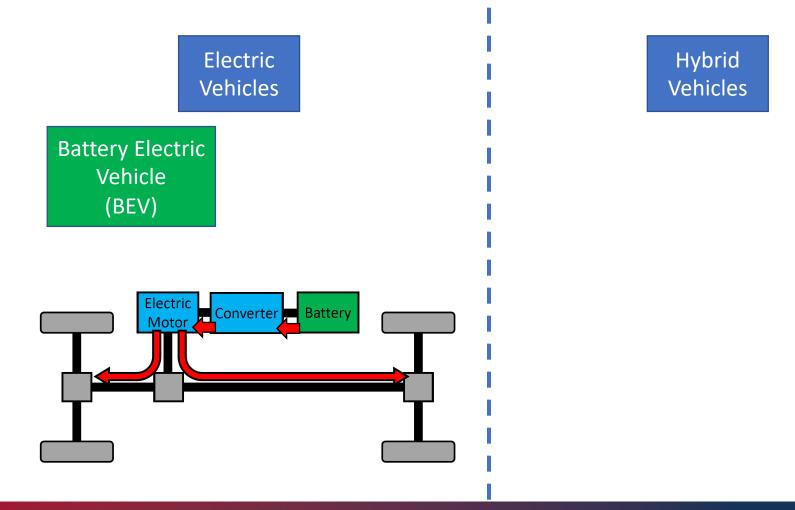
Fuel Type	2018 (Q1)	2017 (Q1)	% Change	% Market Share
Total Market	4,282,134	4,256,637	0.6	100
Petrol	2,355,611	2,060,349	14.3	55
Diesel	1,603,337	1,934,374	-17.1	37.4
Alternatively Powered:	295,524	236,098	25.2	7
- ECV:	88,329	62,695	40.9	2
– – BEV	43,585	32,297	35	1
– – PHEV	44,744	30,398	47.2	1

Source: ACEA



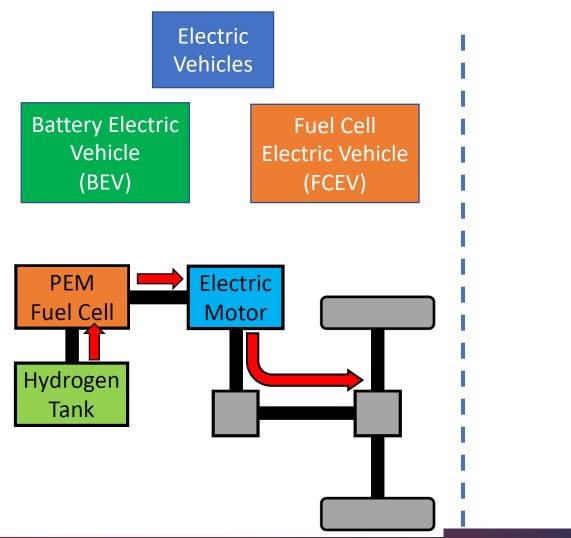


Two categories of sustainable mobility can be identified:





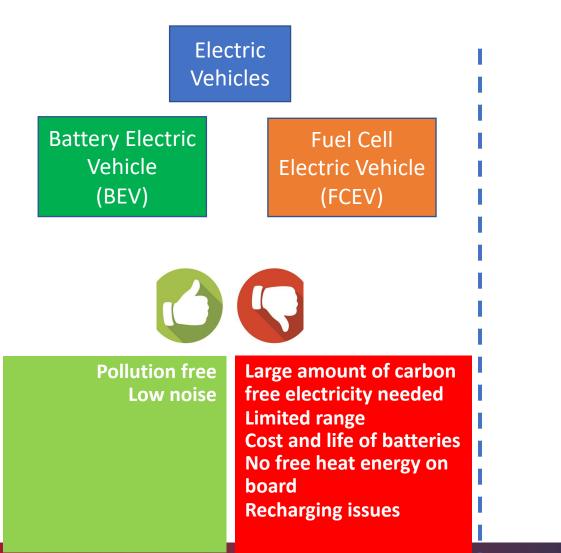




Hybrid Vehicles



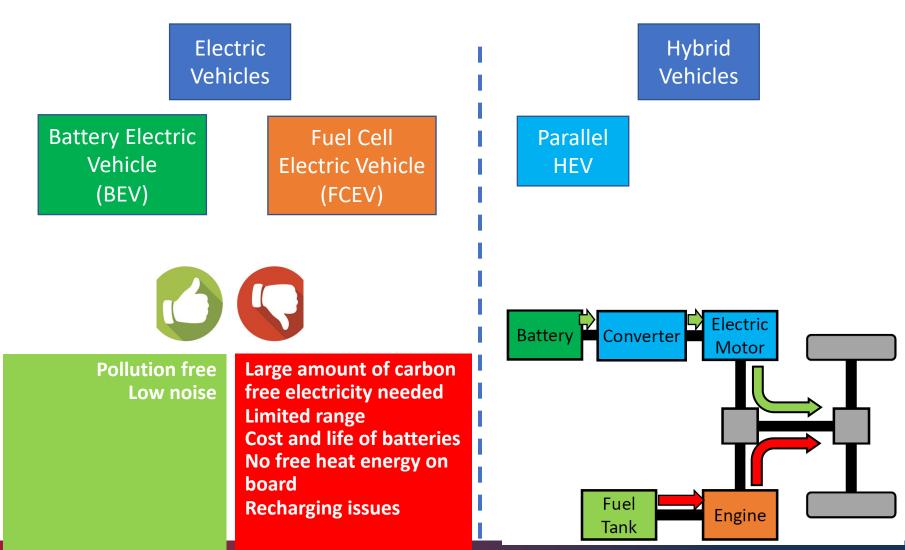




Hybrid Vehicles

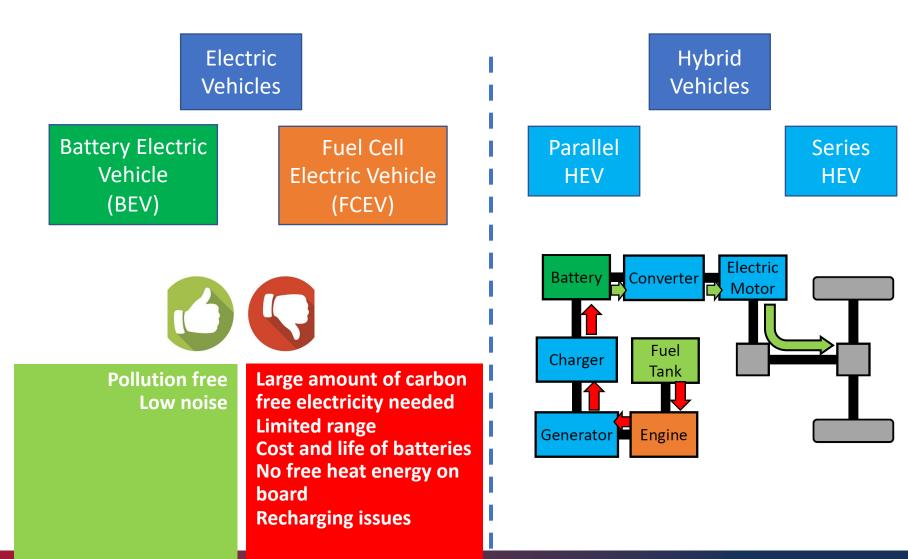






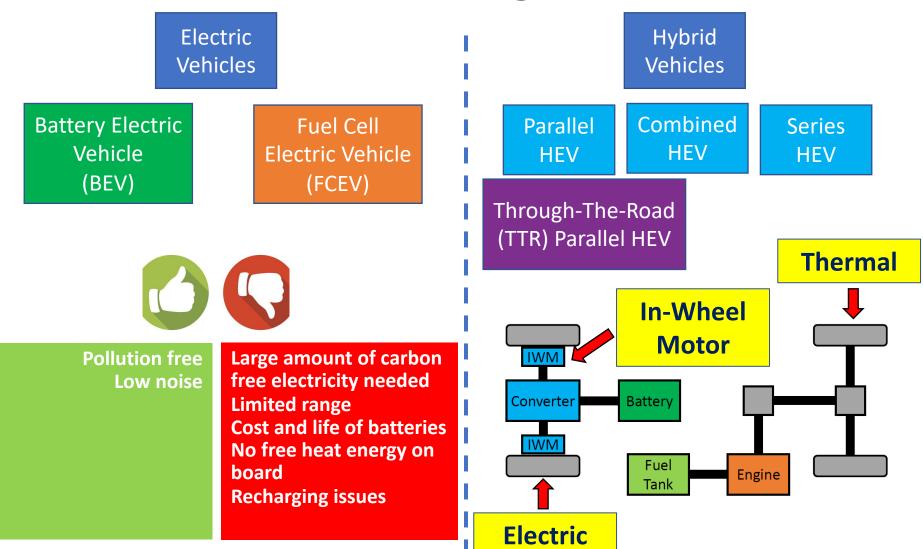






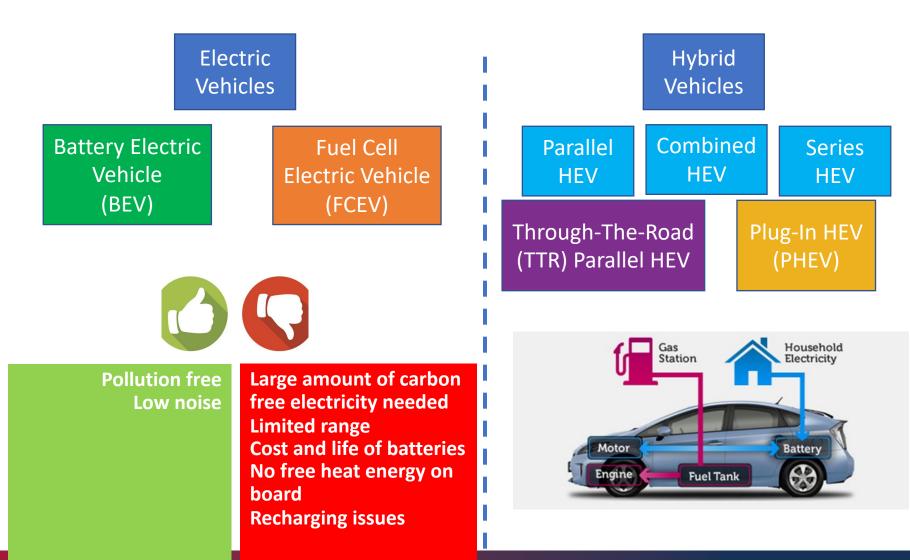






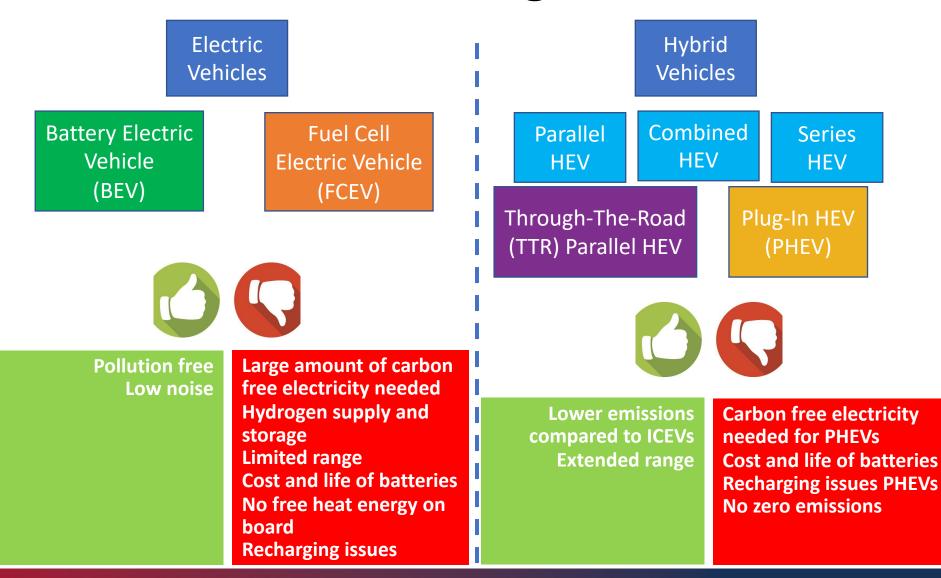








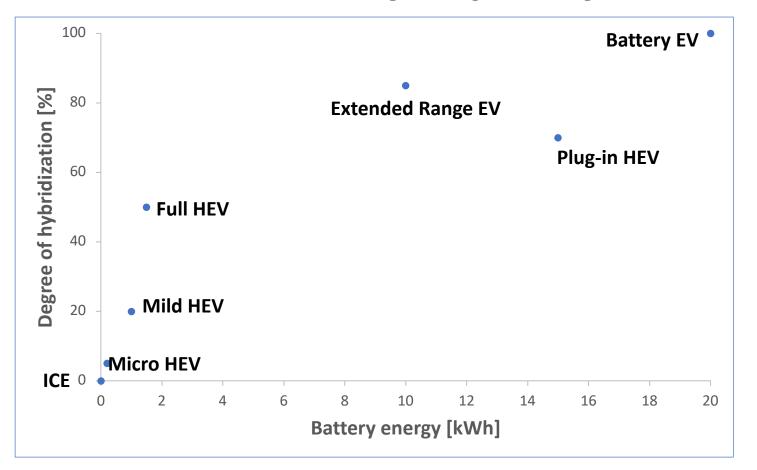






Degree of hybridization vs battery capacity





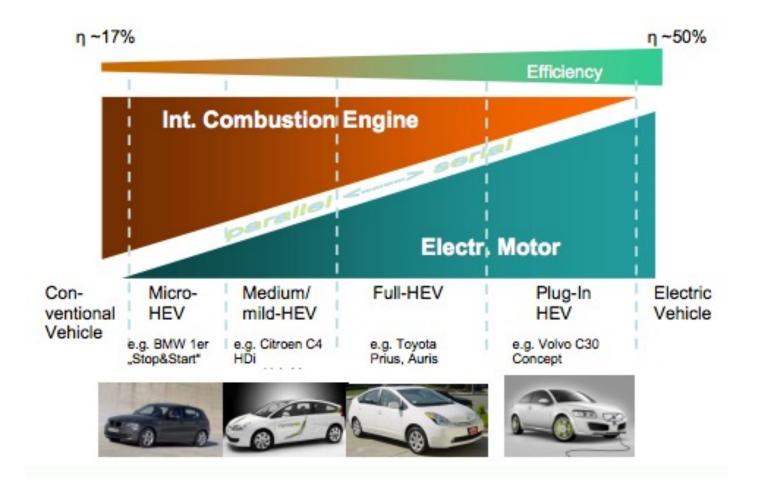
Functional classification of EV/HEVs in terms of degree of hybridization and battery capacity (typical values).

Source: L.Guzzella and A.Sciarretta (2012), Vehicle Propulsion Systems, Introduction to Modeling and Optimization, Springer



Degree of Hybridization





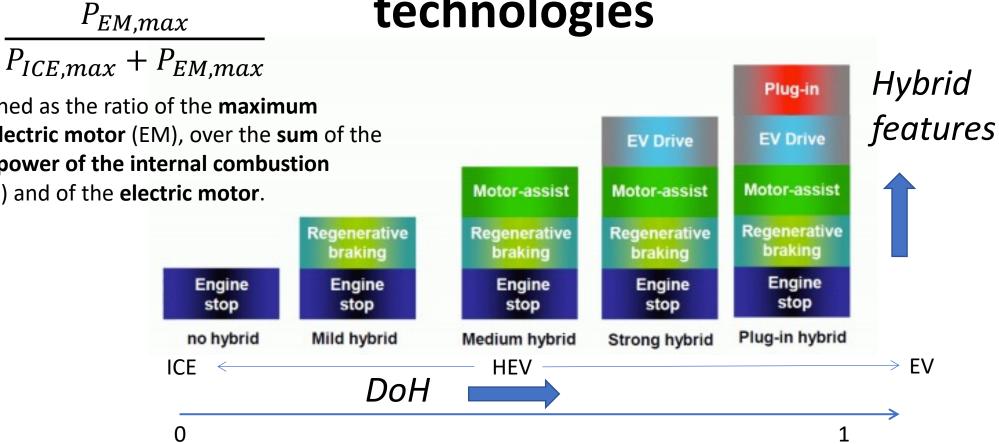


DoH =

Hybrid and electric technologies



DoH is defined as the ratio of the **maximum power of electric motor** (EM), over the **sum** of the maximum power of the internal combustion engine (ICE) and of the electric motor.



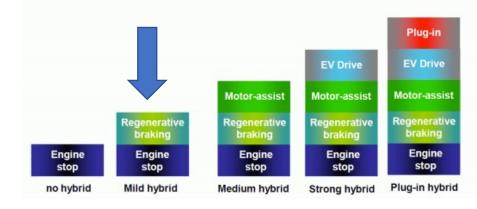
Different levels of hybridization and of hybrid features can be achieved, at increasing values of the Degree of Hybridization DoH.



Micro Hybrids



- Micro hybrids (also called No-Hybrid) are essentially conventional vehicles with oversized starter motors (about 3% the power of the engine), allowing the engine to be turned off whenever the car is coasting, braking, or stopped, yet restart quickly and cleanly.
- During restart, the larger motor is used to spin up the engine to operating rpm speeds before injecting any fuel.
- Start& Stop allows to reduce fuel consumption of 4-5% on NEDC
 Cycle, and up to 8-10% in heavy traffic conditions.
- Usually, the lead-gel batteries at 12 V are used, as in conventional vehicles.
- This technology can be applied with limited modifications in short time on existing vehicles.



MASTER IN ENTREPRENEURSHIF Mild Hybrids with BSG or ISG



Mild hybrids are essentially conventional vehicles with oversized starter motors, allowing the engine to be turned off whenever the car is coasting, braking, or stopped, yet restart quickly and cleanly.

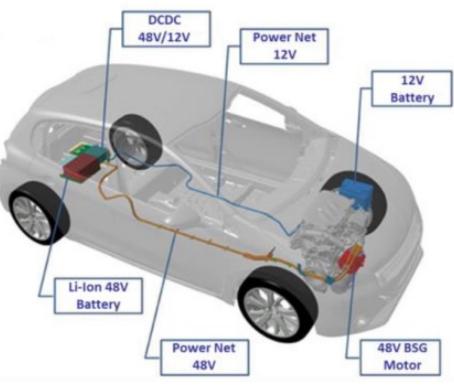
NEi

The Mild Hybrid works at higher voltage (i.e. 48 V) with a **Belt Starter Generator** (BSG) or an **Integrated Starter Generator**, up to about 15 kW.

They use two **different voltage levels** (12V and 48V), a Lithium-Ion battery of about 300-500 Wh, and a DC/DC converter for recharging the 12V battery.

A limited support to the engine during **acceleration** and some recuperation of **braking energy** can be achieved with such systems.

But there is **no EV mode at all**. Therefore, many people do not consider these to be hybrids, since there is no electric motor to drive the vehicle, and these vehicles do not achieve the fuel economy of real hybrid models.





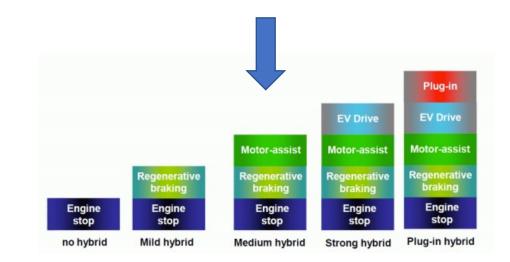
Belt Starter Generator



Medium Hybrid



- Motor assist hybrids use the engine for primary power, with a torque-boosting electric motor connected in parallel to a largely conventional powertrain.
- EV mode is only possible for a very limited period of time, and this is not a standard mode. Compared to full hybrids, the amount of electrical power needed is smaller, thus the size of the battery system can be reduced.
- The electric motor, mounted between the engine and transmission, is essentially a **very large starter motor**, which operates not only when the engine needs to be turned over, but also when the driver "steps on the gas" and **requires extra power**.
- The electric motor works as a generator during **regenerative braking**.

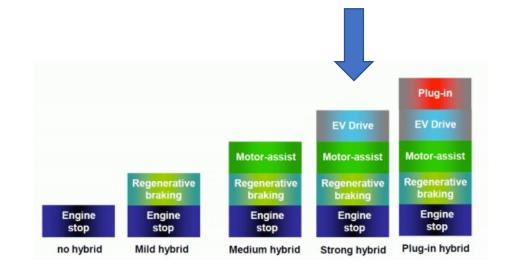








- A full hybrid can run on just the engine (thermal mode), just the batteries (electrical mode), or a combination of both (hybrid mode).
- A large, **high-capacity battery pack** is needed for battery-only operation

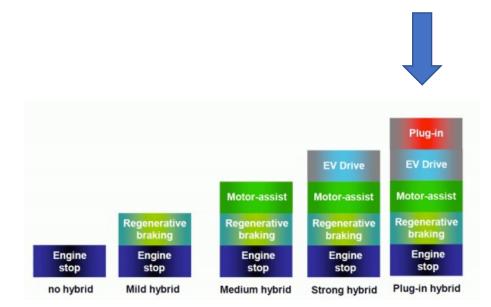




Plug-In HEV



- A plug-in hybrid electric vehicle (PHEV) is a full hybrid, able to run in electric-only mode, with larger batteries and the ability to recharge from the electric power grid.
- Their main benefit is that they can be gasolineindependent for daily commuting, but also have the extended range of a hybrid for long trips.
- Fuel efficiency is calculated based on actual fuel consumed by the ICE and its gasoline equivalent of the kWh of energy delivered by the utility during recharge.
- The "well-to-wheel" efficiency and emissions of PHEVs compared to gasoline hybrids depends on the energy sources used for the grid utility (coal, oil, natural gas, hydroelectric power, solar power, wind power, nuclear power).



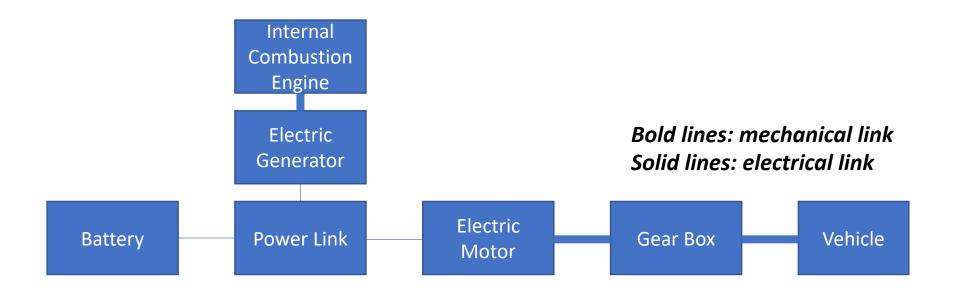


Series hybrid configuration



In a Series HEV, the vehicle is driven only by the electric motor.

The Internal Combustion Engine is used as an **Auxiliary Power Unit** (APU), powering an electric generator to **recharge the battery** and to **extend the range** of the vehicle.





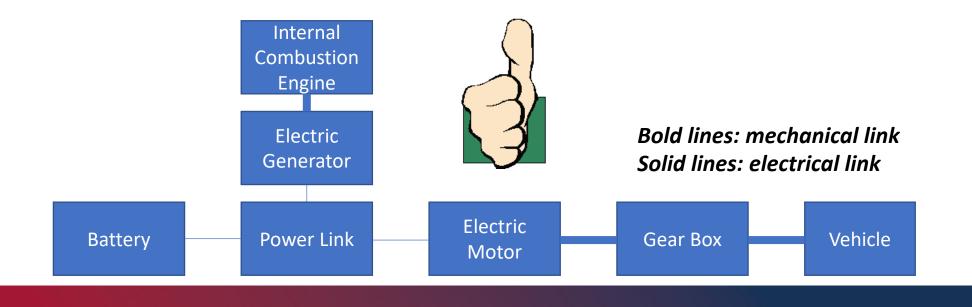
Series HEV - Advantages



The engine operation is not related to the power requirements of the vehicle, thus the engine can be operated at a point with **optimal efficiency and emissions**.

The engine is mechanically decoupled from the drive axle:

- the transmission **does not require a clutch**;
- lay-out can be optimized;
- good **insulation** for **vibrations and noise** can be achieved, since the engine is not mechanically connected to the transmission.





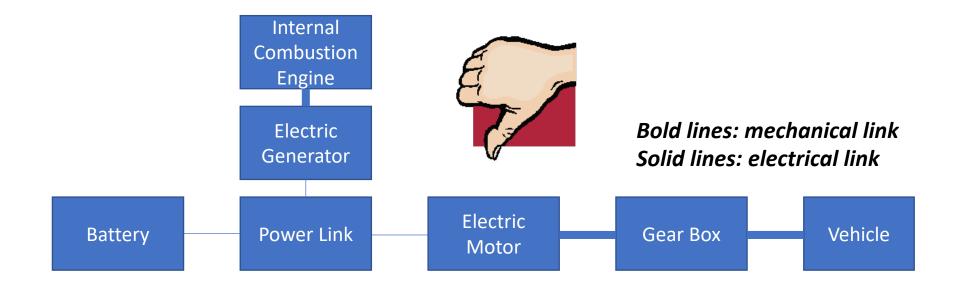
Series HEV -Disadvantages



3 machines are needed: one engine, one electric generator, and one electric traction motor. This cause **additional weight and cost**.

At least the traction motor has to be sized for the **maximum power requirements** of the vehicle.

The overall tank-to-wheel efficiency is reduced due to **multiple energy conversions**.





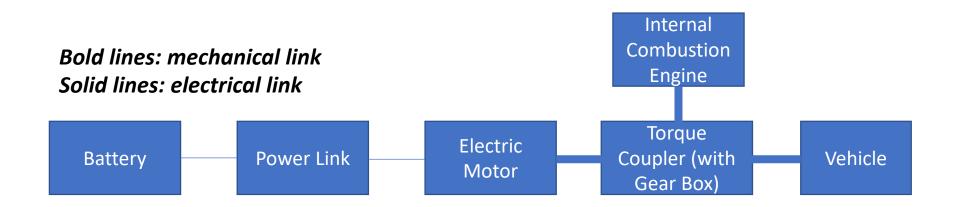
MASTER IN ENTREPRENEURSHIP INNOVATION MANAGEMENT IN COLLABORATION WITH MIT SLOAN



In **parallel HEVs** both the engine and the electric motor can **supply the traction power**, either alone or in combination.

The **electric motor** can **assist the engine**:

- during accelerations and at high power demand
- at idle (engine can be turned off)
- engine can operate at **higher efficiency** with respect to the conventional vehicle, since driver demand can be satisfied by the motor also.





Parallel hybrid - Advantages Dearther

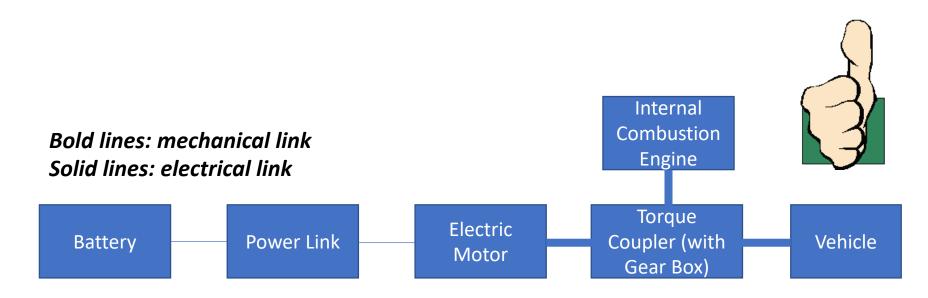


Power could be **optimally distributed** between electrical and thermal mover.

Both machines can be sized for a fraction of the vehicle maximum power \rightarrow Less weight and cost with respect to series hybrid.

Engine can be **downsized**, with increased efficiency.

The overall **tank-to-wheel efficiency** is higher with respect to series hybrid, due to fewer **energy** conversions.





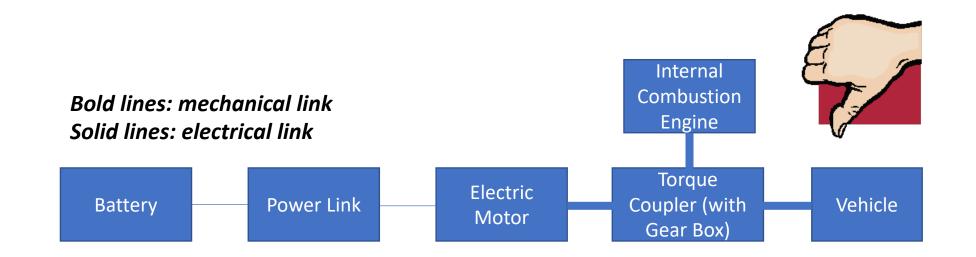
Parallel hybrid -Disadvantages



A **clutch** is needed, since the engine is mechanically linked to the drive train.

The engine generator is smaller, and this may **limit the recoverable braking energy**.

Engine operation can be somewhat optimized thanks to motor assistance, but not so effectively as in a series hybrid.

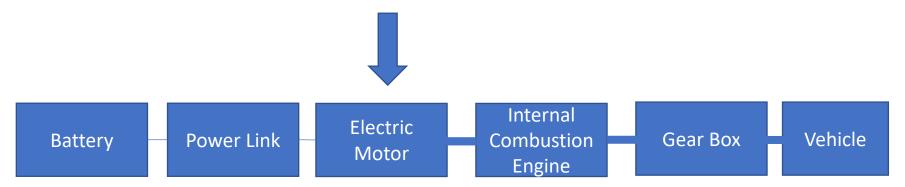




Mild parallel hybrid configuration



- In **mild hybrids**, the electric machine is typically **belt-driven** and mounted on the front of the engine.
- Its speed is always **rigidly linked** to that of the engine.

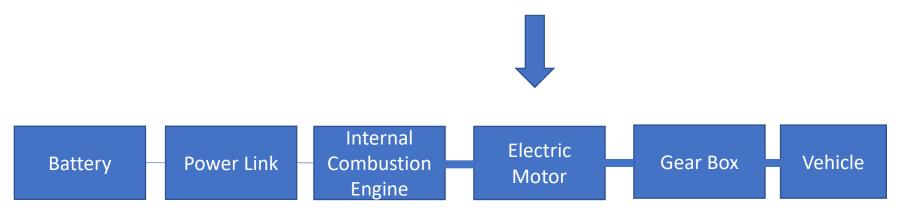




Mild parallel hybrid configuration



- In *pre-transmission* parallel hybrids, the electric machine is mounted between the engine and the gearbox.
- The two speed levels are linked, thus this configuration is also called singleshaft.

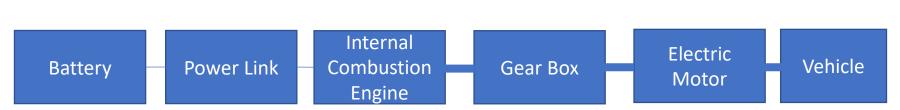




Medium parallel hybrid configuration



 In *post-transmission* or *double-shaft* parallel hybrids, the electric machine is mounted *downstream of the gearbox*, thus the two speed levels are decoupled.

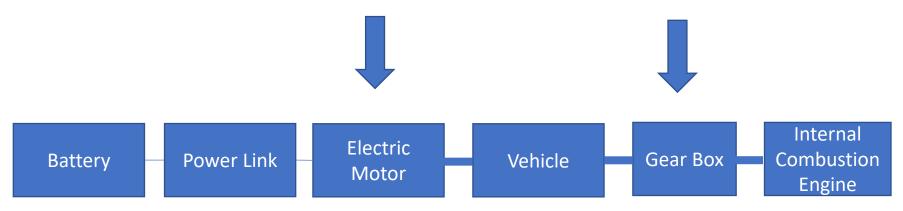




Medium parallel hybrid configuration



- In *through-the-road* parallel hybrids (TTR HEV), the engine and the electric machine are mounted on two separate axles, thus the mechanical link between them is only **through the road**.
- Electric motor speed is rigidly connected to vehicle speed.
- Note: the addition of **wheel-motors** to front drive conventional vehicles allows to convert them in TTR HEV.





Combined hybrid configuration



The **combined hybrid configuration** is mostly a **parallel hybrid**, but it contains **some features of a series hybrid**.

Both mechanical and electric links are present, with **two distinct electric machines**.

As in a parallel hybrid configuration, one is used as a **prime mover** or for **regenerative braking**.

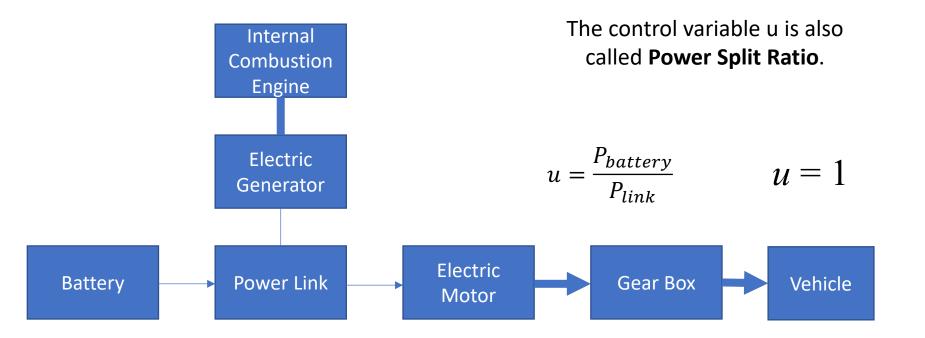
The other machine acts like a **generator in a series hybrid**. It is used to charge the battery via the engine or for the stop-and-start operation.



Series hybrid vehicles 1



Pure electric driving, in zero-emission ZEV mode, can be adopted when the battery is sufficiently charged, usually in urban driving.



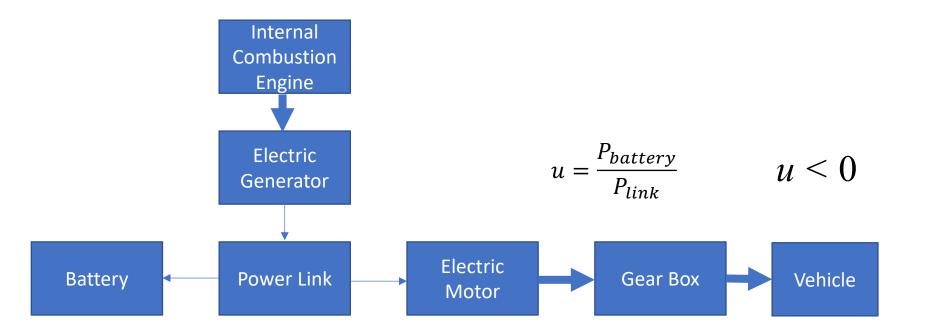


Series hybrid vehicles 2



When the battery charge is too low, the engine is turned on and typically set near its **maximum efficiency operating point**.

The power resulting from the difference between the engine power and the power at the link **recharges the battery** via the generator.

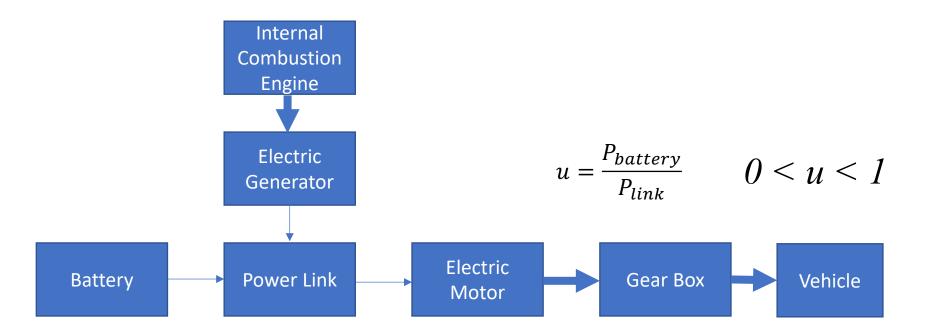








Hybrid driving: when the fuel-optimal engine power is below the power at the link, the battery could provide the **missing power**.

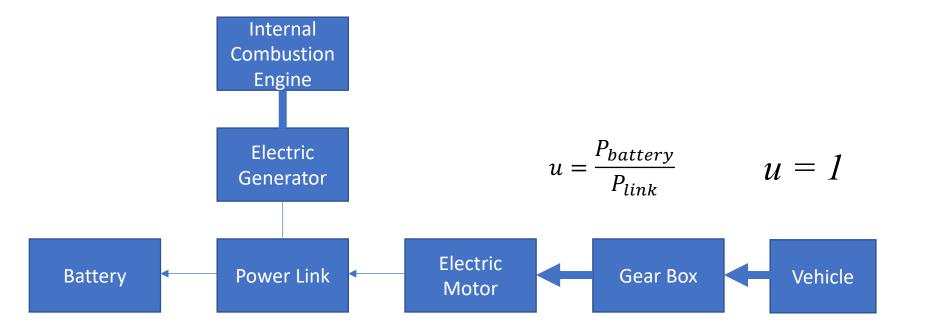








During decelerations or braking, part of the kinetic energy is recuperated in the battery by using the electric machine as **generator**.

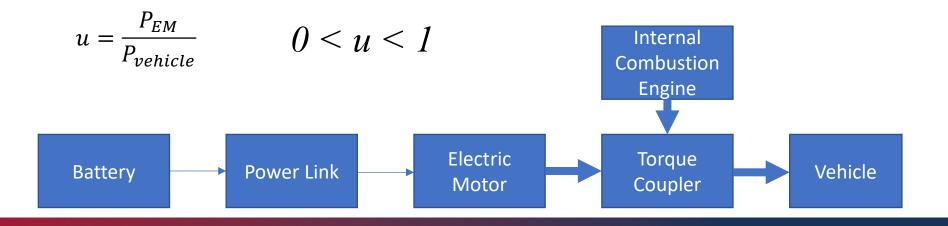






Modes of operation of parallel hybrid vehicles: Power Assist

During **startup** or **acceleration**, the engine provides only a fraction of the total power at the coupler, while the remaining part is delivered by the motor. This operating mode is often referred to as **power assist** mode.

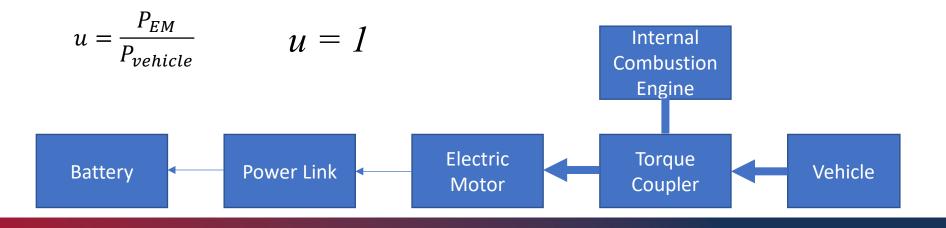






Modes of operation of parallel hybrid vehicles: Regenerative Braking

During **braking** or **deceleration**, the motor acts as generator and recuperates energy into the battery.



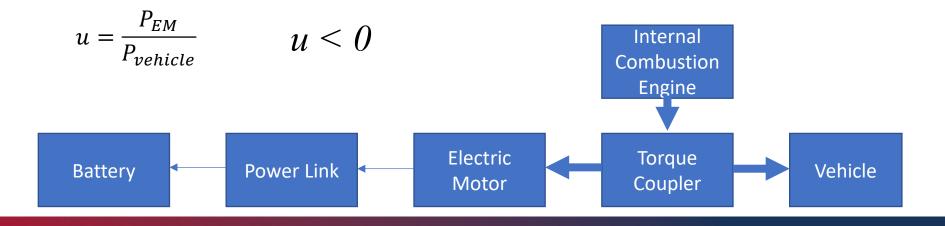




Modes of operation of parallel hybrid vehicles: Battery Recharging

It is also possible to shift the **operating point of the engine** towards **higher efficiency**.

At light load, the engine would then provide more power than strictly demanded and the extra power would be used to charge the battery via the electric machine.



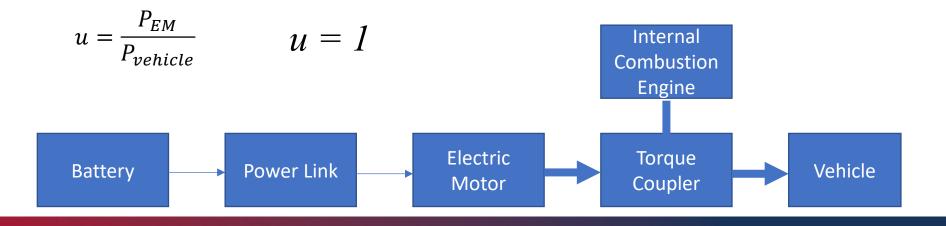




Modes of operation of parallel hybrid vehicles: Pure Electric

In pure electric mode, engine is off and **only the electric motor drivers the vehicle**.

In such way, **Zero Emission Vehicle** mode can be achieved. This is particularly useful in urban driving, when battery is enough charged.



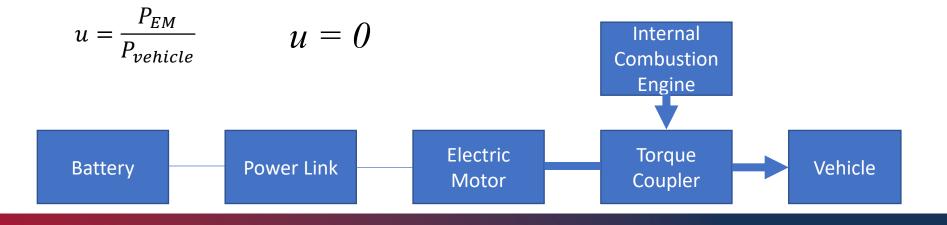




Modes of operation of parallel hybrid vehicles: Thermal Mode

In **thermal mode**, the vehicle is powered **only by the engine**, as in a conventional vehicle.

This mode may be used in extra-urban driving. Electric assistance would be necessary to reach the maximum vehicle power.









Hybrid Electric Vehicles were invented in late 1800's, but started their commercial diffusion after 1997 with Toyota Prius. Their sales are rapidly increasing in last years.

Parallel HEV is the most diffused architecture.

Series HEV's allow to optimize the engine operation, but suffer for multiple energy conversion.

Plug-in HEV (PHEV) combine the benefits of BEV and of HEV, but with higher costs and mass, increasing vehicle energy demand.

The performance and the benefits of HEV's are highly dependent on **Degree of Hybridization**. DoH is a **design variable**, fixed for every hybrid vehicle.

The operation of a HEV during different driving conditions can be analyzed considering their **Power Split** ratio, an **operating variable** changing during vehicle operation.





Electric Components

- Motor/Generator
- Inverter
- Battery



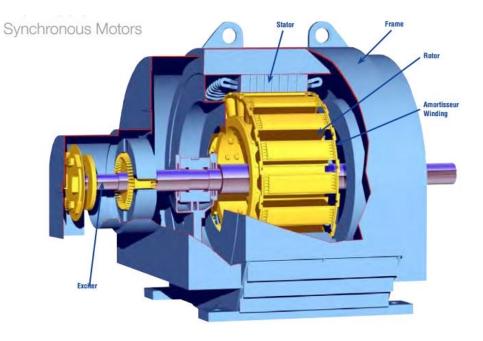
Synchronous electric motor



A synchronous electric motor is

an <u>AC motor</u> in which, at <u>steady</u> <u>state</u>, the rotation of the shaft is synchronized with the <u>frequency of</u> <u>the supply current</u>; the rotation period is exactly equal to an integral number of <u>AC</u> cycles.

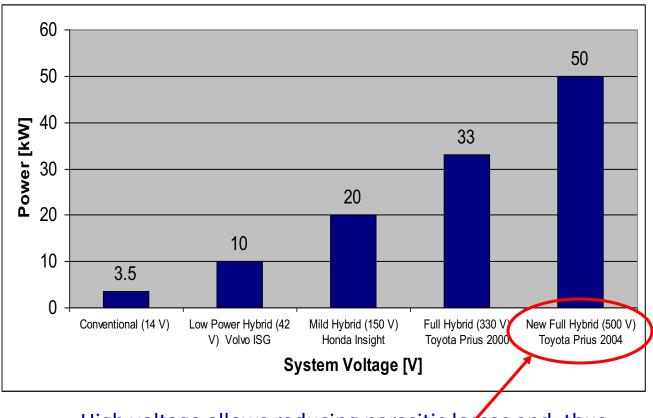
Synchronous motors contain multiphase AC <u>electromagnets</u> on the <u>stator</u> of the motor that create a <u>magnetic field</u> which rotates in time with the oscillations of the line current.





Electric drives/motors for HEV applications – Trends





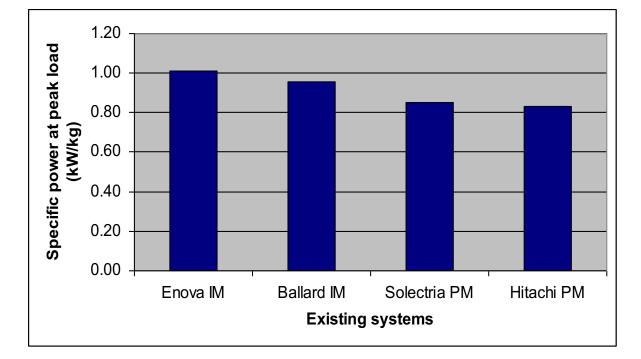
High voltage allows reducing parasitic losses and, thus, increasing power density



Actual features of electric machines for HEV applications



Traction motor	Status
Specific power at peak load (kW/kg)	1.0
Volumetric power density (kW/L)	3.5
Cost per kilowatt at peak load (US \$/kW)	16
Efficiency	93%





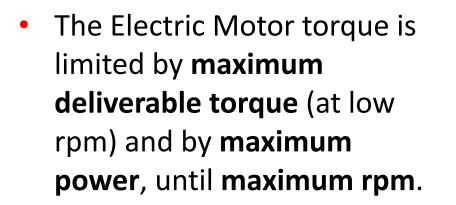


Electric machines in HEVs

- Electric machines are used both as motors and as generators in HEV's.
- One reversible machine is used in parallel hybrid vehicles, while two separate machines are used in series hybrids and in complex hybrids.
- In parallel hybrids, a proper selection of ICE and EM can result in a **favorable torque** curve for the vehicle.



Torque-Speed curve: Electric Motor vs. I.C. Engine



• Engine torque is zero below **idle conditions**, due to combustion instability.

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- Torque drops to zero at higher rpm, due to **mechanical losses**.
- Maximum torque is reached at lower rpm for better driveability of to high rpm for high power.





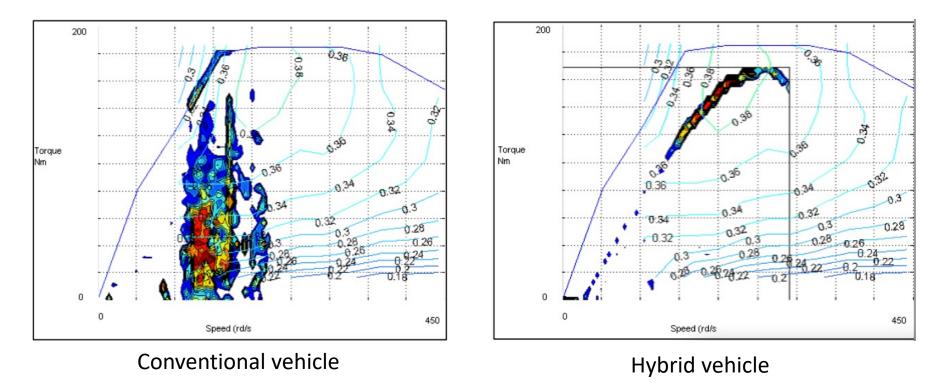
Torque-Speed curve: Parallel Hybrid Powertrain

• Summing up ICE and EM torque allows to optimize powertrain torque, achieving high torque at low speed (as electric motor) and extending the range of higher torque.





Engine efficiency improvement in HEV's



The integration with an electric motor/generator in a hybrid electric vehicle allows thermal engine operating mostly in **higher efficiency region** with respect to a conventional vehicle.



In Wheel Motors



In Wheel Motors are gaining increasing industrial interest, being strongly related to the diffusion of electric vehicles.

They may be considered as a **disruptive technology** (Murata, 2010).

Their use would also allow to integrate drive-bywire and advanced techniques for vehicle control and to expand the applicable range of vehicle control.

An expanding market is in Asia, where IWT are being extensively used for **electrical bicycles and motorcycles**.

OEM	Interest	Work on ECM	Unsprung mass is a major drawback	Concept	Introduction date
Ο ΤΟΥΟΤΑ	٠	•	0	Fine N	2011
🛛 HONDA	•	\bullet	\bigcirc	FCX Dual Note	2010
NISSAN		\bigcirc	\bigcirc		2012
GM	•	•	\bigcirc	Sequel	2018
MITSUBISHI MOTORS	•	\bullet	lacksquare	High	2010
Find	\mathbf{O}	\bigcirc	\bigcirc		
	\bullet	\bigcirc	ullet		
٢	\bullet	\bigcirc	•		
PSA PEUGEOT CITROËN	•	\bigcirc	\bigcirc	Quark	Legend
🚱 RENAULT	•	\bigcirc	\bigcirc	Next	
DAIMLERCHRYSLER	0	0			Low

© Siemens VDO Automotive AG | Bernd Gombert

Munich Network - Mobilität "Trends auf der Straße", 28. November 2007

Interests and activities of OEM's toward inwheel motors

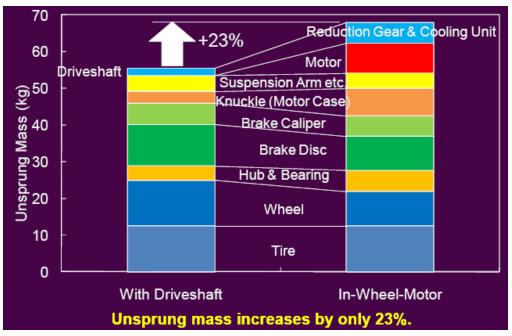




In Wheel Motors: problems

The main problems of IWM are the following:

- The installation of a motor inside the wheel is made difficult by the standpoint of **space constraints**.
- Moreover, deterioration of ride comfort due to increase in unsprung mass occurs.
- The complexity of these problems tends to increase with motor power.



Satoshi MURATA, TOYOTA MOTOR CORPORATION, Innovation by In-Wheel-Motor Drive Unit, AVEC 2010.



Some In-Wheel Motors





Michelin Active Wheel



Kelly (HySolarKit)



Elaphe



Protean Electric



Batteries: introduction

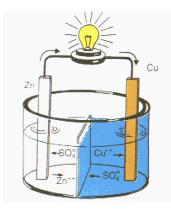


Batteries are electrochemical energy storage systems that convert directly chemical energy into electrical one (discharge) and viceversa (charge)



The first battery was developed by Alessandro Volta in 1799:

- copper and zinc diskettes
- cloth soaked with water and sulfuric acid
- two copper wires







Batteries: Electrochemical Features



battery	anode	cathode	electrolyte	cell voltage		
lead–acid	Pb	PbO ₂	H ₂ SO ₄	2 V		
nickel–metal hydride	Metal hydride	Ni(OH) ₂	КОН	1.2 V		
lithium-ion	carbon	Li oxide	Lithiated solution	3.6 V		
lithium-metal- polymer	Li	Plastic composite	Solid polymer	3.7 V		
sodium–nickel chloride	Na	NiCl ₂	Al_2O_3	2.58 V		
lithium–air	Li	<i>O</i> ₂	organic solution	3.4 V		
Electrochemical features of various traction battery						

technologies



Batteries for automotive application





Toyota Auris (HEV)

Nissan Leaf (EV)

The traveling range of battery-powered vehicles will always be very limited compared to vehicles featuring combustion engines **Specific energy:**

Batteries (40 to 240 Wh/kg) vs. Gasoline (12,000 to 13,000 Wh/kg)

The energy required for a medium vehicle (M1) in a combined cycle is about 140 Wh/km



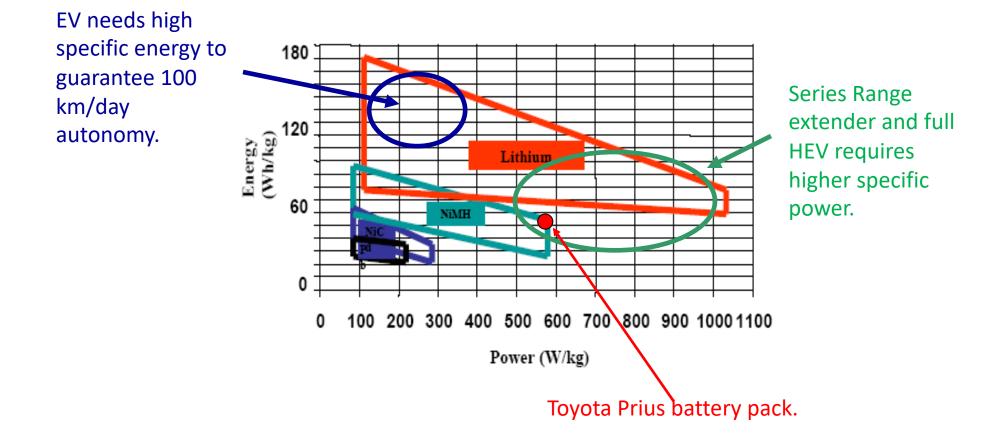
Batteries for automotive application



- Making batteries lighter by significantly higher specific energy and power
- High DOD (>1000 cycles)
- High efficiency
- As maintenance free as possible without sophisticated peripheral equipment.
- No noticeable rise in price through energy consumption during use.
- Same or improved reliability compared to present products.



Comparison of battery characteristics



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Battery technologies for electric road vehicles

Specification	Lead-Acid	NiCd	NiMH	Li - ion
Specific energy density (Wh/kg)	30 - 50	45 - 80	60 - 120	110 - 190
Cycle life (80% discharge)	200 - 300	1000	300 - 50 <u>0</u>	500 - 1,000
Fast-charge time (hrs.)	8 - 16	1 tipical	2 - 4	2 - 4
Overcharge tolerance	High	Moderate	Low	Very low
Self-discharge/month (room temp.)	5 - 15%	20%	30%	<5%
Cell voltage	2.0	1.2	1.2	3.6
Operating temperature	-20 / 60°C	-40/60°C	-20 /60°C	-20 /60°C
	3 - 6 months	30 - 60 days	60 - 90 days	
Maintenance requirement	(equalization)	(discharge)	(discharge)	None
				Protection circuit
Safety requirement	Thermally stable	Thermally stable, fuses common		mandatory
In use since	1881	1950	1990	1991
Toxicity	High	High	Low	Low
Typical battery cost (US\$)	25 (6V)	50 (7,2V)	60 (7,2V)	100 (7,2V)







ICE

1798 (cc) Max power Max torque

72 kW @ 5.200 rpm 142 Nm @ 3.600 rpm

ELECTRICAL MOTOR

Synchronous permanent magnet Nominal Voltage Max Power Max Torque

BATTERY

Nickel-Metal hydride (NiMH) Nominal Voltage Capacity Max Energy



201,6 V 6,5 Ah 201,6x6,5= **1310,4 Wh**



Toyota – Auris (HEV)



ICE

1798 (cc) Max power Max torque

ELECTRICAL MOTOR

Synchronous permanent magnet Nominal Voltage Max Power Max Torque

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Nickel-Metal hydride (NiMH) Nominal Voltage Capacity Max Energy 72 kW @ 5.200 rpm 142 Nm @ 3.600 rpm



201,6 V 6,5 Ah 201,6x6,5= **1310,4 Wh**



Tesla – Model S (EV)



Model S (70D) 244 kW AC synchronous electric motor 70 kWh battery (Lithium ion) 384 km range 224 km/h top speed









80 kW AC synchronous electric motor 24 kWh battery (Lithium ion) 160 km range 144 km/h top speed

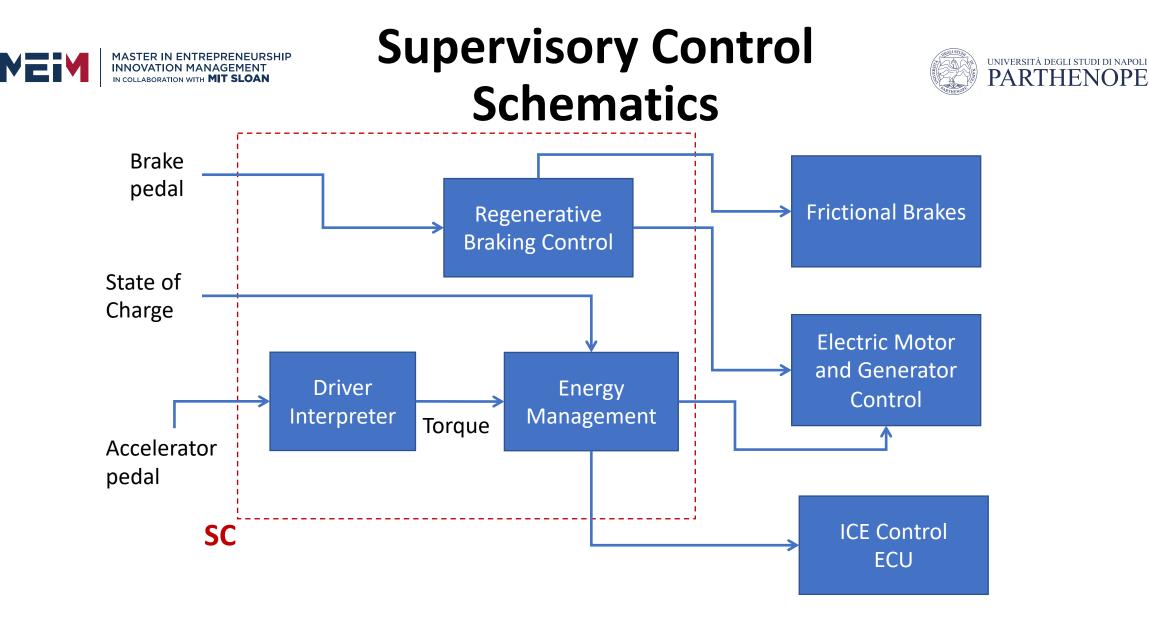






Supervisory Control

- In all types of hybrid vehicles, a **supervisory controller** (SC) must determine how the powertrain components should operate, in order to satisfy the **power demand** of the drive line in the best way.
- The main objective of the SC is reducing the overall energy use, typically in the presence of various constraints due to emissions, driveability requirements and the characteristics of the components.
- Different classification approaches can be adopted for SC:
 - Off-line vs real-time
 - Causal vs non-causal (i.e. vehicle mission known in advance)
 - Heuristic vs optimal
 - Rule based vs model based



The scheme shows the main functions and components of a **Supervisory Control** SC (also Vehicle Management Unit, VMU) for a HEV.

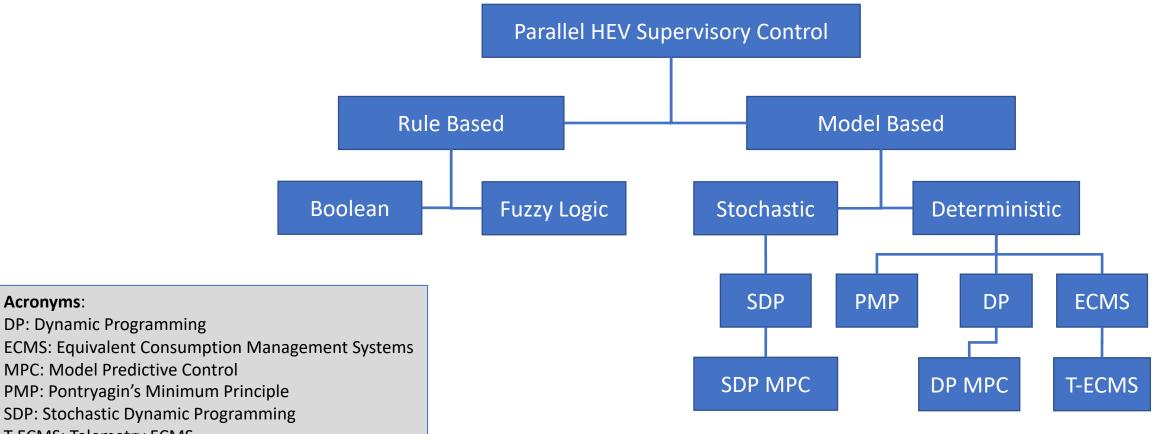


Acronyms:

DP: Dynamic Programming

T-ECMS: Telemetry ECMS

Supervisory Control Classification: Rule Based vs Model Based



Adapted from: Tae Soo Kim, Optimal Control of a Parallel Hybrid Electric Vehicle with Traffic Preview, PhD Thesis, The University of Melbourne, November 2011

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Energy management in a PHEV Map based approach

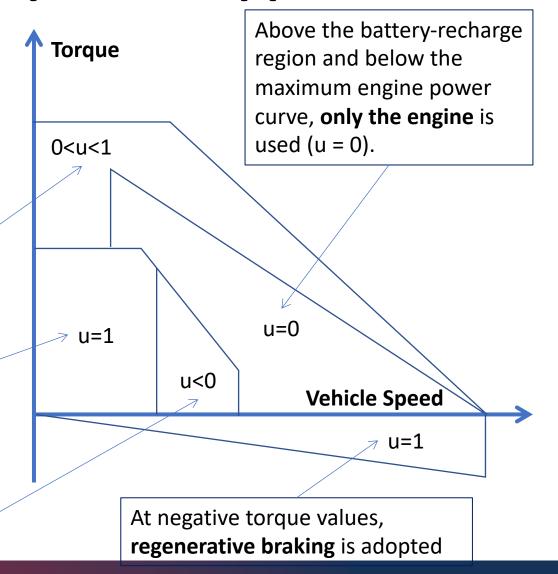


In map based approach, the decisions about power split (u) for a Parallel HEV may be expressed as a function of vehicle torque and speed.

Above the maximum power of the engine, the motor is used to **assist the engine** (0 < u < 1).

Below a certain vehicle speed and a certain wheel power, **pure electric driving** is selected (u = 1).

For intermediate power levels, the engine is forced to deliver excess torque to **recharge the battery** (u < 0).





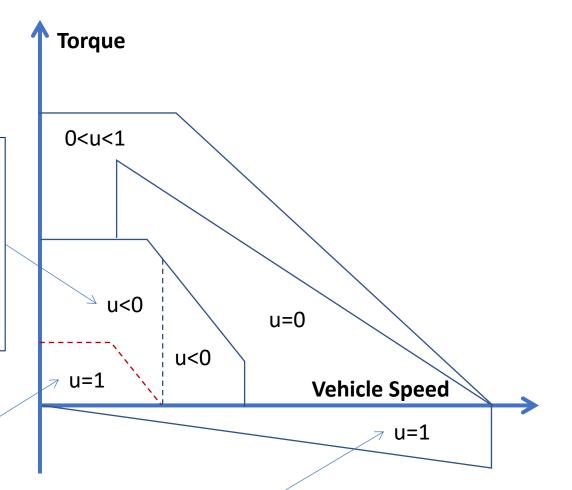
Map based approach Effects of SoC



The extensions of certain areas depend also by the actual state of charge (SoC) of the battery.

The operating region where the engine is forced to deliver excess torque to **recharge the battery** (u < 0) is enlarged as the SoC decreases (**red line**), while it is reduced or eliminated when battery is full charged.

When SoC decreases, the area of **pure electric driving** (u = 1) is reduced also.



When battery is **fully charged**, the current coming from electric brakes **cannot be delivered to the battery**.









Optimal Energy Management. Offline vs real-time strategies

Two basically different approaches can be adopted to design optimal control strategies in a HEV:

- Off-line strategies. The drive cycle is assumed known a priori. No constraints of computational power and time are given. This strategy is not implementable, but is useful to determine benchmarks, to assess the quality of implementable sub-optimal strategies.
- On-line strategies. In general, drive cycle is not known, except in particular conditions. There are also limitations in terms of computational time and power, and on reliability. Sub-optimal strategies are therefore often implemented.



Electronic Horizon & ADAS Maps

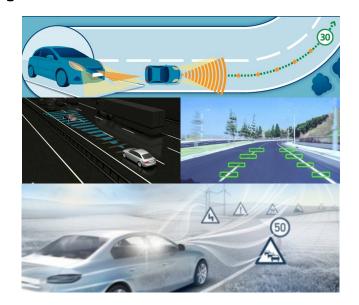


Advanced Driver Assistance Systems (ADAS) allow achieving benefits on safety and driver monitoring apart to improve fuel economy and environmental impact.

ADAS Maps include the information about the road ahead of the vehicle:

- Speed Limits
- Elevation and slope data
- Road length
- Signals
- Lanes number

The **Electronic Horizon (EH)** gathers together all these road information with onboard sensors and cameras data, and enables the vehicle to "see beyond the next bend".









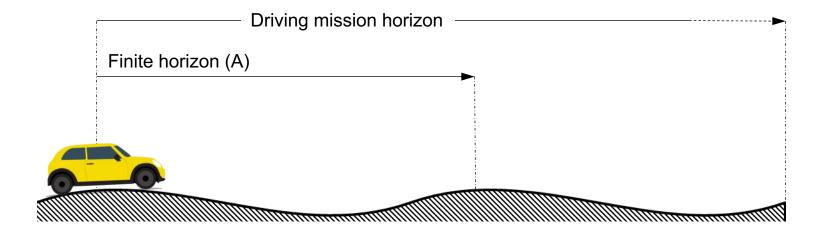
Real driving scenarios are characterized by

- traffic flows
- interactions with surrounding vehicles
- traffic lights...

which can prevent the calculated optimal velocity from being tracked.

The optimal control problem is solved for a finite sliding horizon.









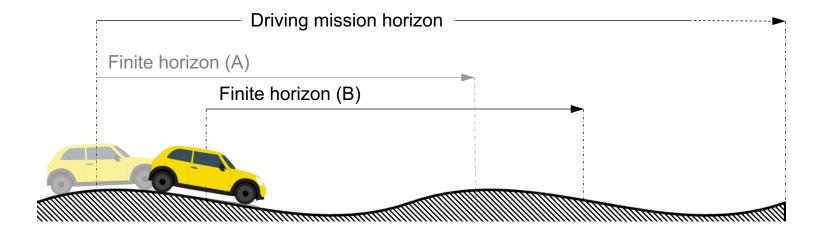
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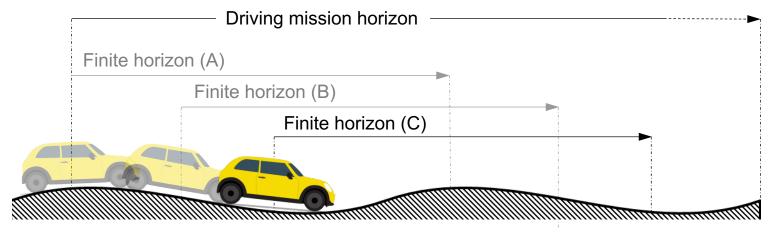
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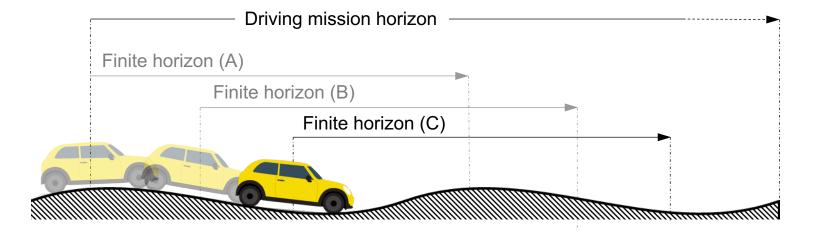






- Sub-optimal solution
- Updates the optimal control law each 500 m
- Reduces the calculation time and memory usage (that are fixed)
- Adaptability to the environmental changes
- ... optimization can be triggered if the vehicle drifts from the optimal reference





Fabrizio Donatantonio, Antonio D'Amato, Ivan Arsie, and Cesare Pianese. A multi-layer control hierarchy for heavy duty vehicles with o-line dual stage dynamic programming optimization. Transportation Research Part C: Emerging Technologies, 92:486 503, 2018. ISSN 0968-090X. doi: 10.1016/j.trc.2018.05.006F.
 Polverino, P., Arsie, I., Pianese, C., Optimal energy management for hybrid electric vehicles based on dynamic programming and receding horizon. Energies, 2021 14(12), 3502.









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Thank you for your attention

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